



## INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

<b>(51) International Patent Classification <sup>7</sup> :</b> <b>A61F 2/06</b>	<b>A2</b>	<b>(11) International Publication Number:</b> <b>WO 00/44309</b> <b>(43) International Publication Date:</b> 3 August 2000 (03.08.00)
<b>(21) International Application Number:</b> PCT/US00/02582 <b>(22) International Filing Date:</b> 1 February 2000 (01.02.00)  <b>(30) Priority Data:</b> 60/118,185           1 February 1999 (01.02.99)       US 60/125,192           18 March 1999 (18.03.99)       US  <b>(71) Applicant:</b> BOARD OF REGENTS, THE UNIVERSITY OF TEXAS SYSTEM [US/US]; 201 West. 7th Street, Austin, TX 78701 (US).  <b>(72) Inventors:</b> HYODOH, Hideki; Kawachi, Tochigi (JP). KONYA, Andras; 550 N. Braeswood #256, Houston, TX 77096 (US). WRIGHT, Kenneth, C.; 1802 Haver, Houston, TX 77006-2414 (US).  <b>(74) Agent:</b> GARRETT, Mark, T.; Fulbright & Jaworski, Suite 2400, 600 Congress Avenue, Austin, TX 78701 (US).		<b>(81) Designated States:</b> AE, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, CA, CH, CN, CR, CU, CZ, DE, DK, DM, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, TZ, UA, UG, UZ, VN, YU, ZA, ZW, ARIPO patent (GH, GM, KE, LS, MW, SD, SL, SZ, TZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG).  <b>Published</b> <i>Without international search report and to be republished upon receipt of that report.</i>
<b>(54) Title:</b> WOVEN BIFURCATED AND TRIFURCATED STENTS AND METHODS FOR MAKING THE SAME  <b>(57) Abstract</b> <p>Bifurcated and trifurcated woven stents for insertion and delivery into a variety of anatomical structures, including the aortic-iliac bifurcation, the superior vena cava junction, and the inferior vena cava junction. The bifurcated stents includes a first leg formed from a first plurality of wires, a second leg formed from a second plurality of wires, and a common body formed from the first and second pluralities of wires. The wires may be nitinol. Biodegradable filaments may also be utilized. The angles created between the crossed wires is preferably obtuse. A variety of delivery devices formed from differently-sized tubes, portions of which may operate co-axially with each other, are also included. The bifurcated stents may operate co-axially with each other, are also included. The bifurcated stents may be formed from as few as two wires. The stents may be formed using plain weaving effected either by hand or by machine.</p>		

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**APPLICATION FOR UNITED STATES LETTERS PATENT**  
**for**  
**WOVEN BIFURCATED AND TRIFURCATED STENTS**  
**AND METHODS FOR MAKING THE SAME**

## BACKGROUND OF THE INVENTION

The present application claims priority to U.S. Provisional Patent Application Serial No. 60/118,185 filed February 1, 1999 and U.S. Provisional Patent Application Serial No. 60/125,192 filed March 18, 1999. The entire texts of the above-referenced disclosures are specifically incorporated by reference herein without disclaimer.

### 1. Field of the Invention

The present invention relates to a self-expanding bifurcated stent and apparatus and methods for inserting the same into a bifurcated anatomical structure.

### 2. Description of Related Art

Numerous studies have reported the use of metallic stents for the treatment of stenotic lesions occurring in tubular anatomic structures (Wallace *et al.*, 1986; Palmaz, 1988; Milroy *et al.*, 1989; Günther *et al.*, 1989; Riving *et al.*, 1989). Placement of these stents is less invasive than surgical procedures and the stents provide more luminal space than most solid tube devices. Therefore, metallic stents have been widely used for treatment of stenotic diseases in humans. Several different types of stents have been used to treat both straight and curved lesions (Gillams *et al.*, 1990).

The use of straight, cylindrical stents has some limitations. One major limitation is the treatment of lesions occurring at a bifurcation (Nashef *et al.*, 1992). Many methods for stenting these lesions with straight stents have been described including side-by-side insertion (Morita, 1997), pull-through technique (Morita, 1987), creation of a T-configuration (Morita, 1987), Y-stenting (Fort, 1996), and V-stent insertion (Schampaert, 1996). However, no ideal method has been established because only straight stents with a cylindrical configuration are commercially available.

Additionally, the use of such a stent to treat disease at or near a branch of a bifurcation of a blood vessel runs the risk of compromising the degree of patency of the primary vessel and/or its branches of the bifurcation. This may occur as a result of

1 several problems such as displacing diseased tissues, vessel spasm, dissection with or  
2 without intimal flaps, thrombosis, and embolism. For example, a bifurcated vascular or  
3 non-vascular lesion can be bridged by two straight cylindrical stents arranged in a Y-  
4 shape. One of the stents is longer forming one leg and the common trunk of the Y, while  
5 another short stent is attached to the longer one in an end-to-side fashion to form the other  
6 leg of the Y-shape. In this situation, the patency of the shorter leg is threatened by the  
7 fact that at the site of the attachment of the two stents the stent mesh of the longer stent  
8 interferes with the free flow of blood, bile, *etc.* Such an attachment has a high propensity  
9 for thrombosis and consequent occlusion in the vasculature, stenosis, bile congestion,  
10 inflammation, and eventually occlusion in the biliary tree. In the tracheobronchial  
11 system, mucus deposition will readily result in serious coughing, infection, and exclusion  
12 of the affected part of the lung from gas-exchange.

13  
14

#### SUMMARY OF THE INVENTION

15 In one respect, the invention is a device suitable for implantation into an  
16 anatomical structure that includes, but is not limited to, a first plurality of wires that  
17 define a first leg, which has a first distal portion; a second plurality of wires that define a  
18 second leg, which has a second distal portion; and a common body that has a distal end  
19 and a proximal portion. The common body is formed from at least the first and second  
20 pluralities of wires. The proximal portion of the common body is adjacent to the distal  
21 portions of both legs, and both ends of at least one wire from one of the pluralities is  
22 located proximate (near) the distal end of the common body.

23 The wires in the first and second pluralities may be made from nitinol. The wires  
24 in the first and second pluralities may be made from FePt, FePd or FeNiCoTi. The wires  
25 in the first and second pluralities may also be made from FeNiC, FeMnSi or  
26 FeMnSiCrNi. The wires in the first and second pluralities may each have a diameter  
27 ranging in size from about 0.006 inches to about 0.014 inches. The first plurality of wires  
28 may include at least 6 wires. Both the legs and the common body may have tubular  
29 shapes with substantially uniform diameters. At least one of the legs of the device may

1 be hand woven. At least one of the legs of the device may be machine woven. The  
2 device may also include a graft material attached to at least the common body. The graft  
3 material may be made from woven Dacron. The graft material may be made from  
4 polyurethane. The graft material may also be made from PTFE.

5 In another respect, the invention is a stent that includes, but is not limited to, a  
6 first plurality of flexible tubular strands woven to form a first leg that has a first distal  
7 portion. The flexible tubular strands in the first plurality cross each other to form a first  
8 plurality of angles. At least one of the angles in the first plurality of angles is obtuse.  
9 The stent also includes, but is not limited to, a second plurality of flexible tubular strands  
10 woven to form a second leg that has a second distal portion. The flexible tubular strands  
11 in the second plurality cross each other to form a second plurality of angles. At least one  
12 of the angles in the second plurality of angles is obtuse. The stent also includes, but is not  
13 limited to, a common body that has a common portion. The common body is formed  
14 from at least the first and second pluralities of flexible tubular strands. The common  
15 portion of the common body is adjacent to the distal portions of the first and second legs.

16 The flexible tubular strands in the first and second pluralities may be made from  
17 nitinol or biodegradable filaments.

18 In another respect, the invention is a stent that includes, but is not limited to, a  
19 first plurality of wires that define a first leg, which has a first distal portion. The stent  
20 also includes, but is not limited to, a second plurality of wires that define a second leg,  
21 which has a second distal portion. The stent also includes, but is not limited to, a third  
22 plurality of wires that define a third leg, which has a third distal portion. The stent also  
23 includes, but is not limited to, a common body that has a proximal portion and a distal  
24 end. The common body is formed from at least the first, second and third pluralities of  
25 wires. The proximal portion of the common body is adjacent to the distal portions of  
26 each of the three legs.

27 The wires in each of the pluralities may be made from nitinol. The first plurality  
28 of wires may include at least 5 wires. Each of the legs and the common body may have

1 tubular shapes with substantially uniform diameters. At least one of the legs may be hand  
2 woven or machine woven. The stent may also include a graft material that is attached to  
3 at least the common body. The graft material may be made from woven Dacron. The  
4 graft material may be made from polyurethane.

5 In another respect, the invention is a stent that includes, but is not limited to, a  
6 first leg that has a first axis and a first end. The first leg includes, but is not limited to, a  
7 first wire that has a first segment and a second segment, which are separated by a bend in  
8 the first wire located proximate (near) the first end of the first leg. The first segment  
9 extends helically in a first direction around the first axis away from the first end of the  
10 first leg, and the second segment extends helically in a second direction around the first  
11 axis away from the first end of the first leg. The segments cross each other in a first  
12 plurality of locations. The stent also includes, but is not limited to, a second leg that has a  
13 second axis and a second end. The second leg includes, but is not limited to, a second  
14 wire that has a first segment and a second segment, which are separated by a bend in the  
15 second wire located proximate (near) the second end of the second leg. The first segment  
16 extends helically in a first direction around the second axis away from the second end of  
17 the second leg, and the second segment extends helically in a second direction around the  
18 second axis away from the second end of the second leg. The segments cross each other  
19 in a second plurality of locations. The stent also includes, but is not limited to, a common  
20 body that is formed from at least one end of each of the wires.

21 The first segment of the first wire may be positioned farther from the first axis  
22 than the second segment of the first wire at at least one location among the first plurality  
23 of locations. The first segment of the first wire may be positioned farther from the first  
24 axis than the second segment of the first wire at each location of the first plurality of  
25 locations. The first and second wires may be made from nitinol.

26 In another respect, the invention is a method of creating a device suitable for  
27 implantation into an anatomical structure. The device may have a first leg, a second leg,  
28 and a common body. Each leg may have an end and a distal portion. The common body  
29 may have a proximal portion and a distal end. The method includes, but is not limited to,

1 bending the wires in a first plurality of wires to create first bent portions in the wires. The  
2 first bent portions are arranged to define the end of the first leg. Each wire in the first  
3 plurality has two ends. The method also includes, but is not limited to, bending the wires  
4 in a second plurality of wires to create second bent portions in the wires. The second bent  
5 portions are arranged to define the end of the second leg. Each wire in the second  
6 plurality has two ends. The method also includes, but is not limited to, weaving the ends  
7 of the wires in the first plurality to create the first leg; weaving the ends of the wires in  
8 the second plurality to create the second leg; and weaving the ends of the wires in both  
9 pluralities to create the common body and the device. The proximal portion of the  
10 common body is adjacent to the distal portions of both legs.

11 The first bent portions may be bends or loops. The wires in the first and second  
12 pluralities may be made from nitinol. The wires in the first and second pluralities may  
13 each have a diameter ranging in size from about 0.006 inches to about 0.014 inches. The  
14 step of weaving the ends of the wires in the first plurality may be performed by hand or  
15 by machine.

16 In another respect, the invention is a method of creating a stent, which may have a  
17 first leg, a second leg, and a common body. Each leg may have an end and a distal  
18 portion, and the common body may have a proximal portion and a distal end. The method  
19 includes, but is not limited to, providing a weaving system that includes, but is not  
20 limited to, a first template that has first template projections, a proximal end and a distal  
21 end. The method also includes, but is not limited to, bending the wires in a first plurality  
22 of wires around the first template projections to create first bent portions in the wires.  
23 The first bent portions are arranged to define the end of the first leg. Each wire in the  
24 first plurality has two ends. The method also includes, but is not limited to, bending the  
25 wires in a second plurality of wires to create second bent portions in the wires. The  
26 second bent portions are arranged to define the end of the second leg. Each wire in the  
27 second plurality has two ends. The method also includes, but is not limited to, weaving  
28 the ends of the wires in the first plurality to create the first leg; weaving the ends of the  
29 wires in the second plurality to create the second leg; and weaving the ends of the wires



1 in both pluralities to create the common body and the stent. The proximal portion of the  
2 common body is adjacent to the distal portions of both legs.

3 The weaving system may also include, but is not limited to, a second template that  
4 has second template projections, a proximal end and a distal end; and a third template that  
5 a proximal end and a distal end. The distal ends of the first and second templates may be  
6 configured to be placed within the proximal end of the third template. The step of  
7 bending the wires in the second plurality of wires may include bending the wires in the  
8 second plurality of wires around the second template projections to create second bent  
9 portions in the wires. The step of weaving the ends of the wires in both pluralities may  
10 include weaving the ends of the wires in both pluralities around the third template to  
11 create the common body and the stent.

12 The weaving system may also include, but is not limited to, a second template  
13 having a proximal end, a distal end, second template projections arranged around the  
14 second template proximate (near) the proximal end thereof, and an opening positioned  
15 between the proximal and distal ends of the second template. The opening is configured  
16 to accept the distal end of the first template. The step of bending the wires in the second  
17 plurality of wires may include bending the wires in the second plurality of wires around  
18 the second template projections to create second bent portions in the wires. The step of  
19 weaving the ends of the wires in the second plurality may include weaving the ends of the  
20 wires in the second plurality around the portion of the second template located proximally  
21 of the opening therein to create the second leg. The step of weaving the ends of the wires  
22 in both pluralities may include weaving the ends of the wires in both pluralities around  
23 the portion of the second template located distally of the opening therein to create the  
24 common body and the stent.

25 The first template projections may be pins, which may be attached to a ring  
26 engaged with the first template. The method may also include, but is not limited to,  
27 securing the wires in the first plurality of wires to the first template. The method may  
28 also include, but is not limited to, forming closed structures with the ends of the wires in  
29 both pluralities. The closed structures may be arranged to define the distal end of the

1 common body. The method may also include, but is not limited to, heating the stent and  
2 the first template.

### 3 BRIEF DESCRIPTION OF THE DRAWINGS

4 The following drawings form part of the present specification and are included to  
5 further demonstrate certain aspects of the present invention. The invention may be better  
6 understood by reference to one or more of these drawings in combination with the  
7 description of illustrative embodiments presented herein.

8 **FIG. 1A** is a perspective view of a bifurcated stent according to one embodiment  
9 of the present invention.

10 **FIG. 1B** is a side view of the arrangement of wires in a plain weave according to  
11 one embodiment of the present invention.

12 **FIG. 1C** is a front view of a bifurcated stent formed from two wires according to  
13 one embodiment of the present invention.

14 **FIG. 2** is a front view of a proximal portion of a delivery system according to one  
15 embodiment of the present invention.

16 **FIG. 3** is a perspective view of a delivery system for a bifurcated stent according  
17 to one embodiment of the present invention.

18 **FIG. 4** is a perspective view of a portion of a delivery system according to one  
19 embodiment of the present invention.

20 **FIG. 5** is a perspective view of a stretched bifurcated stent on a delivery system  
21 according to one embodiment of the present invention.

22 **FIG. 6** is a perspective view of a delivery system according to one embodiment of  
23 the present invention.

1           **FIG. 7** is a front view of a trifurcated stent according to one embodiment of the  
2 present invention.

3           **FIG. 8** is a front view of a trifurcated stent in a delivered position according to  
4 one embodiment of the present invention.

5           **FIG. 9** is a front view of a bifurcated stent according to one embodiment of the  
6 present invention.

7           **FIG. 10** is a front view of a bifurcated stent in a delivered position according to  
8 one embodiment of the present invention.

9           **FIGS. 11-19** show stages in a hand weaving method according to one  
10 embodiment of the present invention.

11           **FIG. 20** depicts two bifurcated stents delivered into the aortic arch according to  
12 one embodiment of the present invention.

13           **FIG. 21** depicts three bifurcated stents delivered into the aortic arch according to  
14 one embodiment of the present invention.

15           **FIG. 22** depicts a partially-covered bifurcated stent delivered into the aortic arch  
16 and sealing an aneurysmal sac according to one embodiment of the present invention.

17           **FIG. 23** is a perspective view of the templates for a bifurcated stent according to  
18 one embodiment of the present invention.

19           **FIG. 24** is a perspective view of the templates for a bifurcated stent in an  
20 assembled position according to one embodiment of the present invention.

21           **FIGS. 25A-C** is a perspective view of wires woven on leg templates that are then  
22 attached to a common body template on which the weaving continues according to one  
23 embodiment of the present invention.

1           **FIG. 26** is a perspective view of a bifurcated stent woven on an assembled  
2 bifurcated template according to one embodiment of the present invention.

3           **FIG. 27A** is a perspective view of templates arranged for use in forming a  
4 trifurcated stent according to one embodiment of the present invention.

5           **FIG. 27B** is a perspective view of templates arranged for use in forming a  
6 trifurcated stent and wires woven thereon according to one embodiment of the present  
7 invention.

8           **FIG. 28** is a perspective view of a biodegradable leg with a reinforcing wire  
9 according to one embodiment of the present invention.

10           **FIG. 29** is a perspective view of a biodegradable leg with a reinforcing wire  
11 according to a second embodiment of the present invention.

12           **FIG. 30** is a front view of an abdominal aortic aneurysm being treated by  
13 transcatheter embolization according to one embodiment of the present invention.

14           **FIG. 31** is perspective view of a template with longitudinal tabs around which  
15 wires are bent according to one embodiment of the present invention.

16           **FIG. 32A** is an enlarged perspective view of the longitudinal tab and bent wire  
17 depicted in **FIG. 31** according to one embodiment of the present invention.

18           **FIG. 32B** is an enlarged perspective view of a longitudinal tab depicted in  
19 **FIG. 31** around which a wire is bent to form a loop according to one embodiment of the  
20 present invention.

21           **FIG. 33** is a perspective view of a wire bent around a longitudinal tab and  
22 wrapped around a pair of bobbins according to one embodiment of the present invention.

23           **FIG. 34** is a top view of upper and lower weaving plates provided with bobbins  
24 according to one embodiment of the present invention.

1           **FIG. 35** is a cross-sectional front view of upper and lower weaving plates  
2 arranged on different planes around a template and provided with bobbins and wires  
3 according to one embodiment of the present invention.

4           **FIG. 36A** is a top view of upper and lower weaving plates provided with bobbins  
5 and wires and arranged around a template, and illustrates the first crossing of the wires  
6 according to one embodiment of the present invention.

7           **FIG. 36B** is a front view of a small caliber loop formed by bending a wire  
8 according to one embodiment of the present invention.

9           **FIG. 37A** is a top view of upper and lower weaving plates provided with bobbins  
10 and wires and arranged around a template, and illustrates the first crossing of the wires  
11 according to another embodiment of the present invention.

12           **FIG. 37B** is a front view of a bend formed by bending a wire according to one  
13 embodiment of the present invention.

14           **FIG. 38** is a perspective view of upper and lower weaving plates provided with  
15 bobbins and arranged around a template such that the surfaces of the weaving plates from  
16 which the bobbin rods extend face each other according to one embodiment of the present  
17 invention.

18           **FIG. 39** is a perspective view of upper and lower weaving plates provided with  
19 bobbins and wires and arranged around a template such that the surfaces of the weaving  
20 plates from which the bobbin rods extend face each other according to one embodiment  
21 of the present invention.

22           **FIG. 40** is a front view of two bifurcated stents placed in side-by-side relationship  
23 with each other in the aorta according to one embodiment of the present invention.

24           **FIG. 41A** is a perspective, partial cross-sectional view of a tool for twisting the  
25 wire ends of a woven stent according to one embodiment of the present invention.

1           **FIG. 41B** is a cross-sectional view of the jaws and outer housing of the tool  
2 illustrated in **FIG. 41A**.

3           **FIG. 42A** is a perspective view of a portion of the common body of a stent woven  
4 around a template having transverse tabs according to one embodiment of the present  
5 invention.

6           **FIG. 42B** is an enlarged perspective view of one of the transverse tabs and twisted  
7 wire ends depicted in **FIG. 42A** according to one embodiment of the present invention.

8           **FIG. 43** is a perspective view of a template around which a ring having finish pins  
9 has been threadably engaged according to one embodiment of the present invention.

10          **FIG. 44** is a perspective view of a template having finish holes through which  
11 finish pins may be placed according to one embodiment of the present invention.

12          **FIG. 45** is a front view of upper and lower weaving plates supported by a weaving  
13 plate supporter according to one embodiment of the present invention.

14          **FIG. 46** is a perspective view showing a combination of two templates on which a  
15 bifurcated stent may be woven according to one embodiment of the present invention.

## 16                   **DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS**

17          As shown in **FIG. 1A**, the present invention comprises a stent **10**, which may  
18 include a common main body **20** and two legs **30** that comprise one coherent element.  
19 The radially expandable and flexible tubular bodies of the stent may be created by using  
20 the principle of plain weave. The arrangement of wires in a plain weave is illustrated in  
21 **FIG. 1B**. As will be described below in greater detail, the weave is started on two  
22 separate straight templates for making the legs **30** and is continued on a single straight  
23 template for the common body **20**. The stent **10** may be made of nitinol wires and may  
24 utilize nitinol's superelastic properties. In one embodiment, the nitinol may comprise  
25 about 55-56% Nickel and about 45-44% Titanium (commercially available from Shape  
26 Memory Applications in Santa Clara, CA). It is to be understood that stent **10** may also

1 be formed of any superelastic or pseudoelastic material. For example, shape memory  
2 alloys such as FePt, FePd, FeNiCoTi with thermoelastic martensitic transformation, as  
3 well as alloys such as FeNiC, FeMnSi, and FeMnSiCrNi, the shape memory effect of  
4 which relies on stress-induced martensite, may be used.

5 As shown in **FIG. 1**, ends **15** of legs **30** have a plurality of closed structures.  
6 These closed structures may be either small closed loops **45** or bends **50**. Both bends **50**  
7 and small closed loops **45** may be formed by bending a wire **40** at a selected point located  
8 between the bends of the wire. For most applications, the selected point of the bend or  
9 small closed loop may be close to the mid-point of wire **40**. The closed structures are  
10 advantageous, because, for example, the closed structures formed by bending are less  
11 likely to cause damage such as perforations or penetrations to the tubular structure stented  
12 than are free wire ends.

13 Moreover, both loops **45** and bends **50** provide many significant advantages, some  
14 of which are unexpected, over woven devices such as the stent disclosed in U.S. Patent  
15 No. 4,655,771 to Wallsten (1987) (hereinafter, the stent therein will be referred to as the  
16 "WALLSTENT"), which is hereby expressly incorporated herein by reference, which  
17 have free wire ends. For instance, the Wallsten patent recognizes that the free wire ends  
18 of the WALLSTENT should be protected, implicitly acknowledging the potential tissue-  
19 damaging dangers such free, sharp wire ends pose. The Wallsten patent suggests  
20 methods by which one can attempt to lessen these dangers, such as connecting the free  
21 wire ends to each other by attaching U-shaped members to them through heat welding,  
22 gluing or the like. These suggested methods are likely time-consuming and, as a result,  
23 expensive. No such steps need to be taken in creating either loops **45** or bends **50** of the  
24 present woven bifurcated stents as will be discussed below in greater detail.

25 Further, the connections resulting from the methods disclosed in the Wallsten  
26 patent are likely more prone to mechanical failure than are loops **45** or bends **50** of the  
27 present woven bifurcated stents. For example, welding can introduce anomalies such as  
28 cracks (which may result from the non-uniform solidification, uneven boundaries, *etc.*);  
29 voids or other irregularities resulting from porosity; inclusions (which include slag,

1 oxides, *etc.*); *etc.*, into the welded metal that create stress concentrations and dramatically  
2 increases the propensity for the welded connection to fail at those locations. In contrast,  
3 the gentle curves and bends resulting in loops 45 and bends 50 are virtually free of any  
4 such induced stresses and, as a result, are much less likely to fail.

5 The Wallsten patent also suggests gluing the free wire ends, a method that  
6 provides even less structural integrity than can welding, because the resulting bond  
7 between the joined wire ends is only as strong as the surface tension between the glue and  
8 the metal used. Consequently, the joint created is more prone to failure than a welded  
9 joint suffering from the anomalies just discussed.

10 Similarly, the Wallsten patent discloses first utilizing electric resistance heating to  
11 weld together the points of crossing of the free wire ends in a ring around the stent and  
12 then folding the free wire ends extending beyond the welded ring inwardly with light  
13 plastic deformation through controlled heating. This method involves not only the likely  
14 introduction of the anomalies discussed above that can result from welding, it also  
15 involves an additional stress on the joints created as the free wire ends are folded  
16 inwardly while being heated. Thus, this preferred joint is similar to the glued joint in that  
17 it is likely even more prone to failure than one involving only welding.

18 In sum, the gentle curves and bends that may be used to create loops 45 and bends  
19 50 of the present woven bifurcated stents provide devices with safer ends: no free wire  
20 ends exist that may unintentionally penetrate and damage the wall of the structure into  
21 which they are delivered; bends 45 or loops 50 are much less likely to mechanically fail  
22 than are the free wire ends that are connected together using welding or glue; and the  
23 likely time-consuming task of creating multiple welded or glued joints does not exist.  
24 Further, while the closed structures 55 (discussed below in greater detail) may be  
25 reinforced using methods similar to those suggested by the Wallsten patent (*i.e.*, such as  
26 by welding), the present woven bifurcated stents have fewer potential locations for using  
27 such methods as either bends or loops exist at the ends of the legs of the present stents  
28 (this is especially true considering fewer wires are generally needed for making the legs  
29 of the present stents than are needed for making comparably-sized WALLSTENTS, even



1 equating one of the present wires to two wires as those are used in the WALLSTENT).  
2 As a result, the potential for mechanical failure of the present woven devices is reduced  
3 accordingly.

4 In addition to the foregoing benefits, loops 45 and bends 50 also provide  
5 advantages over the modified free wire ends disclosed in the Wallsten patent discussed  
6 above that are unexpected. For example, the inventors have found that the mesh of one of  
7 the legs of present woven bifurcated stents may be formed from fewer wires than can the  
8 mesh of a comparably-sized WALLSTENT (even equating one of the present wires to  
9 two wires as those are used in the WALLSTENT). Accordingly, the expansile force of  
10 one of the legs of present woven bifurcated stents of a given size may be maintained with  
11 fewer wires than would be needed to maintain the same expansile force of a  
12 WALLSTENT of the same size by simply increasing the mesh tightness (*i.e.*, by  
13 increasing angle **a** in **FIG. 1**, discussed below in greater detail). Similarly, the inventors  
14 have found that the same result may be achieved by increasing the diameter of the present  
15 wires with or without adjusting the mesh tightness. As a result, the amount of metal  
16 needed for the legs of present woven bifurcated stents may be less than what is needed in  
17 another comparably-sized woven stent, such as the WALLSTENT. This reduction in  
18 necessary metal translates to a cost savings, and also means that patients are less likely to  
19 experience thrombosis and/or restenosis. As a further result, the variety of sizes that may  
20 be created for legs of the present woven bifurcated stents and the variety in the tightness  
21 of the weave of each is virtually unlimited, thereby facilitating virtually all potential  
22 applications.

23 Further, the inventors also discovered that virtually no shortening occurs while  
24 bending the present woven bifurcated stents, nor do the diameters of the legs or the  
25 common body of the present woven bifurcated stents increase during bending. Thus, it is  
26 easier to accurately and predictably position the present woven bifurcated stents in a  
27 tortuous anatomy than it is to position other woven stents that shorten more or suffer  
28 larger increases in diameter when bent, such as the WALLSTENT. For example, a  
29 tightly-woven leg of the present bifurcated stent, 2.5 cm long measured from the end of

1 the leg to the start of the common body (*see* FIG. 1A), 10 mm in diameter, formed from  
2 10 0.006-inch wires may be maximally bent by bringing end 15 of the leg toward the  
3 location at which it meets common body 20, and no shortening or diameter increase  
4 occurs during maximal bending. In contrast, for a WALLSTENT formed from 24 0.005-  
5 inch wires to behave similarly, the inventors found that it should be 6 cm long and 9 mm  
6 in diameter; although, when manipulated in a similar manner, the WALLSTENT  
7 experienced a 10% increase in diameter and some shortening. Thus, the length-to-  
8 diameter ratios of the foregoing stents were 2.5 and 6.6, respectively.

9 At least 5 wires (the number of wires used being designated by  $n$ ) may be used in  
10 the plurality of wires that form each leg 30 of the stent 10. The number of wires that  
11 form each leg 30 may vary. As shown in FIG. 1A, the wires 40 used to form the legs and  
12 common body of stent 10 cross each other in a multiple locations at multiple angles. The  
13 angles between the crossing wires are preferably obtuse, *i.e.* more than 90° (*see* angle  $a$  in  
14 FIG. 1A). However, it will be understood that acute angles may be utilized. In an  
15 exemplary embodiment, the angle may typically be about 150° for applications such as  
16 the aorto iliac. In another exemplary embodiment, the angle may typically be about 160°  
17 for applications such as the biliary tree (*e.g.*, for tumorous lesions). In another exemplary  
18 embodiment, the angle may be typically about 170° for applications such as the superior  
19 vena cava (*e.g.*, for space occupying lesions). Angle  $a$  should be increased as the desired  
20 radial (*i.e.*, expansile) force of the legs and common body of the bifurcated stent  
21 increases. Further, the radial force of the legs and common body of the bifurcated stent  
22 may generally be increased by increasing the diameter of the wires used. Thus, angle  $a$   
23 may be held constant while the diameters of the wires used are increased and, as a result,  
24 the radial force of the legs and common body of the bifurcated stent increase. The weave  
25 is contiguous, meaning that the weave of the common body is formed from the weaves of  
26 the two legs, and from the level of the proximal end 25 of the common body 20 (the  
27 bifurcation),  $2n$  wires (assuming the same number of wires are used to form each leg) are  
28 used to form the common body 20 of the stent 10. As shown, the distal portions 32 of the  
29 legs 30 are positioned adjacent to the proximal end 25 (and hence the proximal portion)

1 of common body 20. At the distal or top end 28 (stent crown) of the common body 20,  
2 adjacent wire ends 42 may be coupled together (as described below) to form closed  
3 structures 55. Because common body 20 is formed from at least the wires making up legs  
4 30, both ends of at least one wire from each of the legs is located proximate distal end 28  
5 of common body 20. Wires 40 may range in diameter from about 0.005 inches to about  
6 0.015 inches, depending on the application.

7 As used herein, the terms “distal” and “proximal” are relative terms only. The  
8 inventors do not intend to impart any limitations of any kind through their use. For  
9 example, as discussed above with respect to FIG. 1A, end 25 of common body 20 is  
10 described as “proximal” while end 28 of common body 20 is described as “distal.” In this  
11 context, as in all other contexts herein, these terms only indicate relative proximity to  
12 either the viewer of the figure, the operator of the delivery device on which the stent is  
13 mounted, or the like. Accordingly, because end 25 is closer to the viewer of FIG. 1A  
14 than is end 28, end 25 is described as being “proximal” and end 28 is described as being  
15 “distal.” Similarly, with respect to the discussion below pertaining to FIG. 5, the  
16 orientation of stent 10 has been reversed in FIG. 5 from its orientation with respect to the  
17 viewer depicted in FIG. 1A. Accordingly, as stated below with regard to FIG. 5, sheath  
18 190 may be oriented over the “proximal” end of the stent—the same end that is described  
19 as “distal” end 28 with respect to FIG. 1A.

20 Bifurcated stent 10 may also be formed from two wires. As illustrated in FIG.  
21 1C, legs 30 have axes 31, and ends 15 (which may be termed proximal ends). Each leg is  
22 shown as being formed from a single wire 40. First segments 46 of wires 40 are  
23 separated from second segments 47 of wires 40 by bends in the wires (in the shape of  
24 loops 45, but which may also be bends 50), which are located proximate ends 15 of legs  
25 30. As shown in FIG. 1C, first segments 46 extend helically in a first direction around  
26 axes 31 away from ends 15 of the legs. Similarly, second segments 47 extend helically in  
27 a second direction around axes 31 away from ends 15 of the legs. First segments 46 cross  
28 second segments 47 in a plurality of locations 48. As shown in FIG. 1C, locations 48  
29 define loops 49, which touch each other such that the loops are contiguous. Loops 49 are

1 “contiguous” because, with the exception of the first and last loops, each loop shares a  
2 point—location 48—with two other loops.

3 In further reference to FIG. 1C, ends 42 of second segments 47 are shown as  
4 being located proximate the distal portions of legs 30 and proximate the proximal portion  
5 of common body 20. These ends 42 may be left free (as shown) or may be may be  
6 coupled together (as described below but not shown) to form closed structures. Ends 42  
7 of first segments 46 are shown in FIG. 1C as forming common body 20. First segments  
8 46 may be arranged about axis 21 of common body 20 in the same manner that the first  
9 and second segments of the wires forming legs 30 may be arranged around axes 31. In  
10 this regard, first segments 46 cross each other in a plurality of locations 48. As with legs  
11 30, locations 48 define loops 49, which touch each other such that the loops are  
12 contiguous. Ends 42 of first segments 46 may be coupled together to form closed  
13 structure 55.

14 First and second segments 46 and 47 may be arranged in different ways with  
15 respect to each other about axes 31. As shown in FIG. 1C, first segments 46 are  
16 positioned farther from axes 31 than second segments 47 at alternate locations 48.  
17 Although not shown, it will be understood to those of skill in the art, with the benefit of  
18 this disclosure, that first segments 46 may be positioned farther from axes 31 at each  
19 location 48. The same is true of first segments 46 with respect to axis 21.

20 In the embodiment of stent 10 depicted in FIG. 1C, loops 49 reside in a series of  
21 planes that includes two groups of planes (not shown) for each leg 30 and for common  
22 body 20, one of which includes the planes passing through the first, third, fifth, *etc.* loops  
23 49, and the other of which includes the planes passing through the second, fourth, sixth,  
24 *etc.* loops 49. The planes in each group are roughly parallel to each other. Additionally,  
25 when body 10 is in its unconstrained state, the planes in one of the groups intersect the  
26 planes in the other group (whether it is a leg or a common body in question) at acute  
27 angles that fall within the range of slightly greater than 0° to about 45°. Moreover, axes

1     **31** and **21** pass generally through the center of each of loops **49** for either the legs or the  
2     common body of stent **10**.

3             In an exemplary embodiment, legs **30** of stent **10** may be formed by various  
4     methods of plain weave including hand weaving and machine weaving. The following  
5     process is an exemplary embodiment of plain weaving according to the present invention.  
6     As shown in **FIG. 11**, a template **300** having a diameter corresponding to the chosen  
7     diameter of the leg of the stent is provided. The top of the template is equipped with  
8     holes **302** around its circumference. Pins **304** are placed through the holes such that they  
9     extend beyond the outer surface of the template on opposing sides. As shown in **FIG. 11**,  
10    wires **40** are bent at about their midpoint around the pins. The bend may result in the  
11    formation of bends **50** as shown, or the wires may be wrapped around the pins to form  
12    small closed loops **45** (not shown). In one embodiment of leg **30**, angle **17** of small  
13    closed loop **45** or bend **50** (**FIG. 1A**) may be less than 90°. In a more typical embodiment  
14    of leg **30**, angle **17** may be equal to or greater than 90°, and may approach, but not  
15    include, 180°.

16            Although only two pins are shown in **FIG. 11**, it is to be understood that this is  
17    done for illustrative purposes only, and not to indicate the appropriate number of wires to  
18    use in any given application. In an exemplary embodiment, template **300** is typically  
19    formed of brass or copper, but may be formed of any suitable material capable of  
20    withstanding the cure temperature discussed below, such as stainless steel. Similarly, in  
21    an exemplary embodiment, pins **304** are typically formed of stainless steel, but may be  
22    formed of any similarly suitable material. It is to be understood that the pins may be  
23    supported by the template by any suitable means capable of withstanding the cure  
24    temperature, including preforming, attachment by welding, threading, or the like.

25            As shown in **FIG. 12**, after the wires have been bent around the pins, the wires are  
26    secured to the template to prevent them from returning to their original, straight, unbent  
27    position. This may be necessary given the superelastic nature of wires such as nitinol and  
28    the like (discussed below). As shown in **FIG. 12**, wires **40** are secured by securing wire

1     **306** around the outside of wires **40** so as to secure wires **40** against the outside of the  
2     template. In an exemplary embodiment, copper is typically used for securing wire **306**,  
3     but it is to be understood that any suitable wire capable of withstanding the curing  
4     temperature of about 500°C discussed below may be used. After the wires are secured,  
5     small weights **360** (shown in **FIG. 15**) are attached to the free ends of the wires using any  
6     suitable means such as tying, or the like. In an exemplary embodiment, weights with  
7     masses of approximately 50-100 grams may typically be used with wires having  
8     diameters of between about 0.005 inches and about 0.011 inches. However, it is to be  
9     understood that weights of different masses may chosen so long as the wires are kept  
10    under tension (*i.e.* straight) during plain weaving (as described below), and properly  
11    balance the central weight (described below).

12           As shown in **FIG. 13**, a stand **330** with a circular plate **320** is provided with an  
13    opening **325**. The diameter of the opening may depend on the diameter of the template.  
14    In an exemplary embodiment, an opening with a diameter of about 4.5 cm may be  
15    typically utilized in conjunction with a template having a diameter of about 1.0 cm. It is  
16    to be understood, however, that an opening with a diameter more closely corresponding  
17    to the diameter of the template may be utilized. It is also to be understood that templates  
18    **300** may have slightly “D-shaped” ends **301** in order to facilitate placement within the  
19    template **400** for the common body as shown in **FIG. 23**.

20           As shown in **FIG. 14**, before or after the weights are attached to the ends of  
21    wires **40**, the template is inverted. In an exemplary embodiment, the weights may be  
22    typically attached to the free ends of the wires prior to inversion of the template such that  
23    the wires are kept under tension and may be prevented from returning to their unbent,  
24    nominal state. A central weight **340** may then be attached to the end of the template. In  
25    an exemplary embodiment, the central weight may have a mass of approximately  
26    600 grams, and may typically be hung from the pins. However, it is to be understood that  
27    a central weight weights of a different mass may chosen so long as the wires are kept  
28    under tension (*i.e.* straight) during plain weaving (as described below), and properly  
29    balance the smaller weights (described above). The central weight may be attached to the

1 template's end in any suitable manner, such as hanging from holes in the template itself,  
2 *etc.*

3 Before or after central weight **340** is attached to the end of the template, the  
4 inverted template is placed through opening **325**, as shown in **FIG. 15**. In an exemplary  
5 embodiment, the central weight may typically be attached to the inverted template after  
6 the inverted template is placed through opening **325**. As shown in **FIG. 15**, the wires **40**  
7 may be arranged fairly evenly around the circumference of the circular plate. As shown  
8 in **FIG. 16**, in an exemplary embodiment of the present invention, 6 wires having 12 ends  
9 numbered 1-12 (each wire having 2 ends) are shown as being arranged in a substantially  
10 symmetrical fashion around circular plate **320**. The weights **340** and **360** typically serve  
11 to keep the wires under tension and in balance. Next, the plain weaving may take place.

12 In the manner shown in **FIG. 17**, the weave may be started by crossing one wire  
13 end over the adjacent wire end. This crossing may be made in either a clockwise or  
14 counterclockwise fashion. This crossing may be carried out as directed by the arrows  
15 shown in **FIG. 17**. After a complete set of crosses (or one "turn") has been carried out,  
16 the location of the crossed wire ends is as shown in **FIG. 18**. In an exemplary  
17 embodiment, the resulting location of the wire ends may be achieved by crossing one wire  
18 end over another in one direction while slightly shifting the wire end not crossed in the  
19 opposite direction. In an exemplary embodiment, for example, this shifting may be about  
20 15°. Thus, wire end 1 may be crossed in a clockwise direction over wire end 2, while  
21 shifting wire end 2 about 15° counterclockwise. Once one turn has taken place, crossing  
22 may begin in the same fashion, but in the opposite direction, as shown in **FIG. 19**. This  
23 process may be repeated until the plain weave is complete.

24 The tightness of the wire mesh (*i.e.*, the angle **a** between the wires - **FIG. 1A**) may  
25 be adjusted by changing the central weight. An increase in the central weight results in a  
26 looser weave (decreased angle **a** between the wires) and vice versa.

27 The other leg of the stent is also woven in the same fashion.

1 In an exemplary embodiment of the plain weave process of legs **30** according to  
2 the present invention, a conventional braiding machine may be utilized to arrange wires  
3 **40** in a plain weave to form legs **30** of stent **10**. In another embodiment, a conventional  
4 braiding machine may also be used to arrange wires in a plain weave to form the common  
5 body of a trifurcated stent (described below). Such a braiding machine may be obtained,  
6 for example, from Wardwell Braiding Machine Company in Central Falls, RI. The  
7 manner in which a plain weave may be achieved using a conventional braiding machine is  
8 displayed in **FIG. 7** of U.S. Patent No. 5,419,231 to Earle, III *et al.* (1995), which is  
9 hereby expressly incorporated by reference, as well as in **FIG. 1** of U.S. Patent No.  
10 5,485,774 to Osborne (1996), which is hereby expressly incorporated by reference.

11 Once the two legs have been woven, the templates **300** may be assembled with a  
12 template **400** for the common body as shown in **FIGS. 24** and **25A-C**. The weaving is  
13 then continued in the same manner around the common body template. The only  
14 difference being that the number of wires being woven has doubled. Or, if the number of  
15 wires in the pluralities of wires used to form the respective legs of the stent is different,  
16 the number of wires in the plurality of wires that are woven to form the common body  
17 includes the wires from both of the pluralities of wires used to form the legs. As  
18 indicated in **FIGS. 23-25C**, in an exemplary embodiment according to the present  
19 invention, template **400** may be generally cylindrical in shape. In such an embodiment,  
20 the shape of a short portion of template **400** near end **401** into which the two leg  
21 templates may be placed may be generally elliptical for a short portion. It is to be  
22 understood, however, that a common body having a consistently cylindrical shape may  
23 also be used.

24 After the weaving of the common body is complete, the adjacent wire ends **42**  
25 (**FIG. 1A**) may be coupled together to form closed structures **55** in any suitable fashion  
26 capable of withstanding the heating described below, and capable of restraining the wires  
27 from returning to their straight, unbent configuration as indicated in **FIG. 26**. In one  
28 embodiment, the wire ends may be coupled together utilizing at least two twists as shown  
29 in **FIG. 26**. In one embodiment, 6 twists may be used. Regardless of the number of



1 twists used, it is preferable to keep the twisted wire ends as short as possible. The shorter  
2 the twisted wire ends are kept, the more resistant to bending the twisted wire ends are.  
3 As a result, the twisted wire ends will be less likely to be inadvertently displaced during  
4 insertion, positioning, repositioning, or retrieval, thus reducing their potential for causing  
5 tissue damage. In other embodiments, the wire ends may be coupled together by bending  
6 or crimping a metal clip around the wire ends, by tying the wire ends together with any  
7 suitable material such as stainless steel wire, by welding, *etc.*

8 Other configurations of template **400** may also be utilized consistently with the  
9 present disclosure. For example, template **400** may be provided with pins around which  
10 the wire ends may be twisted in fashioning closed structures **55**. Finish pins **800** may be  
11 supplied on a ring, such as ring **802** depicted in **FIG. 43**, in any suitable fashion,  
12 including, for example, through removable or permanent attachment. Ring **802** may be  
13 configured to threadably engage template **400** as depicted in **FIG. 43**. In other  
14 embodiments, ring **802** may be configured to engage template **400** by virtue of frictional  
15 forces (not shown) or may be configured to be secured to template **400** as would a clamp  
16 (not shown). Finish pins **800** may also be engaged with template **400** in the same manner  
17 that pins **304** are engaged with template **300**. As shown in **FIG. 44**, in such an  
18 embodiment, template **400** may be provided with finish holes **804** similar to holes **302**,  
19 and finish pins **800** may be placed through finish holes **804**. Ring **802** may also be  
20 utilized in place of holes **302** and pins **304**.

21 In an embodiment in which finish pins **800** are engaged with template **400** through  
22 the utilization of ring **802**, the number of finish pins utilized may be equal to the number  
23 of wires that are used to form both legs. Template **400** may be threaded along any portion  
24 of its length so as to best accommodate a variety of common body sizes. For example,  
25 only a portion of template **400** may be threaded, as depicted in **FIG. 43**. Threads need  
26 not be utilized with a ring that engages template **400** by virtue of frictional forces.

27 An advantage afforded by the use of ring **802** is the ease with which the precise  
28 length of common body **20** may be achieved through the adjustment of the position of

1 ring **802**. Further, the use of ring **802** also facilitates the symmetrical alignment of finish  
2 pins **800** with the longitudinal lines formed by the points at which the wire segments  
3 cross each other within the weave such that the symmetry of the weave may be  
4 maintained and any structural benefits stemming from that symmetry may be realized.

5 In an embodiment in which finish pins **800** are placed through finish holes **804**,  
6 the number of finish pins utilized may be equal to one-half of the number of wires that are  
7 used to form common body **20**, since both ends of the finish pins will be utilized.  
8 Template **400** may be provided with finish holes **804** along any portion of its length so as  
9 to best accommodate a variety of stent sizes. For example, only a portion of template **400**  
10 may be provided with finish holes **804**, as depicted in **FIG. 44**. As with ring **802**, the use  
11 of finish holes **804** advantageously allows the user to easily and precisely achieve a given  
12 length for common body **20**.

13 With the finish pins in place, once the wire ends of the wires have been woven  
14 around the common body template, the wire ends may be secured around the finish pins  
15 in any suitable manner to form closed structures, including by twisting, bending,  
16 wrapping and the like. In one embodiment, the wire ends may be crossed, then bent  
17 around a finish pin and then secured together with a short piece of thin-walled metal  
18 tubing. Such a joint may then be reinforced by soldering, welding, or the like. A suitable  
19 number of additional twists may be utilized after securing the wire ends around the finish  
20 pins in forming closed structures. Securing wires (*see* securing wire **306** depicted in **FIG.**  
21 **12**) may be utilized to secure the closed structures to the common body template during  
22 annealing.

23 As a result of securing the wire ends around the finish pins, the angle created  
24 between the crossed wire ends may be similar, if not identical to, the angle of the other  
25 crossed wires in the woven legs described above. Advantageously, by using finish pins,  
26 this angle between the crossed wire ends may be maintained, preventing the weave of the  
27 woven stent from loosening. Were loosening to occur, the expansile or radial force of the  
28 portion of the stent with the loosened weave could decrease, causing that portion of the  
29 stent to remain elongated within the structure in which it is placed. Therefore, through

1 the use of finish pins and as a result of the correlating maintenance of the angle between  
2 the crossed wire ends that are wrapped or twisted around the finish pins, the tightness of  
3 the weave along the length of the legs and common body of the stent – from end to end –  
4 may be consistent and resistant to loosening. Further, the expansile force of the end of  
5 the stent having closed structures (*i.e.*, the distal end of the stent) may be comparable to  
6 the expansile force of the other portions of the stent.

7 Another method of forming legs **30** of stent **10** and ultimately stent **10**, according  
8 to the present invention, is illustrated in **FIGS. 31-42B**. As shown in **FIG. 31**, the base  
9 of template **300** may be equipped with longitudinal tabs **700** formed by two longitudinal  
10 cuts connected by a transverse cut. The length of the cuts may be determined based upon  
11 the size of the template chosen. For example, a template that is about 10 mm in diameter  
12 may have longitudinal tabs with longitudinal cuts about 4 to 5 mm long, and the  
13 connecting transverse cuts may be about 2 mm long. As illustrated in **FIGS. 31**, tabs **700**  
14 may be slightly elevated from the surface of template **300** and may be positioned  
15 symmetrically around template **300**.

16 **FIGS. 31** and **32A** and **B** also illustrate that wires **40** may be bent around tabs **700**  
17 at selected points located between the ends of the wires to form bent portions along wires  
18 **40**. The bent portions may take the form of bends **50**, as shown in **FIG. 32A**, or may be  
19 further wrapped around tabs **700** to form loops **45**, as shown in **FIG. 32B**. Angle **b** of  
20 bends **50** or loops **45** may be less than 90°. In a more typical embodiment of the legs of  
21 the present stents, angle **b** may be equal to or greater than 90°, and may approach but not  
22 include, 180°. The bent portions may be arranged to define the ends of the legs. The  
23 ends of the wires may then be weaved to create the legs using, for example, the following  
24 machine weave method.

25 As shown in **FIG. 33**, the ends **42** of each wire **40** may be arranged around a pair  
26 of bobbins **702**. The length of the wire wound around each bobbin may be determined by  
27 considering the total length of the wire needed to form the leg as well as the wire length

1 needed to arrange the bobbins around the weaving plates (shown in **FIG. 34**), which are  
2 discussed below in greater detail.

3 As shown in **FIG. 34**, in one embodiment in which bobbins **702** are utilized, two  
4 coaxially arranged weaving plates may be utilized. As shown in **FIG. 35**, upper weaving  
5 plate **704** and lower weaving plate **706** may be positioned in different horizontal planes.  
6 **FIG. 35** illustrates that the weaving plates may be equipped with multiple bobbin  
7 rods **708**, the axes of which are substantially perpendicular to the weaving plates, on  
8 which bobbins **702** may be slidably secured. (**FIG. 35** depicts only 4 bobbins for the sake  
9 of simplicity.) The weaving plates may be provided with holes therein through which  
10 template **300** and/or wires **40** may pass, as shown in **FIG. 35**. Template **300** may be  
11 secured to the base of the weaving machine chosen using any suitable means such as  
12 template rod **710**, around which template **300** may be slidably placed (**FIG. 35**).  
13 Template rod **710** may be configured to firmly engage template **300** through frictional  
14 forces (*e.g.*, by tapering template rod **710**). Instead of template rod **710**, any appropriate  
15 lock mechanism may be used to secure the base of the weaving machine to template **300**.

16 As shown in **FIGS. 36A** and **37A**, the pairs of bobbins **702** may be prepared for  
17 weaving by arranging one bobbin on upper weaving plate **704** and the other bobbin from  
18 the pair on lower weaving plate **706**. Wires **40** may then be bent around tabs **700**, and the  
19 ends of the wires may be attached to bobbins **702** using any suitable means capable of  
20 holding wires **40** under tension throughout the weaving process. An example of such a  
21 mechanism is a one-way brake that allows bobbins **702** to rotate in a single direction only,  
22 such that wires **40** may wind off bobbin **702**. Simultaneously, such a brake may be  
23 configured so as to continuously maintain tension in wires **40** by virtue of the brake's  
24 resistance to the winding off of wires **40**.

25 As shown in **FIG. 36A**, with the ends of the wires in place, the weaving may  
26 begin by crossing the ends of the same wire, which results in the formation of a small  
27 caliber loop **45** (**FIG. 36B**) at the site of the bent portion. In another manner of weaving

1 illustrated in **FIG. 37A**, the ends of different wires may be crossed first, resulting in bend  
2 **50** at the site of the bent portion (**FIG. 37B**).

3 As shown in **FIGS. 38-39**, the two weaving plates may be arranged such that the  
4 surfaces thereof from which bobbin rods extend face each other. In this alternative  
5 embodiment, the diameters of the plates may be the same or different. Wires **40** may be  
6 arranged on bobbins **702** in the same manner as described above, as shown in **FIG. 39**.

7 Despite which of the aforementioned weaving plate arrangements is utilized, the  
8 weaving plates rotate in opposite directions during the weaving process. The weaving  
9 plates may be operated at any suitable speed. In this regard, a speed as low as 1 to 10  
10 cycles per minute is acceptable. The weaving plates may also be driven by hand.

11 The weaving plates may supported and rotated using any suitable means. **FIG. 45**  
12 illustrates one means of supporting and rotating weaving plates **704** and **706**. (**FIG. 45**  
13 depicts on 4 bobbins for the sake of simplicity.) As shown, weaving plate supporter **750**  
14 may be equipped with lower arm **752** and upper arm **754** for supporting lower and upper  
15 weaving plates **706** and **704**, respectively. Weaving plate drivers **760** may be secured to  
16 the upper and lower arms of the weaving plate supporter and engaged with the weaving  
17 plates in order to operate them. The drivers may be configured to operate in any suitable  
18 fashion. For example, the drivers may be configured with a power source and provided  
19 with gears of any suitable configuration for causing the weaving plates to rotate. The  
20 drivers may also be configured to utilize magnetism or electromagnetism to rotate the  
21 weaving plates. The drivers may be also be configured such that the weaving plates may  
22 be rotated by hand. Further, although not shown, it will be understood to those of skill in  
23 the art, with the benefit of this disclosure, that either or both of the upper and lower arms  
24 may be provided with branches to which drivers may be attached. The drivers on the  
25 branches could then be secured to or engaged with the top surfaces of the weaving plates  
26 in the same fashion that drivers **760** are engaged with the bottom surfaces of the weaving  
27 plates as shown in **FIG. 45**. Thus, in such an embodiment, both the top and bottom  
28 surfaces of each weaving plate would be engaged with drivers.

1           Once the legs have been weaved, one of the weaving machines used to weave one  
2   of the legs may be utilized to continue weaving the common body of the stent. To do so,  
3   first, the bobbins and the corresponding wires may be rearranged around half of the  
4   weaving plates of one of the "leg" machines. The template with the other woven leg may  
5   be positioned and secured beside the first leg's template. The template configured for the  
6   common body of the stent, if one is used, may then be placed over both leg templates, or  
7   one template leg may be inserted into an opening of the common body template if such a  
8   configuration is utilized. The bobbins and corresponding wires of the second leg may  
9   then be arranged around the other half of the weaving plates, which is free of the first  
10   leg's bobbins and wires. The weave may then be continued on the common body  
11   template by rotating the weaving plates in opposite directions.

12           A bifurcated stent may also be created using only two templates consistent with  
13   the present disclosure. As shown in **FIG. 46**, template **300** is shown having template  
14   projections in the form of tabs **700** arranged around the template proximate the proximal  
15   end thereof. The distal end of template **300** is shown as being hidden from view because  
16   it is inserted into opening **425** of template **450**. Template projections in the form of tabs  
17   **700** are also arranged around template **450** proximate the proximal end thereof. When  
18   templates **300** and **450** are utilized together, a leg may be woven around template **300** in  
19   any manner described above. Further, wires for the other leg may be bent around the tabs  
20   arranged around the proximal end of template **450**, and the ends of those wires may be  
21   woven around portion **453**, the portion of template **450** located proximally of opening  
22   **425**. The wires from the two legs may be combined and woven around portion **457** to  
23   create the common body and the stent. As shown in **FIG. 46**, portion **457** is the portion  
24   of template **450** located distally of opening **425**.

25           A braiding machine suitable for carrying the weaving process just described (*i.e.*,  
26   utilizing the weaving plates) may be obtained, for example, from Wardwell Braiding  
27   Machine Company in Central Falls, RI.

28           After the weaving process is complete, the ends of the wires may be twisted  
29   together or coupled as described above to form closed structures. To make the process of

1 wire twisting faster and easier, the wires may be twisted with a special hand tool designed  
2 for this purpose. Tool 712 illustrated in FIG. 41A follows the principle of an automatic  
3 pencil. Jaws 714 of tool 712 are configured so that the ends of the wires may be firmly  
4 held between jaws 714. Jaws 714 may be activated by push button 716 moving against  
5 spring 718. After placing the wire ends into pre-formed gaps 720 located between jaws  
6 714 (FIG. 41B), spring 718 expands (or returns to its unconstrained state) and retracts  
7 jaws 714, securing the wire ends firmly between jaws 714 due to the pressure of outer  
8 housing 722 acting to close jaws 714. Outer housing 722 may then be rotated to create  
9 multiple twists of the wire ends. As illustrated in FIGS. 42A and 42B, the twisted ends  
10 of common body 20 may be secured to template 400 using transverse tabs 724, which  
11 may be formed the same way as longitudinal tabs 700.

12 Next, the bifurcated stent may be heated at about 500°C for 5 to 15 min,  
13 preferably about 12 to 15 min and then allowed to cool to room temperature. In one  
14 embodiment, the bifurcated stent may be heated to 500°C for 15 minutes. As a result, the  
15 wires of the stent may exhibit superelastic properties. The initial shape of a stent  
16 programmed with superelasticity may be deformed by applying a force thereto. The  
17 shape memory of the stent may then be activated by removing the force, and the stent may  
18 substantially recover its initial shape. As used herein, “substantially recover” means that  
19 recovery need not be such that the exact original shape be regained. Rather, it is meant  
20 that some degree of plastic deformation may occur. In other words, recovery need not be  
21 total. In another embodiment, the stent may be programmed with thermal shape memory  
22 by heating it to about 500°C for about 60 to 120 minutes, typically about 120 minutes, in  
23 an oven. In one embodiment, the bifurcated stent may be heated to 500°C for 120  
24 minutes. The initial shape of a stent programmed with thermal shape memory may be  
25 deformed upon application of a force at a first temperature. The force may be removed,  
26 and the stent may remain deformed. The shape memory of the stent may then be  
27 activated by heating the stent to a second temperature, at which temperature the stent may  
28 substantially recover its initial shape.

1           To make the final shape of the stent including the creation of slightly tapered legs  
2     and the adjustment of the angle between the common body and the legs, the stent may be  
3     remodeled on another template and reheated. The attachment to the remodeling template  
4     may be achieved in a fashion similar to the manner in which the wires are originally  
5     attached to the template, *e.g.*, wrapped copper wires. Reheating may be done using a  
6     similar time and temperature as the initial heating. The stent crown **28** may also be flared  
7     for better fixation of the stent **10**, with remodeling and reheating. After cooling down to  
8     room temperature, the stent wires may exhibit superelastic properties. It is to be  
9     understood that if the stent is remodeled a number of times and it is not intended that the  
10    stent be programmed with thermal shape memory, care should be taken not to exceed a  
11    total heating time (which includes the first heating time *and* the second heating time, *etc.*)  
12    of about 60 minutes, because at about 60 minutes, the stent may be programmed with  
13    thermal shape memory.

14           In an exemplary embodiment of stent **10**, after heating and cooling, it is preferable  
15    to further reinforce the coupled wire ends **42** of closed structures **55** (particularly if they  
16    were coupled using twists) by any suitable means such as point welding, soldering,  
17    pressure welding, or the like, in order to better ensure that the coupled wire ends will not  
18    separate during delivery (to be discussed in detail below). Coupled wire ends **42** may be  
19    soldered by removing any oxide layer that may have formed over the relevant portions of  
20    the wires used, and applying solder to those portions. Soldering may be enhanced by first  
21    wrapping coupled wire ends **42** with thin stainless steel wires. In an exemplary  
22    embodiment, point welding is preferred to soldering, because point welding is easier to  
23    perform than soldering, and may be more suitable with regard to long-term implantation  
24    of the stent.

### 25                                   *Biodegradable Version*

26           The bifurcated stent of the present invention (and the trifurcated stent discussed  
27    below) may be formed with filaments made of biodegradable material so as to form a  
28    self-expanding, bioabsorbable, biodegradable stent that may, in addition to functioning as  
29    a stent, function as drug or nutrient delivery systems as a result of the material used.



1 Many factors may be considered in choosing materials from which to form the  
2 biodegradable bifurcated stent of the present invention. In one embodiment, the  
3 biodegradable stent of the present invention may be formed from materials of minimal  
4 thickness so as to minimize blood flow blockage and facilitate bioabsorption. In another  
5 embodiment, the material may be chosen so as to exhibit sufficient radial strength to  
6 allow the body formed to function as a stent. The material from which the biodegradable  
7 stent may be formed may also degrade within the bloodstream over a period of weeks or  
8 months, so as not to form emboli. However, the material may be chosen such that the  
9 stent does not degrade before an endothelial layer forms in the stented vessel or structure  
10 in cases in which vascular stenoses of arteriosclerotic origin are treated. The material  
11 chosen may be chosen to be compatible with surrounding tissue in the vessel as well as  
12 with blood.

13 The bifurcated biodegradable stent may be formed by plain weave using the  
14 methods above described. The size of the filaments used may vary according to the  
15 application. In some embodiments, the filaments may be reduced in size in comparison  
16 to the size of wires used in comparable applications involving non-biodegradable stents.  
17 In other embodiments, the number of filaments used may be increased in comparison to  
18 the number of wires used in comparable applications involving non-biodegradable stents.

19 The minimum number of filaments that may be used to create the legs of the  
20 bifurcated stent may be about 5. In one embodiment, 12 filaments may be used. The  
21 minimum number of filaments that may be used to create the legs of the trifurcated stent  
22 (described below) may be about 5. In one embodiment, 8 filaments may be used. The  
23 minimum number of filaments that may be used to create the common body of the  
24 trifurcated stent (described below), prior to the legs being added thereto, may be about 10.  
25 In one embodiment, 8 filaments may be used. In creating the stent using plain weave, the  
26 angle of the crossed filaments (described above as angle **a**) may vary as described above,  
27 but is typically 150-160°. In one embodiment, the angle of the crossed filaments may be  
28 as large as possible to achieve the largest radial force possible and further ensure that the  
29 stent may have enough expansile force to remain in place after being delivered. The

1 filament ends, after plain weaving is complete, may be coupled together to form closed  
2 structures using any suitable means such as by heat treatment or sealing, gluing, tying,  
3 twisting, crimping, taping, or the like.

4 In one embodiment, the filaments used may be made of polyglycolic acid  
5 ("PGA"), poly-L-lactic acid ("L-PLA"), polyorthoesters, polyanhydrides,  
6 polyiminocarbonates, or inorganic phosphates. These polymers are commercially  
7 available from United States Surgical Corporation, Norwalk, CT; Birmingham Polymers,  
8 Inc., Birmingham, AL; and Ethicon, Sommerville, NJ, for example. One factor to  
9 consider in choosing a material from which to make the filament will be the goal of the  
10 stent placement. For example, in an embodiment in which the stent serves mainly as a  
11 drug delivery system, PLA may be used because of its rapid degradation time. In another  
12 embodiment in which the stent serves mainly to maintain the patency of the vessel (*i.e.*,  
13 keeping the vessel open) and as a scaffold or frame for the development of a new  
14 endothelial layer, PGA may be used considering its high strength and stiffness. In other  
15 embodiments, glycolide may be copolymerized with other monomers to reduce the  
16 stiffness of the resulting fibers that may be used.

17 In another embodiment, any of these filaments may be provided with about 0.05  
18 to 0.25 percent by weight of a basic metal compound, such as calcium oxide, calcium  
19 hydroxide, calcium carbonate, calcium phosphate, magnesium oxide, magnesium  
20 hydroxide, magnesium carbonate, magnesium phosphate, sodium phosphate, potassium  
21 sulfate or the like, to increase the *in vivo* strength retention of the biodegradable stent by  
22 about ten to twenty percent or more, as described in U.S. Patent No. 5,478,355 to Muth *et*  
23 *al.* (1995), which is hereby expressly incorporated by reference. As used herein, "*in vivo*  
24 strength retention" refers to the ability of a biodegradable body to retain its strength (*i.e.*,  
25 the breaking load of the body) after being implanted or delivered into a living creature. In  
26 yet another embodiment, a filament obtained from a polymer containing about 15 to about  
27 30 mole percent glycolide in a melt spinning operation, as described in U.S. Patent No.  
28 5,425,984 to Kennedy *et al.* (1995), which is hereby expressly incorporated by reference,  
29 may be used to form a biodegradable body.

1           The filaments of the biodegradable stent may incorporate one or more drugs that  
2           positively affect healing at the location where the stent is delivered. In one embodiment,  
3           these drugs may include anticancer drugs such as paclitaxel (which is commercially  
4           available as TAXOL, from Bristol-Myers Squibb in Princeton, NJ) or docetaxel (which is  
5           commercially available as TAXOTERE, from Rhone-Poulenc Rorer in Collegeville, PA),  
6           fibroblast/smooth muscle cell proliferation-preventing agents, and antithrombogenic  
7           drugs such as heparin which is commercially available from Wyeth-Ayers in  
8           Philadelphia, PA.

9           One or more drugs may be incorporated into a polymer using any suitable means.  
10          For example, in one embodiment, the drugs as a solute may be dissolved in the  
11          biodegradable polymer as a solvent to form a solution. The solution may then be  
12          hardened into a fiber from which the stent may be woven. In another embodiment,  
13          simple mixing or solubilizing with polymer solutions may be utilized. The drugs may  
14          also be dispersed into the biodegradable polymer during an extrusion or melt spinning  
15          process. In yet another embodiment, the biodegradable fibers that have already been  
16          formed may be coated with drugs.

17          The biodegradable filaments may be rendered radiopaque to facilitate their  
18          monitoring under fluoroscopy and/or their follow-up using radiographs, fluoroscopy, or  
19          computerized tomography. The methods described above for incorporating the drugs into  
20          the polymer may be used to mix radiopaque salts, such as tantalum, with the polymer.

21          As used herein, "degradation time" refers to the time during which the  
22          biodegradable stent maintains its mechanical integrity. One factor that should be  
23          considered in choosing a polymer in light of its degradation time is that the polymer will  
24          lose its mechanical integrity before it is completely absorbed into the body. For  
25          example, pure polyglycolide (PGA) sutures lose about 50% of their strength after 2  
26          weeks, and 100% at 4 weeks, and are completely absorbed in 4-6 months. For vascular  
27          applications (*i.e.*, applications in which the stent is placed within a vessel in a body),  
28          polymers having degradation times of about one to twenty-four months may be used,  
29          depending on the application. In a typical embodiment, a polymer having a degradation

1 time of about one to three months may be used. In choosing a polymer for non-vascular  
2 applications such as the esophagus, colon, biliary tree, ureter, *etc.*, one should consider  
3 the polymer's ability to withstand the chemical stimuli in the given environment.

4 During the degradation time of the biodegradable stent, a new endothelial layer  
5 may form on the surface of the stent. The rate of the release of the drugs which may be  
6 incorporated into the polymers may be controlled by the rate of degradation of the  
7 biodegradable material used. Thus, the rate of release of a drug may act as a control  
8 quantity for the rate of degradation. At the same time, other agents such as fibronectin  
9 from human plasma (commercially available from Sigma, St. Louis, MO) may be added  
10 to the polymer used (using any suitable means described above for incorporating drugs  
11 into the chosen polymer) and may affect the rate of biodegradation. For example,  
12 fibronectin may accelerate the growth of cells around the surrounding stent, which, in  
13 turn may accelerate the resorption reactions around the stent.

14 In one embodiment of a biodegradable stent according to the present invention,  
15 one or more shape memory wires may be added to the either the legs or the common body  
16 of the bifurcated or trifurcated stents for reinforcement after forming the leg or common  
17 body using plain weave. Such wires may comprise nitinol or any other comparable  
18 material above described. In one embodiment, the wires may be formed from nitinol  
19 having about 55 to 56% Nickel and 45 to 44% Titanium (Shape Memory Applications).  
20 The wire or wires may be incorporated into the woven biodegradable structure by  
21 threading the wire in and out of openings in the leg several times. In one embodiment,  
22 the manner in which the wire is threaded in and out of openings in a leg is shown in  
23 **FIG. 28**. In **FIG. 28**, designation **520** shows reinforcement wire **510** passing outside  
24 biodegradable leg **500**, and designation **530** shows reinforcement wire **510** passing inside  
25 biodegradable leg **500**, thus showing how wire **510** may be threaded in and out of  
26 openings in leg **500**. As shown in **FIG. 28**, the reinforcement wire(s) **510** may be led  
27 between (*i.e.*, parallel to) two biodegradable filaments **540** and may follow their helical  
28 course. As shown in **FIG. 28**, reinforcement wire **510** may be secured to leg **500** with  
29 loops **550**, or any other suitable means such as tying, twisting, or the like. Loops **550** may

1 be placed around a filament or around the intersection of one or more filaments. As a  
2 result, the wire can move in harmony with the weave and will not interfere with the  
3 movement of the filaments in the weave. By activating the shape memory of  
4 reinforcement wire **510**, ends **560** and **570** of leg **500** may be pulled together, resulting in  
5 a tighter weave. As a result, the expansile force of the stent and its resistance to outer  
6 compression may significantly increase. In one embodiment, loops **550** may also be used  
7 in securing leg **500** to a delivery system.

8 In another embodiment shown in **FIG. 29**, in which a reinforcement wire is  
9 threaded in and out of openings in a biodegradable leg according to the present invention,  
10 reinforcement wire **510** may be bent at a selected point located between its ends, typically  
11 at about the mid-point of the wire, and a small loop **512** may be created (similar to the  
12 small closed loops described above). As shown in **FIG. 29**, small loop **512** may be  
13 entwined around a filament or the intersection of one or more filaments, and  
14 reinforcement wire **510** may be threaded in and out of the openings in leg **500** as  
15 described above, and may be secured to leg **500** with loops **550**, or any other suitable  
16 mean, as above described. Both portions **514** of reinforcement wire **510** may be  
17 symmetrically led along both sides of leg **500** following the sinuous/helical course of the  
18 biodegradable filaments. As described earlier, by activating the shape memory of  
19 reinforcement wire **510**, ends **560** and **570** of leg **500** may be pulled together, resulting in  
20 a tighter weave. As a result, the expansile force of the stent and its resistance to outer  
21 compression may significantly increase. In one embodiment, loops **550** may also be used  
22 in securing leg **500** to a delivery system.

23 In one embodiment, the size of reinforcement wire **510** may range from about  
24 0.005 inches to about 0.012 inches. It is to be understood that increasing the size of  
25 reinforcement wire **510** may increase the force with which ends **560** and **570** are pulled  
26 together when the shape memory of the wire is activated. It is to be understood that using  
27 more than one wire may have the same effect as increasing the size of the wire.

In one embodiment, reinforcement wire(s) **510** may be formed around a template as above described. The reinforcement wire(s) may then be programmed with superelasticity or thermal shape memory as described herein.

### *Bench-work*

With regard to the biodegradable version of the stents according to the present invention, the inventors have used an open-ended plain woven nylon leg (that is, the filament ends were not coupled together to form closed structures after weaving) for initial bench work. The leg was woven using 0.007 inch nylon filaments. The number of filaments used was 16, and the unconstrained diameter of the leg was 11 mm. In an unconstrained state, the size of the weave holes was approximately 1 mm. The expansile force of the leg was relatively good, and after maximum elongation the leg readily reverted to its unconstrained diameter. Compressing the leg from its two ends longitudinally, the expansile force could be increased considerably. At the maximal longitudinal compression, the diameter of the leg was 13 mm. Holding both ends of the leg, it became virtually incompressible.

A 0.006" nitinol wire was threaded through the holes of the unconstrained mesh in the manner described earlier. The wire was a straight nitinol wire and was not formed on a template and programmed with either thermal shape memory or superelasticity. The straight wire caused the leg to elongate and the unconstrained diameter of the leg decreased to 9.5 mm (13% lumen-loss though the other characteristics of the leg did not change. The woven tubular leg could be elongated completely as well as compressed maximally.

### Possible Applications of the Stent

The present invention makes it possible to use stent **10** in several vascular and non-vascular territories where bifurcated anatomical structures are present. The range of possible vascular applications includes the aorto-iliac bifurcation, the superior vena cava (SVC) junction, and the inferior vena cava (IVC) junction. After recanalizing an extended aorto-bi-iliac obstruction (Leriche syndrome), the stent would be ideal to

1 maintain the lumen of the aorto-iliac bifurcation. For treatment of an abdominal aortic  
2 aneurysm, the stent may be covered using some kind of elastic covering material, turning  
3 it into a stent-graft. The stent would also be an ideal solution for treatment of tracheo-  
4 bronchial obstructions. The bifurcated stent may also be used in hilar biliary stenoses  
5 (*e.g.*, Klatskin tumors). For stenting malignant stenoses, the stent may be equipped with a  
6 special cover (*e.g.*, of polyurethane or silicon) and/or with an anticancer coating. Another  
7 possible application may be stenting the venous side of a hemodialysis access graft after  
8 dilating the venous stenosis to maintain the lumens of both the graft and the parent vein.

9       The stent according to the present invention makes it possible to change the  
10 angles between the crossing wires (*e.g.*, creating a tighter weave and/or a tapering shape),  
11 resulting in a controlled expansile force. Selecting the angles between the crossing wires  
12 so that they are close to the practical maximum of 180°, the expansile force of the stent  
13 may be increased to the point that a virtually incompressible stent may be created. As  
14 discussed in the Examples herein, the *in vitro* studies suggest that the same size nitinol  
15 stent with a similar mesh tightness as the WALLSTENT (Schneider, Minneapolis, MN;  
16 Boston Scientific Vascular) may exert much more resistance to outer compression (*see*  
17 Tables 2 and 3 below). This feature may be utilized in some vessel stenoses/obstructions  
18 caused by space occupying malignancies (*e.g.*, SVC syndrome), where high outer  
19 compressive forces are present.

20       The angle between the main body **20** and the legs **30** may be adjusted to  
21 accommodate the patient's anatomy. Because of the flexibility of the stent, the angle  
22 between the legs **30**, which may be selected according to the average sizes of the given  
23 anatomical structure, may be used in the majority of the cases. The angle for a  
24 tracheobronchial application may be about 45 to 70°. In humans, the trachea bifurcation  
25 typically has an angle of about 65°. Similarly, the cross-section of the main body **20** may  
26 also be changed from a round to somewhat elliptical shape, if necessary (*e.g.*, tracheo-  
27 bronchial application). For better fixation of the stent, the crown **28** of the common body  
28 **20** may be flared. The length of the stent's common body **20**, as well as the legs **30** may  
29 also be varied according to the particular requirements of the anatomy.

1           The stent may then be stretched to reduce its diameter as much as possible. Then,  
2           using a delivery system according to the present invention, which may hold the stent in a  
3           stretched state, the stent may be inserted into the bifurcated tubular structure to be  
4           stented.

## 5           **Delivery Systems and Stent Deployment**

6           The present invention also includes delivery systems for the stent, which may vary  
7           according to the applications of the stent. Two basic versions of the delivery systems are  
8           the tracheo-bronchial type and the aorto-iliac type.

### 9           **A. Tracheo-Bronchial Application**

#### 10          **a. First Embodiment**

11           **FIG. 3** is a diagram of an exemplary embodiment of the front part of a delivery  
12           system **100** according to the present invention, which comprises two small caliber tubes  
13           or legs **110** (which may be constructed of Teflon, PVC, Nylon, or any other suitable  
14           material) which fit within either a funnel-shaped sheath (or a Y-shaped) piece **120** (which  
15           may be constructed of a similar material to **110**). A single lumen tube **140** also fits within  
16           this funnel or the common trunk of the Y-shape piece **120**. Tube **140** may be made of a  
17           thin-walled, flexible, metal microtubing. In one embodiment, tube **140** may be made of  
18           nitinol (commercially available from Shape Memory Applications). The distal end **115** of  
19           each small caliber tube may be equipped with two holes positioned close to the tip. Two  
20           securing wires **130**, which in an exemplary embodiment may be nitinol wires between  
21           about 0.009"-0.013" (as used herein, 0.009" means 0.009 inches, and the like) thick, one  
22           in each leg **110**, may be used to hold the distal end of the stent legs **30**. Other materials  
23           from which securing wires **130** may be formed include any superelastic or pseudoelastic  
24           materials. In one embodiment, securing wires **130** (and all other wires described in **A.**  
25           and **B.** herein) may be nitinol wires which comprise about 55-56% Nickel and about 45-  
26           44% Titanium (commercially available from Shape Memory Applications). In an  
27           embodiment in which the securing wires of the present invention are nitinol (including



wires **130** and the others discussed below), the nitinol securing wires may be heat treated as described herein or purchased from a manufacturer such that the superelastic properties of the nitinol may be utilized. These nitinol securing wires **130** come out from the lumen **140** through the proximal hole and go back through the distal hole, forming a small profile tight loop **135** between the two holes, as shown in **FIG. 3**. The nitinol securing wires **130** are threaded into the single lumen tube **140** after passing the funnel or the Y-shape piece **120**. The distal 1.5-2.0-cm-long ends of the nitinol securing wires **130** may be equipped with a small piece of soft tip to facilitate maneuvers within the tracheo-bronchial system. The bifurcated stent **10** is placed over this Y-shaped tubing assembly with the distal legs attached to the tight nitinol wire loops between the holes. That is, wire **130** may be threaded through the proximal hole, through a closed structure (such as a bend or small closed loop or another opening in the weave), and back into the lumen of tube **110** through the distal hole.

It is to be understood that in an exemplary embodiment of delivery system **100** according to the present invention, multiple securing wires may be utilized instead of one in each leg **110** of the delivery system. In this embodiment, the distal ends of legs **110** should be equipped with a series of pairs of holes arranged substantially evenly around the circumference of the legs.

It is to be understood that in an exemplary embodiment of delivery system **100**, two steerable guidewires with good torque control, preferably made of nitinol (commercially available from Microvena Co. in White Bear Lake, MN), may be utilized instead of flexible pieces of soft tip. The guidewires may be equipped with a soft radiopaque tip (made from platinum, tungsten, or any other suitable material) and may be placed in the lumens of the tubes **110** and in the single lumen tube **140**. In a further embodiment, these tubes may be equipped with two channels; one channel may be created for the securing wires and the other for the guide wires. As a result, the movement of the guidewires during manipulations will not interfere with the firm position of the securing wires and vice versa.

1           To create some free covered space around tube **140** immediately behind the  
2           conflation of tubes **110**, a short segment **160** of a larger caliber thin-walled sheath may  
3           cover tube **140** as well as the proximal ends of the small caliber tubes **110**. If the  
4           connection between the small caliber tubes and tube **140** is created by a funnel shaped  
5           piece **120**, **120** and **160** may be fabricated from the same piece (as shown in **FIG. 3**). If a  
6           Y-shape piece is used, segment **160** may be attached to the common trunk of the Y-shape  
7           piece **120**. In such an embodiment, **120** and **160** may be fabricated from the same piece.  
8           The created space may be used to hide inverse tabs attached to the proximal part of the  
9           delivery system **100**.

10           Coaxially, a larger tube **170** (which may be Teflon or any other material described  
11           above and two French-sizes larger than tube **140**) may be positioned over tube **140**. Near  
12           its distal end **175**, tube **170** may be equipped with some metal hooks **180** facing  
13           proximally (**FIG. 3**). These inverse metal hooks **180** may be used for securing the  
14           proximal end of the common body **20** of stent **10**.

15           After securing both the legs **30** and the common body **20** of stent **10** using the low  
16           profile nitinol loops and the inverse hooks **180** (which may be threaded through the  
17           closed structures or other openings near the stent's end), the stent may be maximally  
18           stretched over the tubes, as shown in **FIG. 5**. An outer thin-walled sheath **190** may be  
19           pulled over the proximal end of the stent. As a result, the proximal end of the stent **10**  
20           may be fixed to the delivery system **100**, and simultaneously the hooks will be covered.  
21           Separate lock mechanisms attached to the proximal ends of the parts of the delivery  
22           system **100** will ensure that the stent **10** remains in the extended state during delivery.  
23           Separate lock mechanisms may also be used to secure the nitinol wires **130** and prevent  
24           the premature release of the stent **10**.

25           As shown in **FIG. 2**, a push-button lock/release switch mechanism **90** (such as a  
26           FloSwitch®HP device from Meditech/Boston Scientific Corp., Watertown, MA or a  
27           CRICKETT device from Microvena in White Bear Lake, MN) may be used to secure tube  
28           **140** to tube **170** when necessary. When switch **91** of push-button lock/release switch

1 mechanism 90 is in an open or unlocked position, the two tubings are unlocked and as a  
2 result tube 170 moves freely on tube 140. This free movement allows for the stent to take  
3 on its unconstrained shape and size. When switch 91 of push-button lock/release switch  
4 mechanism 90 is in a closed or locked position, the two tubings are locked, the two tubes  
5 cannot move relative to each other, and the stent may be maintained in a completely  
6 stretched state. Tube 170 may be provided with a hub or flange for facilitating the  
7 attachment of push-button lock/release switch mechanism 90 thereto.

8 As shown in FIG. 2, an end fitting 92 with a side-arm 93 may be attached to tube  
9 140 using a Luer lock mechanism. The attachment between tube 140 and end fitting 92  
10 may be facilitated by providing tube 140 with a hub or flange (not shown). End fitting 92  
11 may be equipped with two tightening screw mechanisms 94, one for the two steerable  
12 guidewires 95 (only one of which is shown), and the other for the securing nitinol wires  
13 130 (although one securing wire is illustrated, it is to be understood that more than one  
14 may be used in this exemplary embodiment). These tightening screws may be used to  
15 secure the guidewires and the nitinol securing wires in position during the stent delivery.  
16 The proximal ends of the securing nitinol wires 130 may be held together with a "handle"  
17 piece 97, facilitating their simultaneous movement during stent deployment. End fitting  
18 92 may be equipped with separated lumens in a double channel system. The guidewire(s)  
19 may be placed in one lumen, and the securing wire(s) may be placed in another lumen.

20 With regard to the securing wires described herein, which may be used to secure  
21 the present stents to the delivery systems described herein, it will be understood to those  
22 of skill in the art, having the benefit of this disclosure, that the securing wires may be  
23 controlled by creating openings in whatever tube the securing wires are positioned within  
24 (the holes generally being made near the proximal end of the relevant tube) and threading  
25 the proximal ends of the securing wires through those holes. In this way, the relevant  
26 portion of the stent being delivered may be released by pulling the proximal ends of  
27 securing wires, which are positioned exterior of the relevant tube.

1           At the first stage of deployment, the delivery system **100** may be inserted through  
2 a tracheal tube. Both legs **110** of the delivery system **100** may be advanced in the main  
3 bronchi so that the junction of the legs **110** can be caught by the carina of the trachea.  
4 Holding the delivery system **100** in this position, the proximal portion of the common  
5 body **20** may be released. To do so, the outer thin-walled sheath **190** may be withdrawn  
6 to expose hooks **180**. Tube **170** with hooks **180** may be moved distally to unhook the  
7 stent. Tube **170** with hooks **180** may then be moved further distally so that hooks **180**  
8 will be covered by segment **160** attached to the Y-piece. The wires **130** of each leg may  
9 be pulled back one after the other, and legs **30** of the stent will be released.

10           The stent may be released by starting the deployment with the release of the legs.  
11 The method of deployment which releases the common body of the stent first may be  
12 preferred to a first-legs-release, because the released common body can secure itself  
13 above the carina, and thereby significantly decrease the chance of deploying the stent  
14 higher than optimal within the trachea. No matter which order of release is used, after  
15 hiding the proximal hook mechanism in the thin-walled sheath piece **160**, the delivery  
16 system can be easily withdrawn and removed.

#### 17   **b.     Second Embodiment**

18           In an alternate embodiment shown in **FIG. 4**, the proximal portion of the delivery  
19 system does not use the inverse hook mechanism. Instead, the proximal end of the stent  
20 may be secured to tube **170** with a tight nitinol loop as above described, similar to that  
21 used for securing the distal ends of the stent legs to tubes **110**. To achieve an even  
22 arrangement of the stent's twisted wires around the tube, multiple tapered nitinol wires  
23 **130** (having tapered segment **a**) may be threaded through multiple pairs of holes arranged  
24 substantially evenly around the circumference of the tube, as shown in **FIG. 4**. In this and  
25 all exemplary embodiments utilizing securing wires, the ends of the securing wires may  
26 be tapered, making it possible to avoid a crowded arrangement of the coupled wire ends  
27 on tube **170**.

1           In general, the strength of the small profile nitinol loops depends primarily on the  
2 size of the wire used. But the size and shape of the holes, as well as the relationship of  
3 the corresponding holes (that is, whether they are arranged parallel to the longitudinal  
4 axis of the tubing or run obliquely) may have an impact on the strength of the securing  
5 loops.

6           The tracheo-bronchial type versions of the delivery system described above may  
7 also be used for an SVC bifurcated stent placement from a femoral vein approach, or for  
8 an IVC bifurcated stent placement from a jugular approach.

#### 9       **B.     Aorto-Iliac Application**

10           As shown in **FIG. 6**, the delivery system **200** of this alternate embodiment may  
11 comprise two straight tubes **210** and **220** (which may be Teflon or any other material  
12 described above, and may be preferably D-shaped, although round shapes may be used) of  
13 different lengths. The shorter tube **210** is flexibly connected to the longer tube **220** (in  
14 some applications, the connection may be at about the mid-point of tube **220**), thereby  
15 creating a joint. At the point of connection, a notch may be cut on the longer tube **220**  
16 facing toward the shorter tube **210**. Notch **215** may facilitate movement of the shorter  
17 tube **210** at the joint, and with the two tubes in a side-to-side arrangement forming a  
18 slightly elliptical cross-section, the size of the delivery system may be minimized.

19           The flexible connection between the two tubes may use, in an exemplary  
20 embodiment, a wire **230**, as shown in **FIG. 5**, such as a 0.011"-0.015" wire made of  
21 nitinol (commercially available from Shape Memory Applications) or any pseudoelastic  
22 or superelastic material. The wire **230** may be fed through two holes positioned on the  
23 shorter tube **210** close to its proximal tip. The wire **230** may form a low profile, tight  
24 loop **235** (like the loops described above) between the holes and may be used to secure  
25 the proximal end of the contralateral or left leg **30** of the Y-shape stent in the manner  
26 described above. The wire **230** may then be placed within the lumen of the shorter  
27 tubing. At the site of the attachment, the wire **230** may be contiguously led through a  
28 hole in the longer tube **220** to the lumen of the longer tube **220**. The wire **230** may be led

1 almost to the distal end of this tubing. Another low profile, tight loop **235** may be formed  
2 from the wire **230** at any suitable location along the longer tube **220**, in order to  
3 strengthen the connection between the two tubes. In this regard, low profile loop **235** is  
4 shown about mid-way between notch **215** and distal end **222**, but it will be understood  
5 that the loop may also be located close to distal end **222**.

6 A small-profile, tight securing loop **225** (like those described above) may be  
7 created using wire **240** (which may be made of nitinol (Shape Memory Applications) or  
8 other suitable materials described above) close to the distal end **222** of the longer tube  
9 **220**. This loop may be used to secure the common body **20** (stent crown) of the Y-shape  
10 stent **10** to tube **220** in the manner above described. Within the same lumen, another wire  
11 **270** (which may be made of nitinol (Shape Memory Applications or other suitable  
12 materials described above) may be placed, which may form another small-profile, tight  
13 loop **275** near the proximal end of the longer tube **220**. This loop may be used for  
14 securing the ipsilateral or right leg of the stent.

15 To facilitate the positioning of the contralateral leg **30**, a monofilament **250** which  
16 may be a 3.0-4.0 (metric 1.5-2.0) and made of, for example, 2-0, 3-0, or 4-0 Prolene  
17 (commercially available from Ethicon) or nylon, may be attached to the proximal end of  
18 the contralateral leg of the Y-shape stent. This monofilament may be connected firmly to  
19 the proximal portion of wire **230** that secures the contralateral leg of the stent.

20 In operation, both femoral arteries may be punctured and adequately-sized  
21 introducer sheaths inserted in each. From the left femoral approach, a first nitinol snare  
22 *e.g.*, an Amplatz Gooseneck snare (commercially available from Microvena), may be  
23 inserted and manipulated into the right iliac artery. From the right femoral approach, a  
24 second nitinol snare similar to the first (*e.g.*, Amplatz Gooseneck from Microvena) may  
25 be inserted by which the first nitinol snare may be pulled through the right femoral  
26 sheath. While the stent **10** remains still outside the body, monofilament **250** and wire  
27 **230**, both of which are attached to the contralateral leg of the stent **10**, may then be pulled  
28 through the left femoral sheath by the first nitinol snare.

1           The delivery system **200** may then be inserted through the right femoral sheath  
2   and positioned in the abdominal aorta so that the contralateral leg **30** of the stent **10** can  
3   be above the aorto-iliac bifurcation. Pulling back monofilament **250**/wire **230** together  
4   with the whole delivery system, the contralateral leg **30** of the stent **10** may be positioned  
5   in the left iliac artery.

6           As the first step of deployment, wire **230**, which secures the contralateral leg of  
7   the stent, may be pulled out so that the contralateral leg will be released first. Pulling on  
8   the monofilament **250**, tube **210** may be removed through the left femoral artery sheath.  
9   The ipsilateral leg **30** of the stent **10** may be released by withdrawing the third wire **270**.  
10   In the next step of delivery, the common body **20** of the stent may be released after  
11   pulling nitinol wire **240** out. In the final step, the longer tubing of the delivery system  
12   **200** may also be withdrawn and removed through the right femoral sheath. It is to be  
13   understood that the order of release of the legs and common body of stent **10** may differ  
14   from that just described.

15           In an exemplary embodiment of delivery system **200** according to the present  
16   invention, multiple securing wires may be used to form small profile loops instead of only  
17   one for each leg and the common body of the stent (*i.e.*, **240**, **230** and **270**). In such an  
18   embodiment, the wires may be formed with tapered ends so as to reduce the possibility of  
19   a crowded arrangement of securing wires and closed structures. It is also to be  
20   understood that in an exemplary embodiment of delivery system **200** according to the  
21   present invention, a single securing wire such as **240**, **230** or **270** may be threaded back-  
22   and-forth through multiple pairs of holes so as to form multiple small profile loops for  
23   securing more than one closed structure of a given portion of the stent. In such an  
24   embodiment, the wire may be tapered for the same reason earlier given. It is to be  
25   understood that any combination of the two embodiments above may be utilized. Thus, 2  
26   or more securing wires (which may be tapered) may each be threaded back-and-forth  
27   through multiple pairs of holes, while one securing wire may be threaded through only  
28   one pair of holes, *etc.*

1           The aorto-iliac type of delivery, which may use two access sites, may be used for  
2 placement of bifurcated stents in the biliary system or in hemodialysis grafts.

3           The present invention thus permits an advantage anywhere there is a bifurcated  
4 anatomical structure. This invention comprises a coherent element that can maintain all  
5 three lumens forming the Y-shape. A stent according to the present invention formed  
6 from one contiguous main body and two legs may eliminate all possible problems  
7 associated with Y-shaped stentings using separate stents. Separate stents need to be  
8 positioned in close apposition to each other to form the best possible seal and prevent  
9 tumor invasion (provided a covered stent is used) (Peterson, 1995). If any T, Y or V  
10 shape configurations are achieved with separate stents, the angled portion of the tubular  
11 structure remains the weakest.

12           Stents which are commonly used for the creation of a complex configuration  
13 (such as the WALLSTENT and the Gianturco Z-stent) show lower than expected  
14 expansile force when they are arranged side-by-side. According to the inventors' *in vitro*  
15 measurements, the expansile force of two WALLSTENTS and two Z-stent, respectively,  
16 positioned side-by-side were lower than those measured at the center of a same-size  
17 single WALLSTENT and a Z-stent, respectively (Tables 2 and 1). The stent according to  
18 the present invention showed the most expansile force, even at the level of the bifurcation  
19 (Table 3). In asymmetrical side-by-side arrangement of two WALLSTENTS, the  
20 behavior of the free ends of the partially compressed stent poses an additional concern  
21 considering the damage free ends may do.

22           Except for isolated tracheal and/or bronchial lesions, self-expanding metal stents  
23 have not been used to maintain the lumen of the bifurcations. Apart from stent-grafts,  
24 which are widely used for treatment of abdominal aortic aneurysms, only the Dynamic  
25 tracheo-bronchial stent has been made as a bifurcated stent (Freitag, 1994).

26           In selecting the proper size of the bifurcated stent, one should take into account  
27 the different diameters of the vessel at both the proximal and the distal ends of the stent.  
28 Ideally, the best possible matching between the diameters of the vessel and the stent



1 would result in a wedge-effect. This wedge effect may be utilized to fix the stent within  
2 the vessel, preventing distal migration and possibly reducing intimal hyperplasia induced  
3 by a pressure that is higher than ideal. In a comparative experimental study, it turned out  
4 that of the Palmaz stents, WALLSTENTS and the Memotherm nitinol stents, none  
5 appeared to be preferable to the others regarding neointimal formation in the short- to  
6 mid-term follow-up period (Schurmann, 1996). At this time, the advantage of using a  
7 flexible vs. a rigid stent, or whether a balloon-assisted deployment is more advantageous  
8 over a self-expanding delivery mechanism with regard to preventing the production of  
9 intimal hyperplasia has not been established. As for a nitinol bifurcated stent, a possible  
10 flared proximal end of the stent may further improve the fixation of the stent if it is  
11 necessary.

12 The following general description may further provide one with guidance in  
13 selecting an appropriately sized stent. The stent may be inserted into the body in a  
14 completely elongated state. When the stent is allowed to assume its unconstrained size  
15 and shape, it may be significantly shortened. As the stent is first shortened, a small  
16 decrease in length may result in a relatively large increase in stent diameter. As the stent  
17 approaches its completely unconstrained state, however, this relationship is less  
18 pronounced, and a proportionate decrease in length may result in a much smaller increase  
19 in diameter. As a result, if a stent leg or common body with a diameter of 12 mm is  
20 deployed in a vessel with a diameter of 10 mm, that leg or common body may remain  
21 significantly elongated. This characteristic, though, may be advantageous if the tissue of  
22 the vessel is flexible. Data gained with other stents (*e.g.*, Z-stent) have shown that the  
23 wall of a tubular structure (vessel, biliary tree, *etc.*) is readily, gradually, and quickly  
24 dilated and the stent is able to assume its unconstrained size within hours to days.

25 In the inventors' tracheobronchial study, described in the Example below, the  
26 inventors observed that both the stent legs and the common body changed in diameter and  
27 length even two weeks after stent placement.

28 The present invention may also be used in the treatment of aneurysms. The  
29 successful treatment of an aortic aneurysm "either abdominal (AAA) or thoracic (TAA)]

1 depends on completely excluding it from the circulation. Therefore, incompletely fixing  
2 a stent-graft may result in persistent flow within the aneurysm sac. These perigraft leaks,  
3 also called endoleaks, can occur because of incomplete fixation at the proximal and distal  
4 ends. Endoleaks complicate between 8-44% of endovascular AAA repairs. There is  
5 experimental and clinical evidence that endoleaks can cause aneurysm rupture (Bakal,  
6 1998).

## 7 **Abdominal Aortic Aneurysm Treatment**

8 Short infrarenal necks (< 2 cm) may increase the risk of a proximal endoleak. In  
9 these cases, deploying the proximal fixation stent, typically a Z-stent, of an endovascular  
10 graft in the juxtarenal rather than in the infrarenal aorta can potentially prevent a proximal  
11 leak. The bare portion of the anchoring stent is placed across the renal arteries, with the  
12 covered portion beginning at the infrarenal level. Serious concern remains that any  
13 proximal dislodgment of the stent-graft (due to endoluminal migration and/or to  
14 shrinkage of the aneurysm) may threaten with occlusion of the renal artery(ies).

15 AAAs with non-short infrarenal necks may also be treated by placement of a  
16 covered bifurcated stent-graft. The covering material should be thin and stretchable  
17 enough to be able to follow the movements of the weave. The possible covering  
18 materials include woven Dacron, non-thrombogenic polyurethane, ultrathin and  
19 somewhat elastic PTFE, polyester (commercially available from Tetko Inc. in Briarcliff  
20 Manor, NY), and any other suitable materials that are biocompatible and may follow the  
21 movement of the weave of the stent. Woven Dacron may be coupled to the stent using  
22 polypropylene monofilament sutures. In one embodiment, it may be coupled to the stent  
23 using 5-0, 6-0, or 7-0 sutures (Ethicon). Ultrathin and somewhat elastic PTFE may be  
24 coupled to the stent in the same manner as the woven Dacron. Nonthrombogenic  
25 polyurethane may be coupled to the stent using glue or heat. In other embodiments,  
26 Teflon or silicon compounds may be coupled to the stent using any suitable means above  
27 described.

1           Using a stent according to the present invention, a covered trifurcated stent may  
2 be created. In this embodiment of the invention, the stent **300** has a common body **310**  
3 and two legs **320** (**FIG. 7**). The common body **310** (or suprarenal trunk) of the stent **300**  
4 will be placed into the lumen of the abdominal aorta, whereas the legs **320** are placed into  
5 the main renal arteries. The third leg **305** (or infrarenal trunk) will also be placed in the  
6 abdominal aorta, but it will be located below (or caudad) of the renal arteries. Although  
7 an appropriate portion of the stent **300** depicted in **FIG. 7** may be covered, this covering  
8 is not shown for the sake of clarity. According to this embodiment, the lumen of the  
9 juxtarenal portion **331** of the aorta **312** together with those of the renal arteries **313** should  
10 be maintained first with the trifurcated stent-graft (**FIG. 8**, again, the graft material is not  
11 shown for the sake of simplicity), then another covered stent-graft (a straight tube graft or  
12 a bifurcated stent-graft) may be positioned into the distal abdominal aorta. The two  
13 stent-grafts should then be anastomized to each other, creating a completely sealed  
14 endograft. To achieve a good contact/connection between the two stent/stent-grafts with  
15 an appropriate seal, the straight tube stent or the common body of the bifurcated stent  
16 may be preferably flared.

17           The potential advantages of this embodiment include: (1) the shortness of the  
18 proximal aortic neck of the aneurysm will not be a limiting factor in selecting patients  
19 suitable for endovascular repair of stent-grafts; (2) the potential hazard from distal  
20 embolization and/or occlusion of the renal arteries can be eliminated; and (3) complete  
21 exclusion of the aneurysmal sac can potentially be achieved because the stent-graft will  
22 be anchored in the intact suprarenal portion of the aorta.

23           The weaving for this embodiment is similar to that which is used to create a  
24 bifurcated stent according to the present invention. To produce the trifurcated version,  
25 the weaving process should be started on three templates as above described. According  
26 to the inventors' studies, a minimum of 4 wires may be used to form the smaller (renal)  
27 legs **320** of the stent. The common trunk **310** of the stent, where all the wires are used for  
28 weaving the stent structure, may be formed with the largest diameter. This portion of the  
29 stent will be placed more cephalad (suprarenally, or, in other words, closer to the head)

1 into the aorta. The weaving may be started on the two legs and the common trunk in  
2 separate stands. As in the case of the bifurcated stent, the templates for the legs may then  
3 be joined with the template of the common trunk as shown in **FIG. 27A**, and the plain  
4 weaving may be continued as above described and shown in **FIG. 27B**. The assembly  
5 may then be heated and cooled as described above, and reshaped and reheated as  
6 described above as needed.

7         The trifurcated stent may be delivered in the following manner. The delivery  
8 system depicted in **FIG. 6** may be modified using the same materials described above to  
9 include a third tube such that both legs and both the lower and upper portions of a  
10 common trunk may be secured to tubes in the manner above described. The stent may  
11 then be so secured. Then, a right femoral artery access may be established by placing an  
12 introducer sheath in it. Two steerable guidewires may then be inserted from a cranial  
13 approach (from an axillary, brachial, or carotid artery) into the aorta. Using a foreign  
14 body retrieval device (preferably a snare), both of them may be pulled through the right  
15 femoral artery access. Each of the guidewires may be pulled through the lumen of the  
16 stent legs still outside the body. The stent may then be inserted and advanced into the  
17 abdominal aorta over a third guidewire placed into the lumen of the delivery system.  
18 From the cranial arterial access, a guidewire may be placed into each renal artery. The  
19 stent's proper orientation may be facilitated by placing markers on the dedicated portion  
20 of the stent. The guidewires should preferably be marked as right and left on their  
21 segments which are outside the body so that one can avoid twisting the stent. Once both  
22 renal wires are in place, the securing nitinol wires used to hold the stent legs to the  
23 common body as well as to the delivery system may be released one by one. In the final  
24 stage of the procedure, the securing wires holding the common body of the stent may  
25 also be released.

## 26     **Thoracic Aorta Aneurysm Treatment**

27         The thoracic aortic aneurysm (TAA) can be treated by less invasive endovascular  
28 strategies for patients considered at high risk for conventional surgery. Using the  
29 stent-grafts currently available for this purpose, the aortic neck proximal and distal to the

1 aneurysm must have a diameter  $\leq 40$  mm and a length  $\geq 15$  mm (Semba, 1998). Shorter  
2 proximal necks cannot be safely treated with a stent-graft because of the potential  
3 occlusion of the left subclavian artery. The positioning of the proximal anchoring stent of  
4 the stent-graft across the left subclavian artery offers a possible alternative to eliminate  
5 this problem. Deployment of another stent into the left subclavian artery to maintain its  
6 lumen is another possibility. Both solutions, however, carry some risk of distal  
7 embolization and arterial occlusion.

8 As shown in **FIGS. 9** and **10**, a bifurcated stent-graft **500** according to the present  
9 invention having a smaller caliber leg **510** for the left subclavian artery and a larger trunk  
10 **520** for the aortic lumen may solve the problem. This stent-graft effectively seals the  
11 lumen of the aneurysm and simultaneously maintains the patency of the subclavian artery.  
12 For the sake of simplicity, the graft materials that may be used to cover all or part of the  
13 stents of stent-grafts **500** are not shown in **FIGS. 9** and **10**. Stent-graft **500** depicted in  
14 **FIGS. 9** and **10** will be understood to have a first leg, leg **510** for example, a second leg,  
15 trunk **520** for example which resides in aorta **312** as illustrated in **FIG. 10**, and a common  
16 body having a portion **511** that is proximate portions of both leg **510** and trunk **520**, and  
17 which is formed from the wires forming both leg **510** and trunk **520**. **FIG. 10** depicts a  
18 delivered stent-graft **500**.

19 Stent graft **500** may be formed using plain weave as described above, and may be  
20 delivered using the **Aorto-Iliac Application** delivery system above. The concept of  
21 maintaining the lumen patency of the larger branches of the aorta adjacent to the  
22 aneurysm with the same stent-graft used to treat the aneurysm itself may be utilized to  
23 solve the most frequent and serious problems currently associated with endografting of  
24 AAA and TAA.

## 25 **Aortic Arch Reconstruction**

26 One or more of the present bifurcated stents may be used for reconstruction of the  
27 aortic arch. If the disease affects both the aorta and one or more large vessels (such as the  
28 brachiocephalic, left carotid or left subclavian artery) the treatment utilized should be

1 designed to maintain the aortic lumen without compromising the blood flow in the side  
2 branches. The underlying pathological condition (such as an aneurysm) may require that  
3 the treatment involve the use of a stent-graft in order to exclude the aneurysmal sac from  
4 the circulation by creating a new lumen. This treatment is depicted in one embodiment in  
5 **FIG. 10**, which shows treatment of the TAA with a bifurcated stent-graft (although the  
6 cover material is not shown) according to the present invention.

7 In other cases involving the stenosis of large arteries (*e.g.*, the subclavian, and the  
8 common carotid arteries) along with that of the aorta, the aortic lumen can be  
9 reconstructed using combinations of uncovered bifurcated stents. **FIGS. 20-22** depict the  
10 aortic arch **313**, the left subclavian artery **314**, the carotid artery **316** and the right  
11 subclavian artery **317**. **FIG. 20** also depicts two bifurcated stents: the first of which,  
12 bifurcated stent **A**, may be delivered using delivery system **200** depicted in **FIG. 6** in the  
13 manner described above. After bifurcated stent **A** is delivered, bifurcated stent **B** (the  
14 second of the two) may be delivered using the same delivery system and in the same way.  
15 As depicted in **FIG. 20**, the two bifurcated stents may be delivered such that **A** overlaps  
16 **B** somewhat. The weave of bifurcated stent **B** is not depicted in **FIG. 20** for the sake of  
17 simplicity of illustration.

18 **FIG. 21** depicts three bifurcated stents, **A**, **B**, and **C**, delivered in the same manner  
19 as the two bifurcated stents depicted in **FIG. 20**, and with the same type of overlap. In  
20 some situations, a combination of a bifurcated stent-graft and a stent-graft that is formed  
21 using the weaving methods disclosed herein, but that is straight, may also be used. Thus,  
22 the doctor is free to utilize any combination of stents to achieve his or her purpose.

23 The extent to which the current bifurcated stents are covered may be varied  
24 according to the treatment method needed. As shown in **FIG. 22**, the portion of trunk  
25 **520** (which occupies the portion of aortic arch **313** downstream of left subclavian artery  
26 **314**, and which is designed to seal aneurysmal sac **318**) is covered, while leg **510**, which  
27 occupies left subclavian artery **314**, and the portion **511** of stent **500**, which is positioned  
28 upstream of left subclavian artery **314** are uncovered.

1           This embodiment may be advantageous when the thoracic aortic aneurysm affects  
2   the segment of the aorta immediately surrounding the orifice of left subclavian artery **314**,  
3   or in other words, when the cephalad neck of the aneurysm is very short. In this situation,  
4   the use of a straight stent-graft (that is, a non-bifurcated stent-graft) is controversial  
5   because the shortness of the cephalad neck of the aneurysm virtually eliminates the  
6   possibility of safely and adequately achieving fixation of the straight stent-graft without  
7   compromising blood flow in left subclavian artery **314**. Using the embodiment of the  
8   present invention depicted in **FIG. 22**, however, uncovered leg **510** is designed to  
9   maintain the patency of left subclavian artery **314** while the covered portion of trunk **520**  
10   should effectively seal aneurysmal sac **318**, thereby preventing endoleak from left  
11   subclavian artery **314**. If left subclavian artery **314** suffers from aneurysmal dilation, a  
12   completely covered bifurcated stent-graft should be used. Either embodiment – partially  
13   or completely covered – may be delivered using delivery system **200** as described above.

#### 14   **Aorta and Bilateral Renal Artery Replacement Using Two Bifurcated Stents** 15   **Positioned Side-By-Side**

16           As shown in **FIG. 40**, two bifurcated stents **10** (stent-grafts, not shown, may also  
17   be used) are used side-by-side in aorta **312**, and renal arteries **313**. In this embodiment,  
18   the bifurcated stents **10** (or bifurcated stent-grafts **500**, not shown) may be secured to two  
19   delivery systems **200** and delivered as described above. They may be released  
20   simultaneously so as not to allow either to expand at the expense of the absence of the  
21   other. In one embodiment, each trunk occupies about 50% of the intraluminal space  
22   available in the aorta.

23           The use of two uncovered bifurcated stents as just described is warranted if the  
24   abdominal aortic aneurysm has a short proximal neck (that is, one that extends only  
25   slightly upstream of the renal arteries) that makes it virtually impossible to use stents  
26   having a graft material that would block renal circulation. Depending on the length of the  
27   aneurysmal neck and/or the possibility of endoleak from the renal arteries, the renal legs  
28   of the bifurcated stent may be covered or uncovered. If the renal circulation would not be

1     compromised by covering the renal legs, the portion of the trunk located upstream of the  
2     renal arteries may be left uncovered.

### 3     **Combined Treatment of Aneurysms Consisting of Stent Placement and** 4     **Transcatheter Embolization**

5             In one embodiment of the present invention, the bifurcated (and in some lesions  
6     even the trifurcated) stent may be used for aneurysm treatment without being equipped  
7     with a graft material. In this embodiment, the “naked” stent may serve as a scaffold for  
8     developing an endothelial layer on the newly formed vessel lumen, while the aneurysmal  
9     sac may be excluded from circulation by transcatheter embolization.

10            Generally, the stent may be delivered into place, and an embolic agent may be  
11     inserted into the surrounding aneurysmal sac as shown in **FIG. 30**, which depicts the  
12     abdominal aorta **650**, the left renal artery **652**, the right renal artery **654**, the left iliac  
13     artery **656**, and the right iliac artery **658**.

14            The stent may be delivered into place as above described. As shown in **FIG. 30**,  
15     once the stent is in the appropriate position, an angiographic catheter **600** (5-French to 7-  
16     French) that is chemically compatible with the embolic agent (not polyurethane when the  
17     embolic agent contains DMSO) may be inserted and advanced into the lumen of the stent.  
18     In advancing the angiographic catheter into the lumen of the stent, one may use the same  
19     guidewire which may have been used in delivering the stent. However, one may advance  
20     the angiographic catheter without the use of a guidewire. An adequately sized  
21     microcatheter **610** (2-French to 4-French) that is chemically compatible with the embolic  
22     agent may then be advanced through the angiographic catheter, on an appropriately-sized  
23     guidewire (0.014-inches to 0.025-inches). The tip of the microcatheter may then be led  
24     through the weave of the stent into the aneurysmal sac **620**. If the openings in the weave  
25     of the stent are approximately 2.0 to 2.5 mm, **600** may also be advanced into the  
26     aneurysmal sac. An embolic agent **630** may then be inserted into the aneurysmal sac  
27     through the microcatheter. Embolic agent **630** may be chosen so as to be: non-toxic, non-  
28     irritant/reactive to the tissues; easily handled; suitable for continuous injection;



1 adequately radiopaque; capable of filling the space contiguously without leaving  
2 unoccupied spaces; and non-fragmented, thereby not getting back through the stent's  
3 weave into the newly formed lumen which could result in peripheral embolization.

4 Although several fluid embolic materials (alcohol, poly-vinyl alcohol,  
5 cyanoacrylates, Ethibloc *etc.*.) are available for transcatheter vessel occlusion, none of  
6 them is considered ideal or even suitable for this purpose. Recently, a nonadhesive,  
7 liquid embolic agent, ethylene vinyl alcohol copolymer (EVAL), has been used clinically  
8 for treatment of cerebral AVMs in Japan (Taki, AJNR 1990; Terada, J Neurosurg 1991).  
9 The co-polymer was used with metrizamide to make the mixture radiopaque and may  
10 serve as the embolic agent for the present invention.

11 Very recently, a new embolic agent (similar to EVAL), EMBOLYX E (ethylene  
12 vinyl alcohol copolymer) (MicroTherapeutics Inc., San Clemente, California) was  
13 developed, which was designed for aneurysm treatment (Murayama, Neurosurgery 1998),  
14 and may be utilized as an embolic agent in one embodiment of the present invention.  
15 The embolic agent is composed of a random mixture of two subunits, ethylene  
16 (hydrophobic) and vinyl alcohol (hydrophilic). Micronized tantalum powder is added to  
17 it to obtain an appropriate radiopacity, and DMSO (di-methyl sulfoxide) is used as an  
18 organic solvent. When the polymer contacts aqueous media, such as blood, the solvent  
19 should rapidly diffuse away from the mixture causing in situ precipitation and  
20 solidification of the polymer, with formation of a spongy embolus and without adhesion  
21 to the vascular wall. Any kind of material with characteristics similar to those of  
22 EMBOLYX E may be used as an embolic agent for the present invention.

23 Both abdominal and thoracic abdominal aneurysms may be treated as above  
24 described. In some other locations (*e.g.*, external iliac artery), pseudoaneurysm and/or  
25 tumor-induced corrosive hemorrhage may also be treated as above described.

26 The size of the delivery system that may be used to deliver a bifurcated stent  
27 without a graft cover may be sufficiently small, such that insertion of the stent into the  
28 vessel may take place following a percutaneous insertion. The delivery system would

1 also be well-suited to negotiating through tortuous vascular anatomy. The treatment  
2 described above may be performed using interventional radiology techniques, thereby  
3 eliminating the need for surgery. The embolization may occlude the lumbar arteries from  
4 which the excluded aneurysmal sac is frequently refilled. As a result of using the  
5 treatment described above, the leak from the patent lumbar arteries may be eliminated.

6 The following examples are included to demonstrate illustrative embodiments of  
7 the invention. It should be appreciated by those of skill in the art that the techniques  
8 disclosed in the examples which follow represent techniques discovered by the inventors  
9 to function in the practice of the invention, and thus can be considered to constitute  
10 illustrative modes for its practice. However, those of skill in the art should, in light of the  
11 present disclosure, appreciate that many changes can be made in the specific  
12 embodiments which are disclosed and still obtain a like or similar result without  
13 departing from the spirit and scope of the invention.

## 14 **EXAMPLE 1**

### 15 **Materials and Methods**

16 Below, the inventors present the results of an *in vitro* study designed to establish  
17 the characteristics (*i.e.* expansile or radial force and flexibility) of the inventors' new  
18 bifurcated stent design and compare these characteristics to those of the Gianturco-Rösch  
19 biliary Z-stent and the WALLSTENT. In addition, the inventors also present the  
20 inventors' preliminary results with the tracheobronchial application of the new stent in  
21 the pig.

22 As discussed above, the self-expandable bifurcated stent according to the present  
23 invention has a Y-shape (Y-stent) comprising a common main body and two legs that are  
24 made as one coherent element.

25 The stents used for this study were made by hand weave. A wooden stand with a  
26 circular plate was used for weaving the stents. One of the ends of the tubular copper  
27 template was equipped with multiple holes around its circumference. The midportion of

1 each wire was hanged on metal pins placed through these holes and secured to the  
2 template with some copper wire. A 100 gram weight was attached to each free end of the  
3 nitinol wires. The template with the attached wires was then placed through the wide  
4 central hole of the circular plate of the stand in an up-side-down position. In this  
5 arrangement, the end of the template with the holes made for wire attachment faced  
6 down. A central weight (approx. 600 g) was hanged on this end of the template, and the  
7 nitinol wires with the 100 gram weights were led over the flat surface of the circular  
8 plate.

9 The wire ends were evenly arranged around the circumference of the circular  
10 plate. The 100 gram weights and the central weight kept the wires under tension and in  
11 balance. The weave started with two wire ends. One of the wire ends (*e.g.*, the left one)  
12 was crossed over the right one. In clockwise direction, the left wire end was crossed  
13 similarly over the corresponding right one. This move was continued until the circle was  
14 finished. The direction of the move was then reversed, and the wire crossings were done  
15 counterclockwise. The tightness of the weave (*i.e.* the angle between the wires) was  
16 adjusted by changing the central weight. An increase in the central weight resulted in a  
17 looser weave (decreased angle between the wires) and vice versa.

18 After the plain weave of nitinol wires was completed on the metallic template, the  
19 stent/template unit was heated to 500° C for 12-15 min. After cooling to room  
20 temperature, the stent wires possessed superelastic properties.

21 For this *in vitro* study, Y-stents according to the present invention were made  
22 using 12 0.005-inch nitinol wires (Shape Memory Applications, Santa Clara, CA). The  
23 outer diameter of the common body and the legs was 8.5 mm and 5.5 mm, respectively.  
24 The characteristics of the Y-stent were compared to a four-body Gianturco-Rösch biliary  
25 Z-stent® (Cook Inc., Bloomington, IN) and a WALLSTENT (Schneider, Minneapolis,  
26 MN). Each body of the Z-stent was constructed of 0.012-inch stainless steel wire with  
27 6-bends at each end and a 12 mm outer diameter. The WALLSTENT was made of 24  
28 surgical grade stainless steel alloy wires (0.006-inch) and had an unconstrained outer  
29 diameter of 9.5 mm.

1           In addition, straight, cylindrical nitinol stents were fabricated with a uniform outer  
2 diameter of 13 mm to evaluate the effect of varying the number of wires and weave  
3 tightness on expansile force. Stents were constructed from six, eight, and ten 0.011-inch  
4 super-elastic nitinol wires and the tightness of the weave was varied in two stents made of  
5 six wires.

6           The expansile force of the stents was measured using the method described by  
7 Fallone (Fallone *et al.*, 1988). Measurements made by this method are based on the fact  
8 that the final radius to which the stent expands within a tubular structure (*e.g.*, a blood  
9 vessel) depends on the pressure exerted by the wall of the structure on the stent. At  
10 equilibrium, the pressure exerted by the wall on the stent is equivalent to that produced by  
11 the stent on the wall. The response of the stent to external pressure can be measured by  
12 using a non-elastic collar-type device placed around the stent.

13           An apparatus comprising a non-elastic paper strip and a tubular spring gauge with  
14 a capacity of 500 g was fabricated to measure stent expansile force. One end of the  
15 non-elastic paper strip was fixed and the other end was attached to the spring gauge,  
16 forming a circular collar with an adjustable diameter. The stent was placed within the  
17 collar. Pulling on the spring gauge caused uniform pressure to be exerted upon the stent,  
18 thus decreasing the radius of the stent from the original value of  $R_0$  to  $R$ . The change in  
19 radius was expressed as the circumferential displacement measured in mm directly on the  
20 paper strip. The force (measured in grams) needed to cause a 10 mm circumferential  
21 displacement of the stent was used to compare the expansile force of each stent design.

22           The unit "grams" has been used herein as a measure of force. Although the  
23 correct unit of force is the "dyne", which is equal to the mass in grams multiplied by the  
24 gravitational constant, the inventors believe that the average reader will have a better idea  
25 about the size of force when the associated mass unit (grams) is specified.

26           For the Z-stent and WALLSTENT, the relationship between the force exerted by  
27 the collar and the circumferential displacement of the stent was measured at the mid-part  
28 of the stent. Initially, measurements were made on a single stent and then a second

1 identical stent was placed alongside the former one and the measurements were repeated.  
2 This was done to simulate two stents being placed side-by-side to treat a lesion occurring  
3 at a bifurcation. Taking into account the fact that the multiple-body Gianturco-Rösch  
4 biliary stents are the weakest at the point where the bodies are joined by nylon  
5 monofilament suture, measurements were made at the mid-portion of the second body of  
6 these stents. The Y-stent of the present invention was measured at the mid-portion of the  
7 common body and at the bifurcation (junction of legs and common body). Measurements  
8 were obtained 10 times on each stent and the results were averaged.

9 To establish the flexibility of the stents, the luminal diameter at the mid-portion of  
10 the stent was measured while holding the stent at both ends and bending it 180° in the  
11 middle. A transformation ratio was then calculated using the formula:

$$12 \quad \frac{D_0 - D_1}{D_0} \quad 13 \quad \quad \quad 14 \quad \quad \quad 15 \quad \quad \quad 16 \quad \quad \quad 17 \quad \quad \quad 18 \quad \quad \quad 19 \quad \quad \quad 20 \quad \quad \quad 21 \quad \quad \quad 22 \quad \quad \quad 23 \quad \quad \quad 24 \quad \quad \quad 25 \quad \quad \quad 26 \quad \quad \quad 27 \quad \quad \quad$$

13 where D0 is the luminal diameter of the stent before bending and D1 is the luminal  
14 diameter after bending. This test was performed 10 times on each stent and the results  
15 were averaged.

16 For statistical analysis, repeated ANOVA method (flexibility) as well as Student's  
17 t-test and Mann-Whitney U-test (expansile force) were used.

### 18 *Animal Studies*

19 Fourteen of the Y-shape stents of the present invention and the corresponding  
20 delivery systems were tested in the tracheobronchial systems of 9 pigs. First, the  
21 inventors fabricated and used bifurcated stents, the common body of which had a slightly  
22 elliptical cross-section with a larger frontal diameter (18 mm vs. their 15 mm a-p  
23 diameter). The height of the common body was 10-12 mm in these stents, while the legs  
24 were 2.8 - 3.1 cm-long and had a diameter of 9 mm.

25 A bifurcated delivery system was constructed from two 7-F Teflon tubings. A  
26 piece of a 14-F thin-walled Teflon sheath was pulled over the proximal halves of these  
27 tubings to hold them together. After gaining some experiences with the delivery system,

1 the inventors covered the 7-F tubings in a longer segment, leaving free only the distal  
2 15-17 cm of the tubings (which length corresponded with the totally stretched length of  
3 the stents). Four pairs of holes were made close to the end of each 7-F tubing and were  
4 arranged evenly around the circumferences of the tubings. The distance between the  
5 corresponding holes of each pair was about 4-5 mm. Two other pairs of holes were also  
6 made on the same tubing approximately 14-16 cm away from the distal holes. 0.009-inch  
7 superelastic nitinol wires were used to secure the stent's ends to the delivery system.  
8 First, four securing nitinol wires were placed through the lumen of one of the 7-F tubings.  
9 These wires were placed into the lumen through the proximal holes positioned close to  
10 the distal end of these tubings. One of the legs of the bifurcated stent was pulled over the  
11 7-F Teflon tubing and the four prepared superelastic nitinol wires were led through the  
12 stent mesh at its distal end. Actually, the angles made from the mid-portion of the  
13 stent-wires were used to secure the stent to the delivery system.

14 The distal ends of the securing nitinol wires were then threaded through the distal  
15 holes of each hole-pair, forming a low-profile tight nitinol wire loop between the two  
16 corresponding holes of each hole-pair. The tight wire loops held the end of the stent leg  
17 firmly to the tubing. The other leg of the stent was attached to the delivery system in the  
18 same way. The stent crown was secured to the delivery system using the same technique:  
19 altogether 4 other 0.009-inch securing nitinol wires were used (2 per tubing) to create a  
20 steady connection between the proximal part of the stent and the delivery system. The  
21 proximal hole-pairs created on the 7-F tubings were used for this purpose. Altogether 6  
22 securing nitinol wires were placed in the lumen of each 7-F Teflon tubing.

23 The proximal ends of the securing nitinol wires were marked and separated from  
24 each other, forming two bunches of wires within each 7-F tubing: two of them were used  
25 for securing the stent crown, the other four to hold one of the legs of the stent. A  
26 0.018-inch nitinol guidewire with a floppy tip (Microvena Corp.) was placed in the lumen  
27 of each tubing. The guidewires were able to move freely without interfering with the  
28 movement of the securing wires and vice versa.

The stents were deployed through an 8 mm or 8.5 mm diameter tracheal tubing under fluoroscopy. In the first stage of the delivery, the inventors cannulated the main bronchi with the nitinol guide wires. Once the right position of the guidewires was achieved, the legs of the delivery system were advanced over the guide wires until the bifurcation of the stent was caught by the carina. At this point, the stent crown was released by pulling back the two securing nitinol wires in each 7-F tubings. Immediately after that, the stent's legs were released by withdrawal of the 4 securing nitinol wires on each side. The delivery system was then removed from the tracheobronchial system.

## RESULTS

### Part 1: *In vitro* Study

#### *Expansile Force*

The cumulative data from the measurements of the stents' expansile force is summarized below in Tables 1, 2 and 3 below. In each table, the designation  $\Delta$  in the leftmost column of each table represents the circumferential displacement (in mm) of the stent in question. For example, a  $\Delta$  of 2 mm indicates that the circumference of the stent in question was reduced by 2 mm, and the force necessary to effect that displacement was then recorded.

Table 1 – Z-Stent, 6 Bends, Caliber: 12 mm

$\Delta$ (mm)	Body Center	Between Bodies	Side By Side
2	16	13	19
4	36	28	31
6	51	44	42
8	63	61	56
10	81	79	62
12	100	98	76
14	115	119	90
16	127	133	101
18	146	192	122
20	165		142

Table 2 – WALLSTENT 0.006” diameter wire, 24 wires

$\Delta$ (mm)	Center	Overlap	Side by Side
2	15	35	18
4	25	59	22
6	42	80	35
8	50	108	42
10	60	126	48
12	74	149	54
14	84	170	63
16	100	197	73
18	111	220	84
20	129	248	96

Table 3 Y-Stent, 0.005” nitinol wire, 12 wires,  
caliber: trunk - 8 mm, branch - 5mm

$\Delta$ (mm)	Trunk	Junction
2	44	51
4	91	109
6	126	143
8	158	155
10	167	164
12	175	191
14	184	
16	202	

The force (measured in grams) needed to cause a 10 mm circumferential displacement of a single four-body Z-stent was 81 g, and 62 g was required for two four-body Z-stents placed side-by-side ( $p < 0.0001$ ). For the WALLSTENT, 60 g and 48 g were needed, respectively ( $p < 0.0001$ ). The values for the common body and the bifurcation of the Y-stent were 167 g and 164 g, respectively. These results indicate that the expansile force of a nitinol Y-stent constructed according to the present invention from 12 0.005-inch nitinol wires is greater than the force exerted by a 6-bend Z-stent fabricated from 0.012-inch stainless steel wire or a WALLSTENT made of 24 stainless



1 steel alloy wires (0.006-inch). The bifurcated stent exhibited significantly greater  
2 expansile force than the Z-stent or WALLSTENT ( $p<0.0001$ ). The expansile forces  
3 measured at the common body and the bifurcation of the Y-shape stent were almost  
4 identical ( $p<0.0092$ ).

#### 5 *Stent Flexibility*

6 The four-body Gianturco-Rösch biliary Z-stent started to lose its lumen in the  
7 mid-portion of the stent at an angle of  $40^\circ$ . The lumen collapsed completely at  $90-100^\circ$ .  
8 When the WALLSTENT was bent, the luminal diameter increased from 9 mm to an  
9 average diameter of 12.0 mm (range: 11.5 - 13.0 mm) at a bend of  $180^\circ$ . This means the  
10 transformation ratio was 33.3% (range: 27.7% to 44.4%). However, the stent shortened  
11 at the same time the luminal diameter increased. When the common body of the Y-stent  
12 of the present invention was bent  $180^\circ$  in the middle, the luminal diameter decreased  
13 from 8 mm to an average of 7.3 mm (range: 7.5 - 7.0 mm). The transformation ratio for  
14 the Y-stent was 8.75% (6.25 - 12.50%). The stent did not shorten during bending. The  
15 flexibility of the Y-shape stent was superior to both the Z-stent and the WALLSTENT  
16 ( $p<0.0001$ ).

#### 17 **Part 2: Animal Evaluation**

18 The stent placement was technically successful in 9 of 14 cases. Delivery system  
19 failure resulted in premature deployment (2 cases), twisting of stent legs during  
20 deployment (2 cases), and inability to release stent legs (1 case). Five stents migrated  
21 because the unconstrained stent diameter was smaller than the tracheobronchial system.  
22 Three of them were removed one week after stent delivery because of significant  
23 discrepancy between the size of the stent and the tracheobronchial system. Persistent  
24 cough occurred in 3 pigs because the stent legs were longer than the main-stem bronchi  
25 which resulted in distal bronchi placement.

26 Three animals were followed up for 8 wk, one animal for 4 wk after stent  
27 placement. All these stents remained patent, there were no pulmonary lesions related to  
28 the presence of the stents. These animals tolerated the stent well.

## DISCUSSION

Due to the characteristics of nitinol wire, the Y-stent of the present invention can be stretched into low profile and deployed using its superelasticity. Therefore, after inserting the stent at the lesion, the stent should readily recover from its constrained state and a balloon catheter should not be required. The unique contiguous weave of the design makes it possible to achieve virtually complete coverage of a lesion occurring at a bifurcation without gap formation. Therefore, it might be possible to use a single stent according to the present invention to treat this type of lesion, whereas now it requires special techniques and the placement of multiple stents.

In the present *in vitro* study, the Y-stent of the present invention demonstrated greater expansile force than the Z-stent or WALLSTENT. This study showed that two Z-stents or two WALLSTENTS positioned side-by-side exhibit lower radial force than a single stent of each type ( $p < 0.0001$ ). Therefore, the rationale for using Z-stents or WALLSTENTS positioned side-by-side is questionable.

There are many factors that influence the characteristics of a stent made by using a simple weave pattern such as the Y-stent and the WALLSTENT. The size and the number of the wires used to form the mesh, the angle created between the wires, and the shape memory properties of the wire will determine the physical properties of the tubular prosthesis. Therefore, stents of similar luminal diameter that possess completely different expansile force may be produced by altering the size and/or the number of the wires and the tightness of the weave.

Increasing the number of wires or the tightness of the weave can further increase the stent's radial force. It is well known that the angle between the wires of a stent, which is produced by plain weave (e.g., WALLSTENT), should preferably be greater than  $90^\circ$  (Wallsten, 1987). The greater the angle between the wires, the greater the expansile force of the stent. These characteristics, along with the excellent shape memory of nitinol wire make it possible to produce a Y-stent with a high radial force. A Y-stent

1 having high expansile force may help treat rigid strictures, such as those caused by scar  
2 tissue formation or malignant tumors.

3 Stent diameter and wire-angle are also closely related. By increasing the angle  
4 between the wires, the inner diameter of the Y-stent increases, and inversely, by  
5 decreasing the wire-angle, the stent's inner diameter decreases and the stent elongates.  
6 This characteristic may be utilized for production of a wide variety of woven nitinol  
7 stents simply by re-adjusting the wire-angle and then re-heating the nitinol mesh. As a  
8 result, the weave, radial force, diameter, length, and shape of the nitinol stent can be  
9 secondarily modified after completing the primary weaving and heating processes. In the  
10 case of the WALLSTENT, the physical properties are imparted to the stent during the  
11 weaving process, and they cannot be changed later.

12 In addition to exhibiting a greater expansile force, the woven nitinol straight-stent  
13 and Y-stent demonstrated good flexibility. These features may allow these stents to be  
14 deployed in a tortuous curved structure while maintaining their luminal diameter and  
15 preventing the lumen from collapse, which may occur with the Z-stent.

16 The WALLSTENT and Y-stent reacted differently to 180° bending at their  
17 mid-portion. The inner diameter of the WALLSTENT increased, the wire mesh  
18 tightened, and the stent shortened, whereas the inner diameter, wire mesh, and length of  
19 the Y-stent remained virtually unchanged. The different behavior of the two stents can be  
20 in part ascribed to the closed structures of the woven nitinol stent.

21 The closed structures of the Y-stent are also an advantageous feature for stent  
22 delivery. These closed structures, created by bending the stent wires at about their  
23 mid-portions, as well as by using multiple twists or other means to couple the free ends of  
24 the stent-wires, allow for both ends of the stent to be secured to the delivery catheter.  
25 Using a delivery system made of two coaxially placed movable tubes, the stent can be  
26 repositioned even after 100% expansion prior to complete release. In addition, since the  
27 stent has no sharp wire ends, potential tissue laceration and perforation can be avoided.

1           These preliminary *in vitro* and animal studies have shown that the Y-stent woven  
2 with continuous nitinol wires has excellent self-expandable characteristics. This new  
3 stent design may be useful for the treatment of both vascular and non-vascular lesions  
4 occurring at bifurcations of tubular anatomic structures.

5           The good flexibility and high expansile force of the design may promote stenting  
6 tortuous lesions as well as bridging rigid strictures resulting from scarring or malignancy.  
7 The stent of the present invention has been developed for bifurcated and trifurcated  
8 regions and may provide a new approach for solving problems in this area.

9           All of the methods and/or apparatus disclosed and claimed herein can be made  
10 and executed without undue experimentation in light of the present disclosure. While the  
11 compositions and methods of this invention have been described in terms of preferred  
12 embodiments, it will be apparent to those of skill in the art that variations may be applied  
13 to the methods and/or apparatus and in the steps or in the sequence of steps of the method  
14 described herein without departing from the concept, spirit and scope of the invention.  
15 More specifically, it will be apparent that certain elements may be substituted for the  
16 elements described herein while the same or similar results would be achieved. All such  
17 similar substitutes and modifications apparent to those skilled in the art are deemed to be  
18 within the spirit, scope and concept of the invention as defined by the appended claims.

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- 21

1     **WHAT IS CLAIMED IS:**

- 2     1.     A device suitable for implantation into an anatomical structure, comprising:  
3             a first plurality of wires defining a first leg, the first leg having a first distal  
4             portion;  
5             a second plurality of wires defining a second leg, the second leg having a second  
6             distal portion; and  
7             a common body having a distal end and a proximal portion, the common body  
8             being formed from at least the first and second pluralities of wires, the  
9             proximal portion of the common body being adjacent to the distal portions  
10            of both legs, and both ends of at least one wire from one of the pluralities  
11            being located proximate the distal end of the common body.  
12
- 13    2.     The device of claim 1, wherein the wires in the first and second pluralities  
14            comprise nitinol.  
15
- 16    3.     The device of claim 1, wherein the wires in the first and second pluralities  
17            comprise FePt, FePd or FeNiCoTi.  
18
- 19    4.     The device of claim 1, wherein the wires in the first and second pluralities  
20            comprise FeNiC, FeMnSi or FeMnSiCrNi.  
21
- 22    5.     The device of claim 1, wherein the wires in the first and second pluralities each  
23            have a diameter ranging in size from about 0.006 inches to about 0.014 inches.  
24
- 25    6.     The device of claim 1, wherein the first plurality of wires includes at least 6 wires.  
26
- 27    7.     The device of claim 1, wherein both the legs and the common body have tubular  
28            shapes with substantially uniform diameters.  
29
- 30    8.     The device of claim 1, wherein at least one of the legs is hand woven.

- 1
- 2 9. The device of claim 1, wherein at least one of the legs is machine woven.
- 3
- 4 10. The device of claim 1, further comprising a graft material attached to at least the
- 5 common body.
- 6
- 7 11. The device of claim 10, wherein the graft material comprises woven Dacron.
- 8
- 9 12. The device of claim 10, wherein the graft material comprises polyurethane.
- 10
- 11 13. The device of claim 10, wherein the graft material comprises PTFE.
- 12
- 13 14. A stent, comprising:
- 14 a first plurality of flexible tubular strands woven to form a first leg having a first
- 15 distal portion, the flexible tubular strands in the first plurality crossing
- 16 each other to form a first plurality of angles, at least one of the angles
- 17 therein being obtuse;
- 18 a second plurality of flexible tubular strands woven to form a second leg having a
- 19 second distal portion, the flexible tubular strands in the second plurality
- 20 crossing each other to form a second plurality of angles, at least one of the
- 21 angles therein being obtuse; and
- 22 a common body having a common portion, the common body being formed from
- 23 at least the first and second pluralities of flexible tubular strands, the
- 24 common portion of the common body being adjacent to the distal portions
- 25 of the first and second legs.
- 26
- 27 15. The stent of claim 14, wherein the flexible tubular strands in the first and second
- 28 pluralities comprise nitinol.
- 29



1 16. The stent of claim 14, wherein the flexible tubular strands in at least the first  
2 plurality comprise biodegradable filaments.

3  
4 17. A stent, comprising:  
5 a first plurality of wires defining a first leg, the first leg having a first distal  
6 portion;  
7 a second plurality of wires defining a second leg, the second leg having a second  
8 distal portion;  
9 a third plurality of wires defining a third leg, the third leg having a third distal  
10 portion; and  
11 a common body having a proximal portion and a distal end, the common body  
12 being formed from at least the first, second and third pluralities of wires,  
13 the proximal portion of the common body being adjacent to the distal  
14 portions of each of the three legs.

15  
16 18. The stent of claim 17, wherein the wires in each of the pluralities comprise  
17 nitinol.

18  
19 19. The stent of claim 17, wherein the first plurality of wires includes at least 5 wires.

20  
21 20. The stent of claim 17, wherein each of the legs and the common body have  
22 tubular shapes with substantially uniform diameters.

23  
24 21. The stent of claim 17, wherein at least one of the legs is hand woven.

25  
26 22. The stent of claim 17, wherein at least one of the legs is machine woven.

27  
28 23. The stent of claim 17, further comprising a graft material attached to at least the  
29 common body.

1     24.     The stent of claim 23, wherein the graft material comprises woven Dacron.

2  
3     25.     The stent of claim 23, wherein the graft material comprises polyurethane.

4  
5     26.     A stent comprising:

6             a first leg having a first axis and a first end, wherein the first leg comprises a first  
7                 wire having a first segment and a second segment, the segments being  
8                 separated by a bend in the first wire located proximate the first end of the  
9                 first leg, the first segment extending helically in a first direction around the  
10                first axis away from the first end of the first leg, the second segment  
11                extending helically in a second direction around the first axis away from  
12                the first end of the first leg, the first and second segments crossing each  
13                other in a first plurality of locations;

14            a second leg having a second axis and a second end, wherein the second leg  
15               comprises a second wire having a first segment and a second segment, the  
16               segments being separated by a bend in the second wire located proximate  
17               the second end of the second leg, the first segment of the second wire  
18               extending helically in a first direction around the second axis away from  
19               the second end of the second leg, the second segment of the second wire  
20               extending helically in a second direction around the second axis away  
21               from the second end of the second leg, the first and second segments of the  
22               second wire crossing each other in a second plurality of locations; and

23            a common body formed from at least one end of each of the wires.

24  
25     27.     The device of claim 26, wherein the first segment of the first wire is positioned  
26     farther from the first axis than the second segment of the first wire at at least one location  
27     among the first plurality of locations.

1 28. The device of claim 26, wherein the first segment of the first wire is positioned  
2 farther from the first axis than the second segment of the first wire at each location of the  
3 first plurality of locations.

4  
5 29. The device of claim 26, wherein the first and second wires comprise nitinol.

6  
7 30. A method of creating a device suitable for implantation into an anatomical  
8 structure, the device having a first leg, a second leg, and a common body, each leg having  
9 an end and a distal portion, the common body having a proximal portion and a distal end,  
10 the method comprising:

11 bending the wires in a first plurality of wires to create first bent portions in the  
12 wires, the first bent portions being arranged to define the end of the first  
13 leg, each wire in the first plurality having two ends;

14 bending the wires in a second plurality of wires to create second bent portions in  
15 the wires, the second bent portions being arranged to define the end of the  
16 second leg, each wire in the second plurality having two ends;

17 weaving the ends of the wires in the first plurality to create the first leg;

18 weaving the ends of the wires in the second plurality to create the second leg; and

19 weaving the ends of the wires in both pluralities to create the common body and  
20 the device;

21 wherein the proximal portion of the common body is adjacent to the distal  
22 portions of both legs.

23  
24 31. The method of claim 30, wherein the first bent portions are bends.

25  
26 32. The method of claim 30, wherein the first bent portions are loops.

27  
28 33. The method of claim 30, wherein the wires in the first and second pluralities  
29 comprise nitinol.

1     34.     The method of claim 30, wherein the wires in the first and second pluralities each  
2     have a diameter ranging in size from about 0.006 inches to about 0.014 inches.

3  
4     35.     The method of claim 30, wherein the weaving the ends of the wires in the first  
5     plurality is by hand.

6  
7     36.     The method of claim 30, wherein the weaving the ends of the wires in the first  
8     plurality is by machine.

9  
10

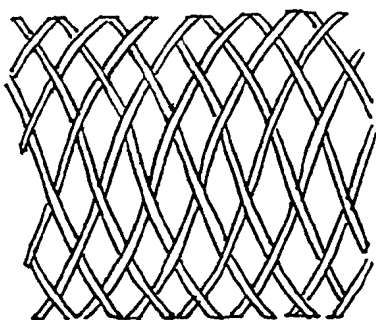


FIG. 1B

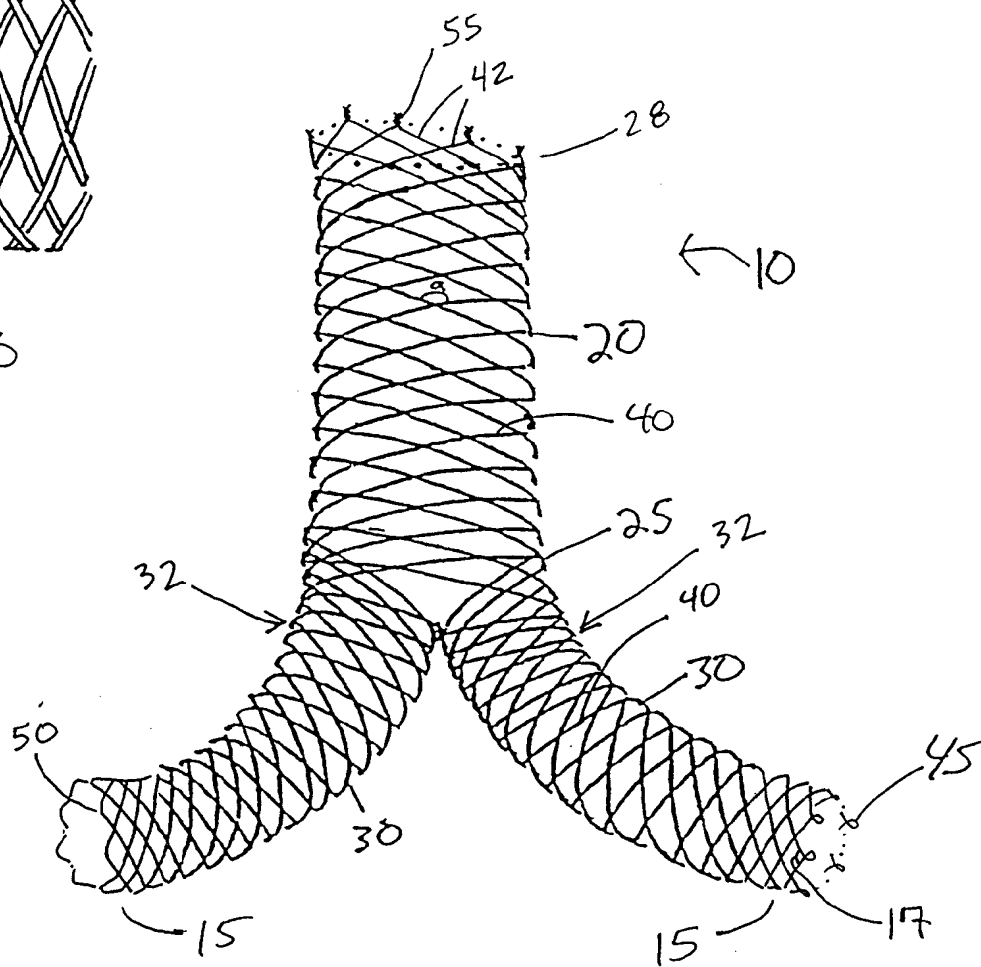


FIG. 1A

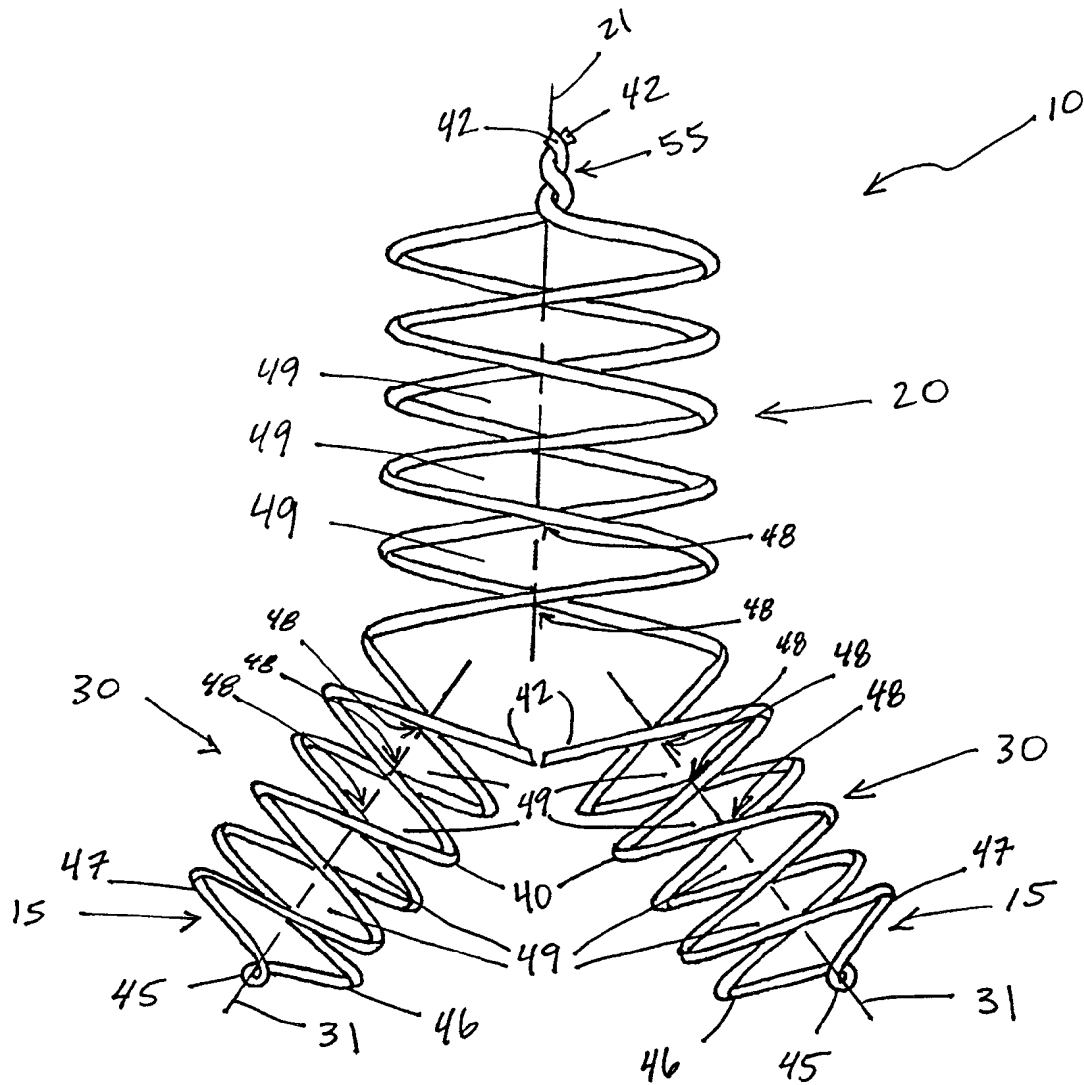
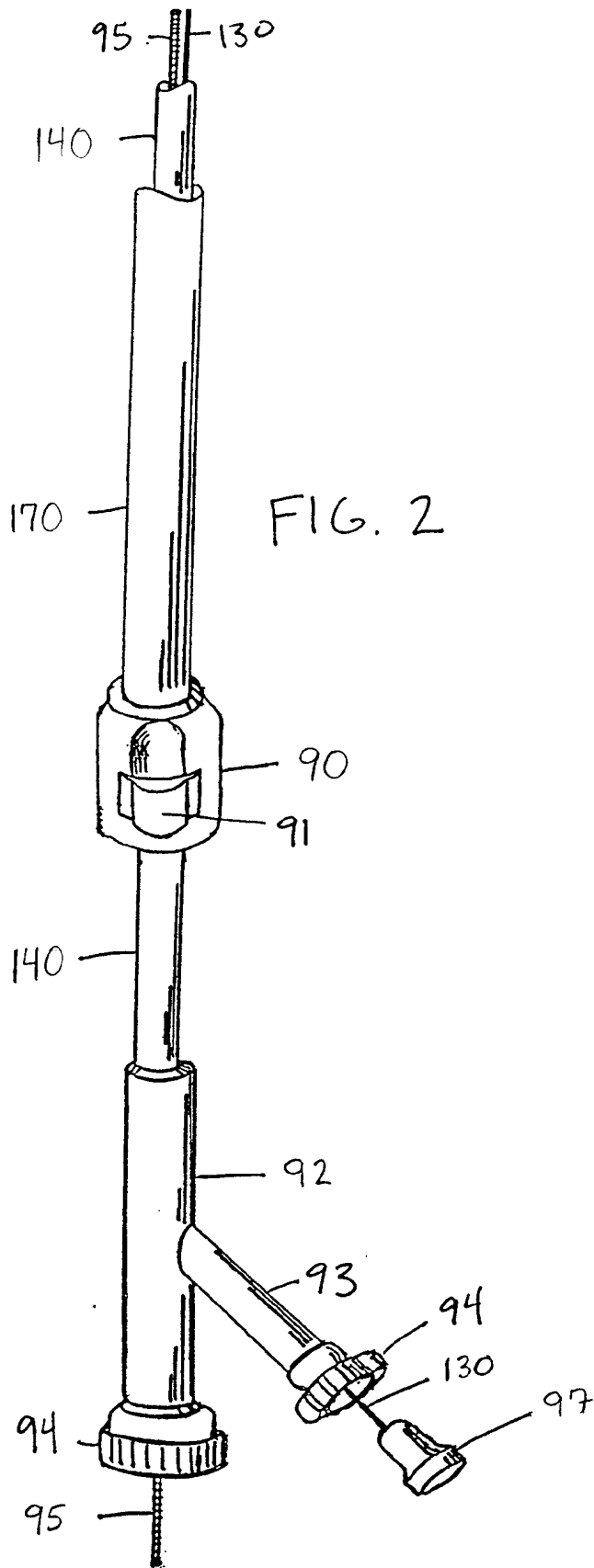
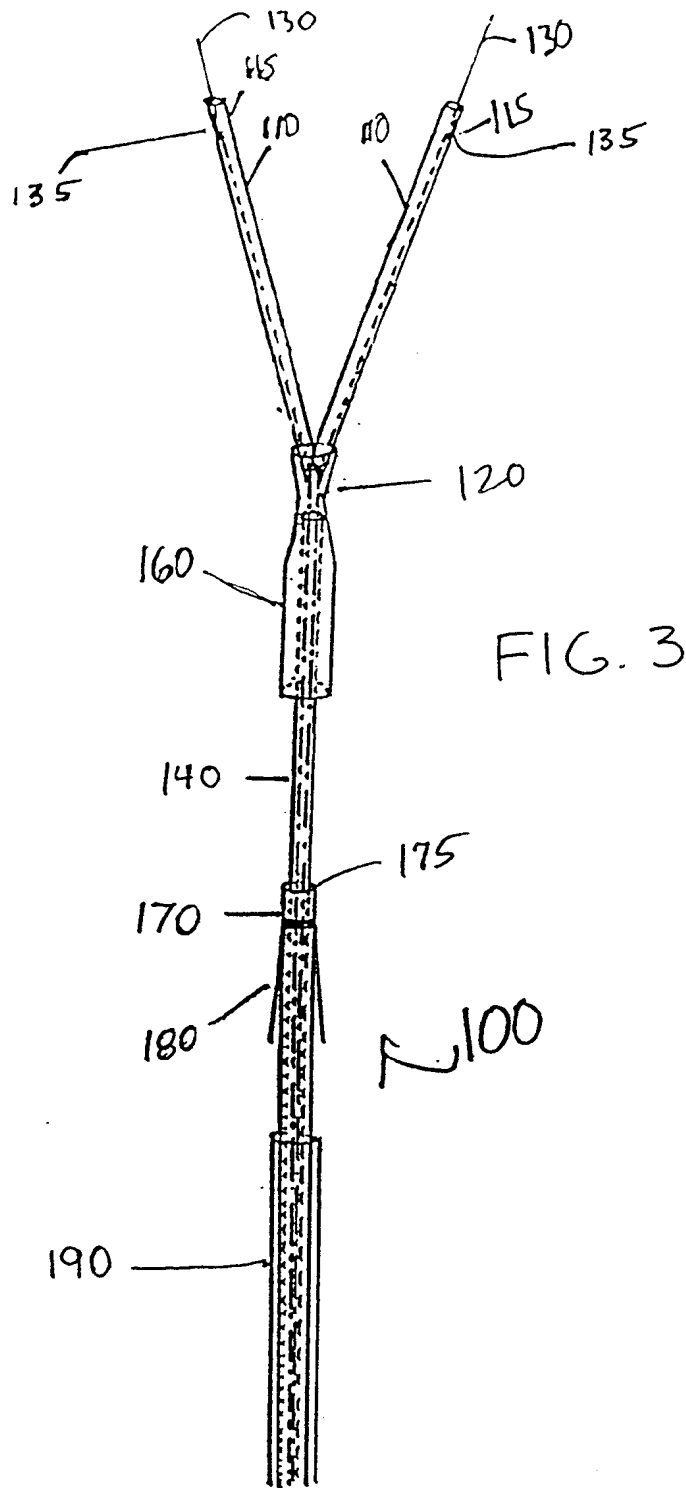


FIG. 1C







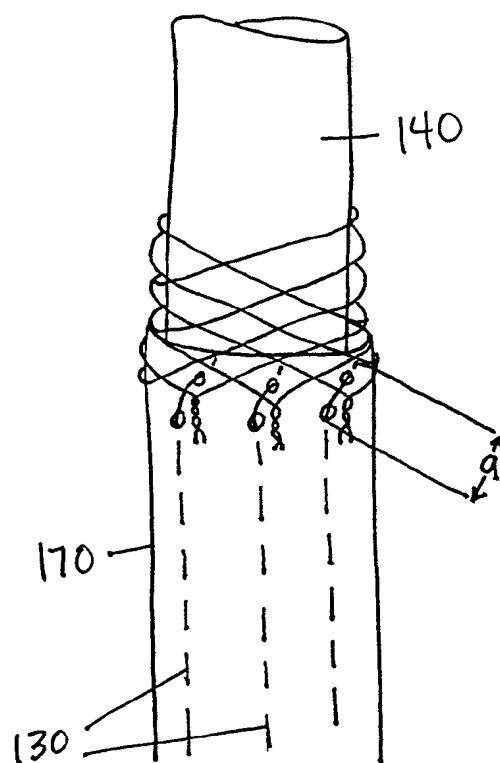
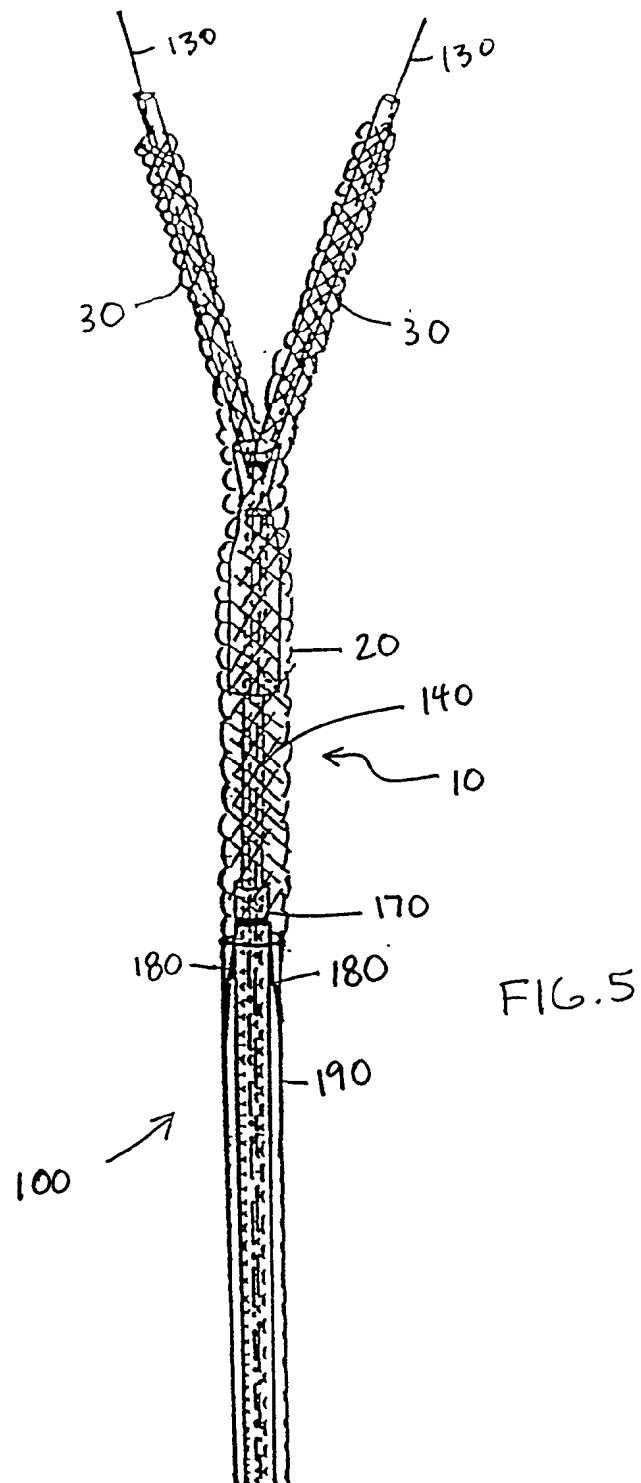
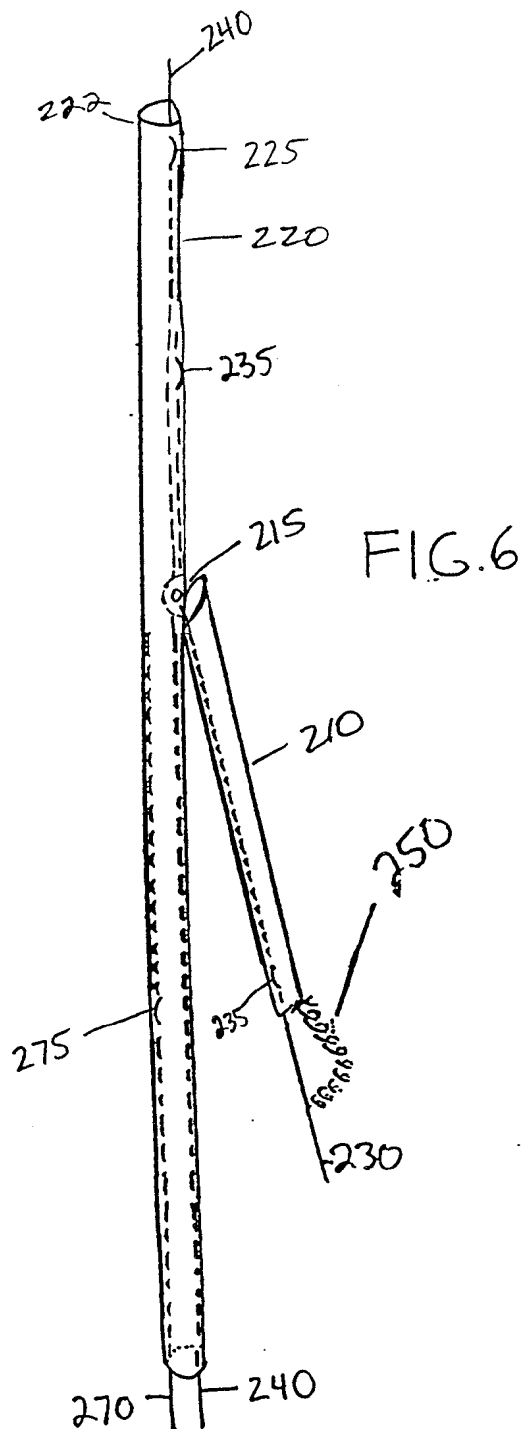


FIG. 4





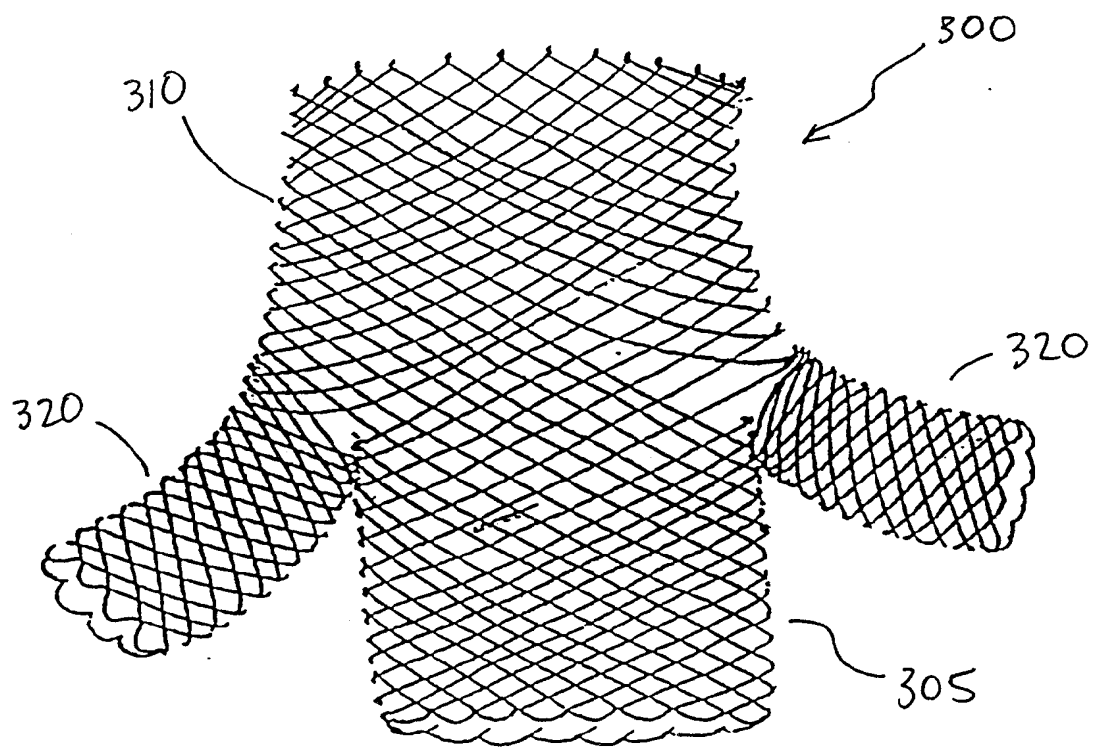


FIG. 7

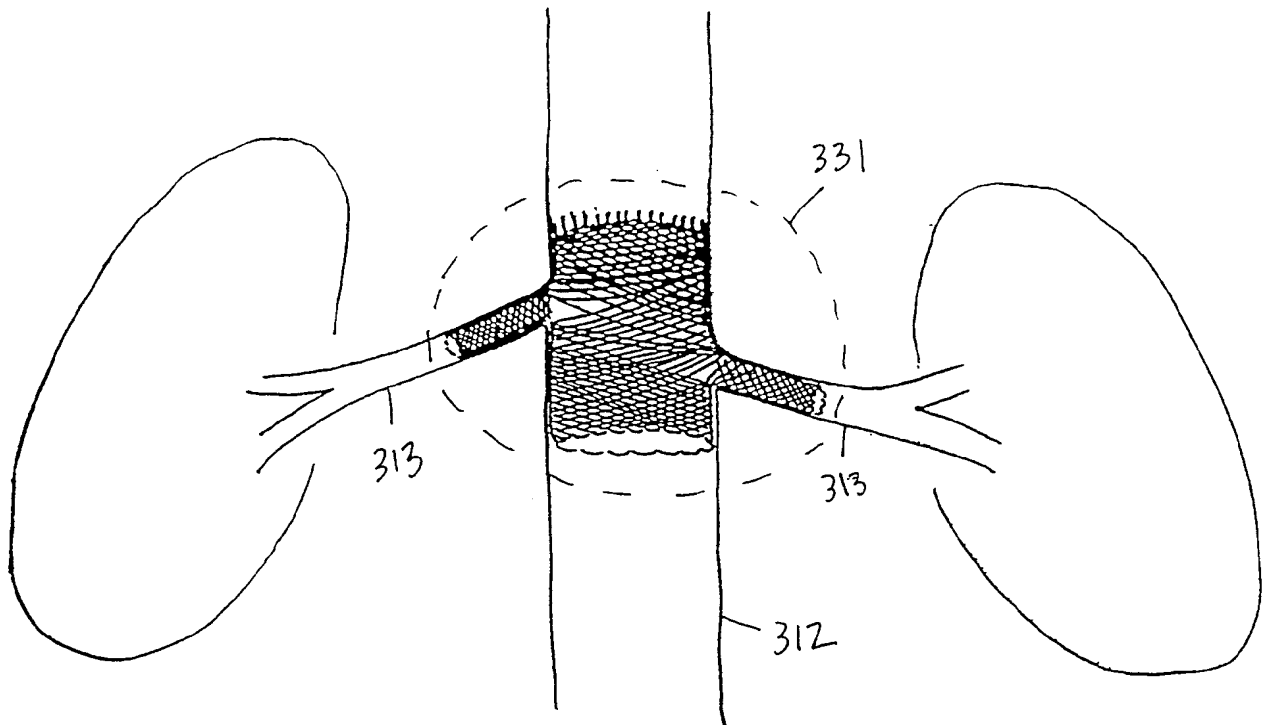


FIG. 8

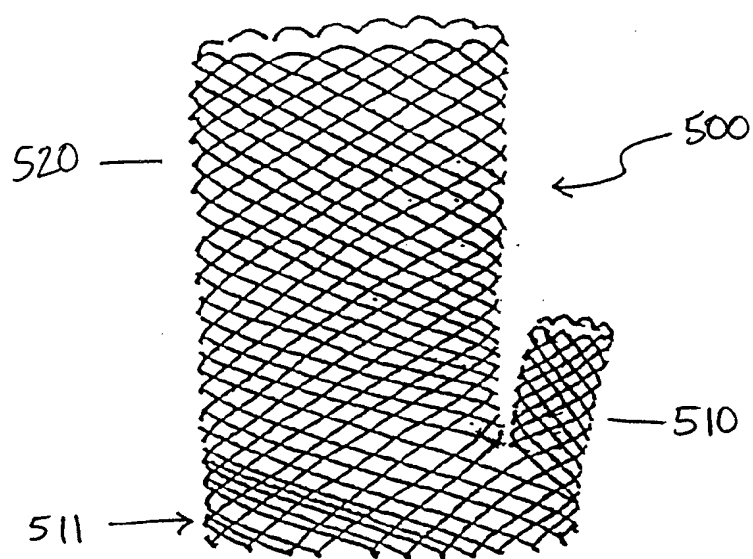
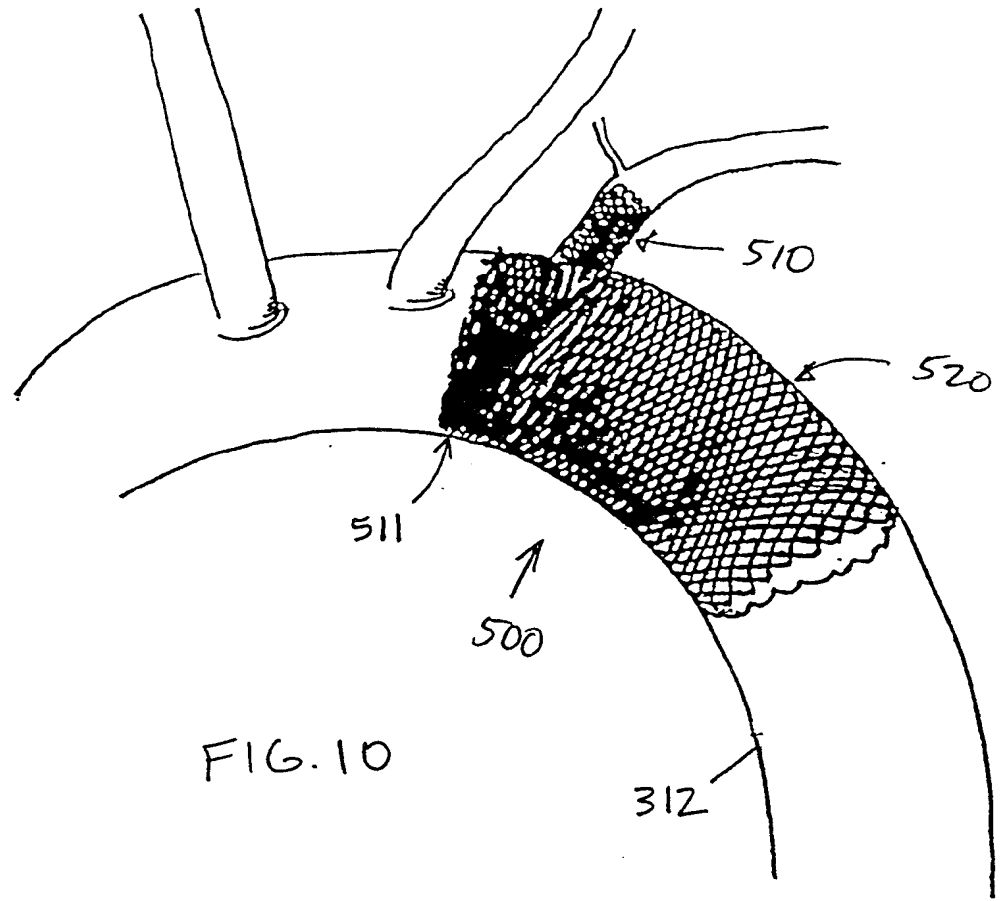


FIG. 9



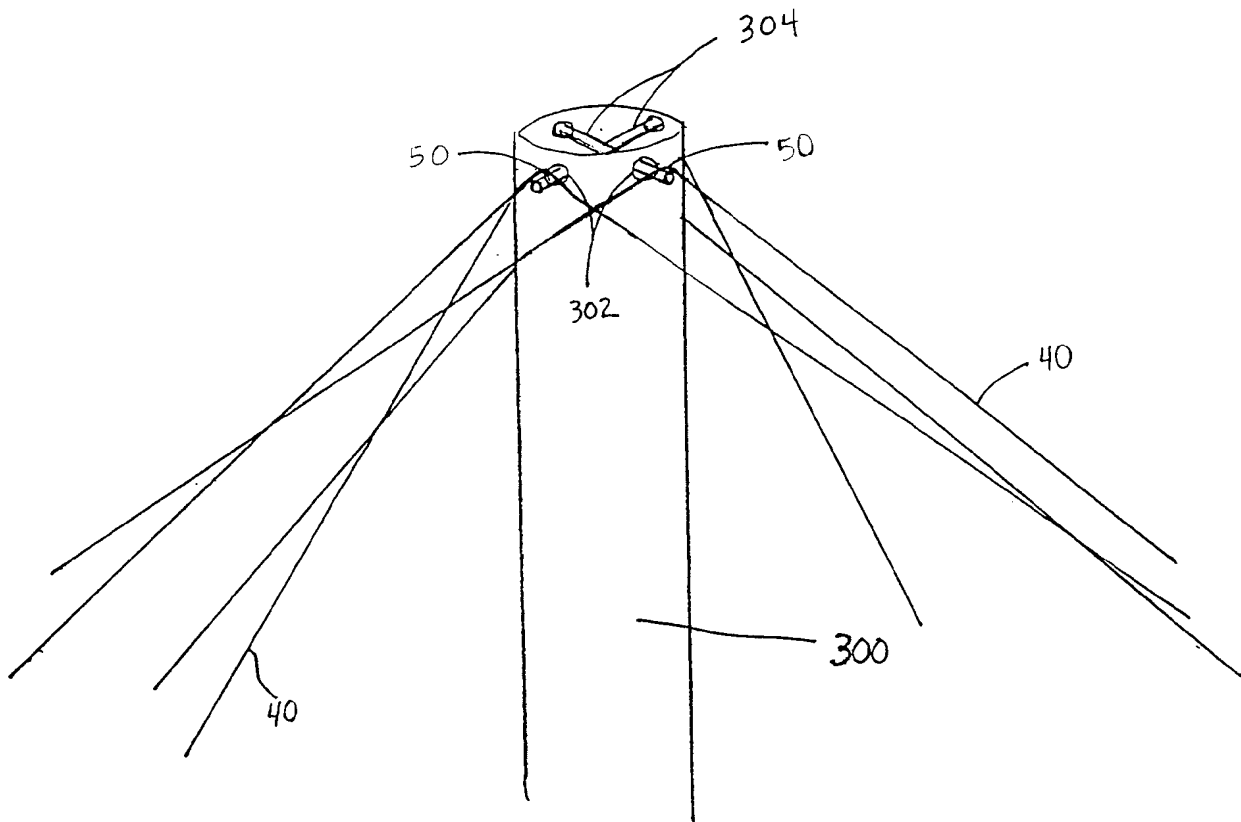


FIG. 11



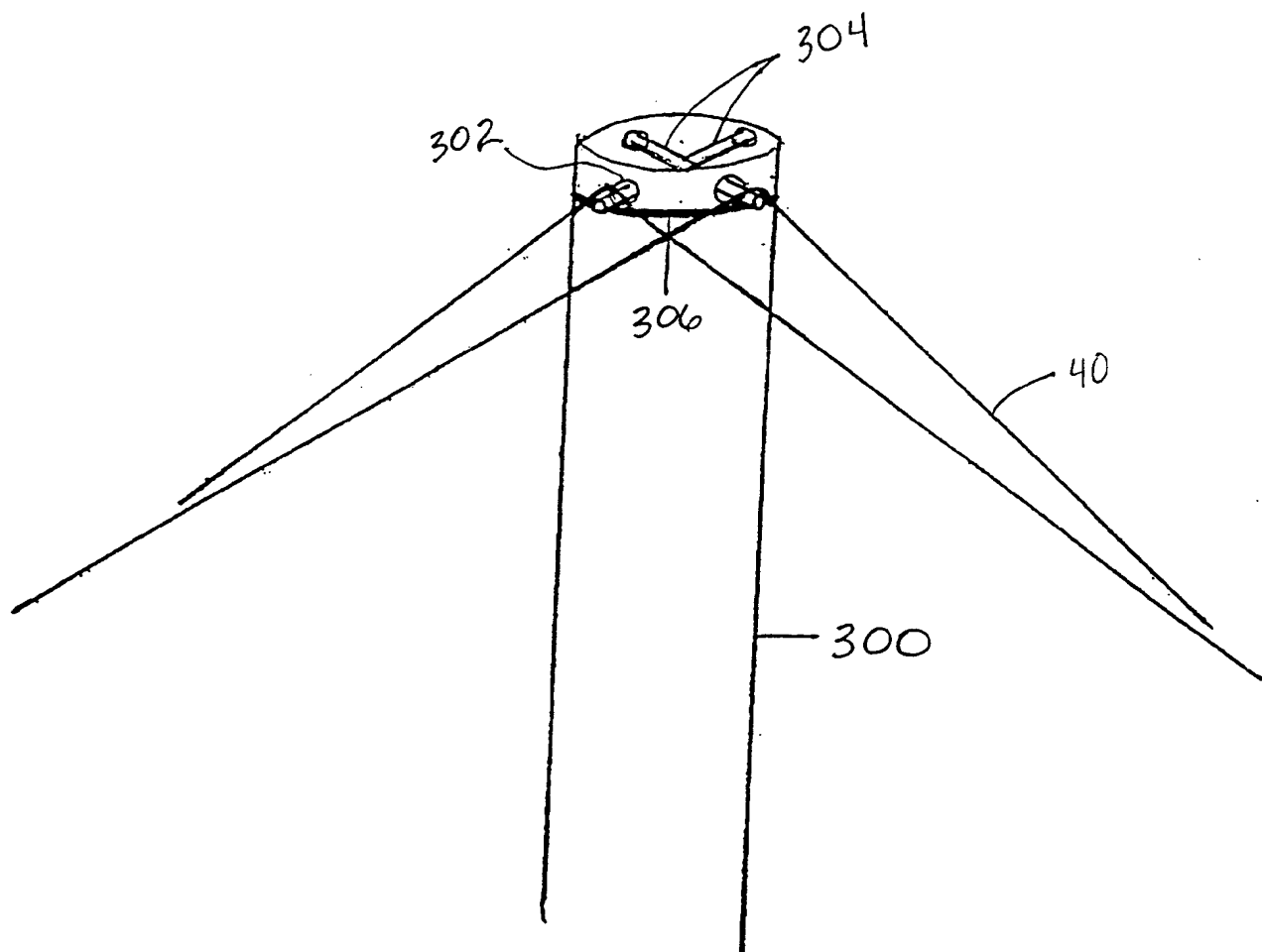


FIG. 12

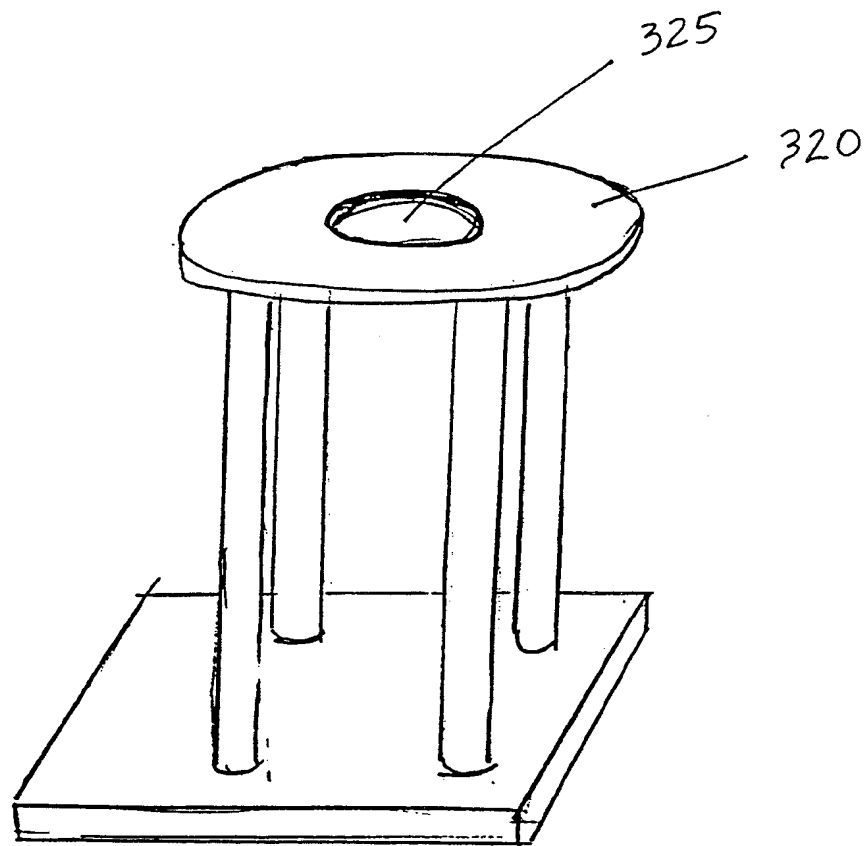
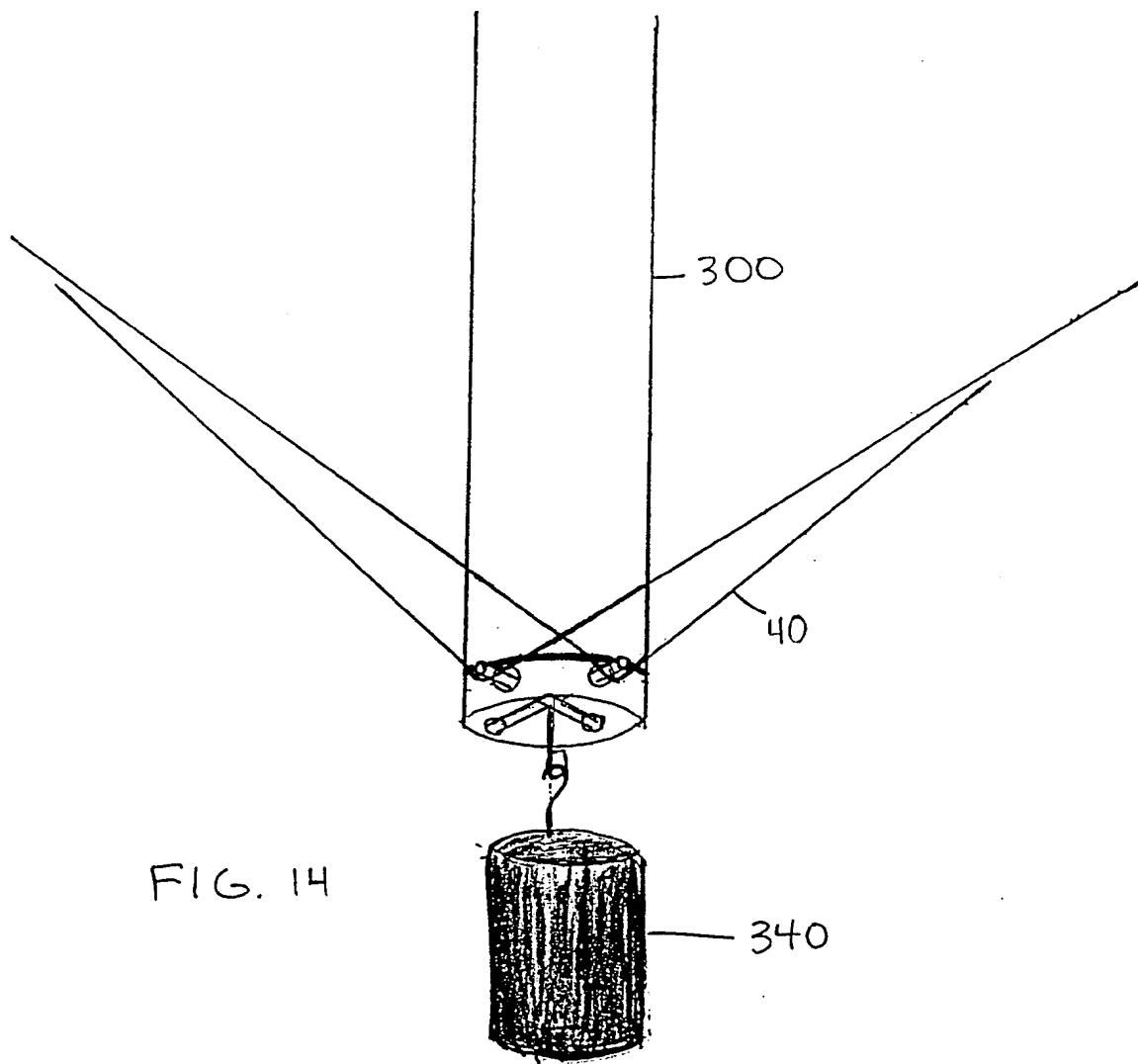


FIG. 13

330



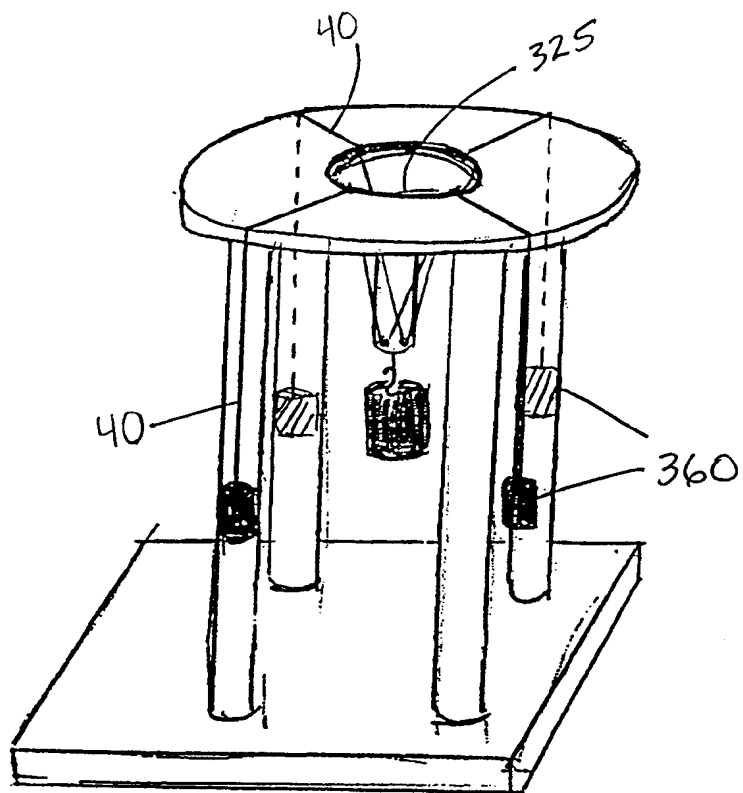


FIG. 15

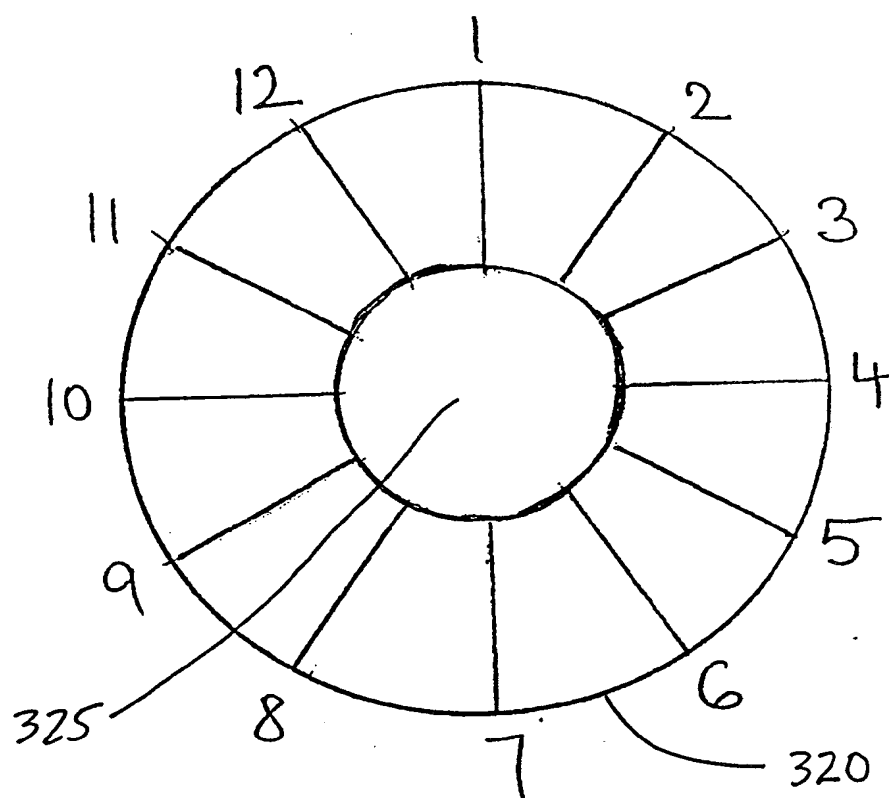
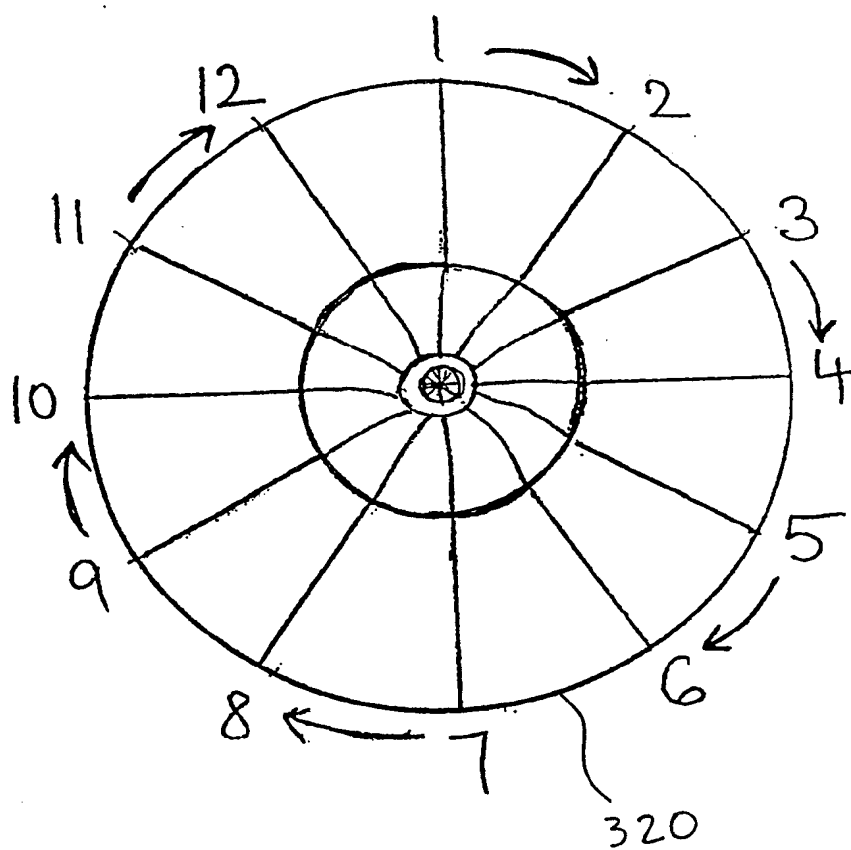
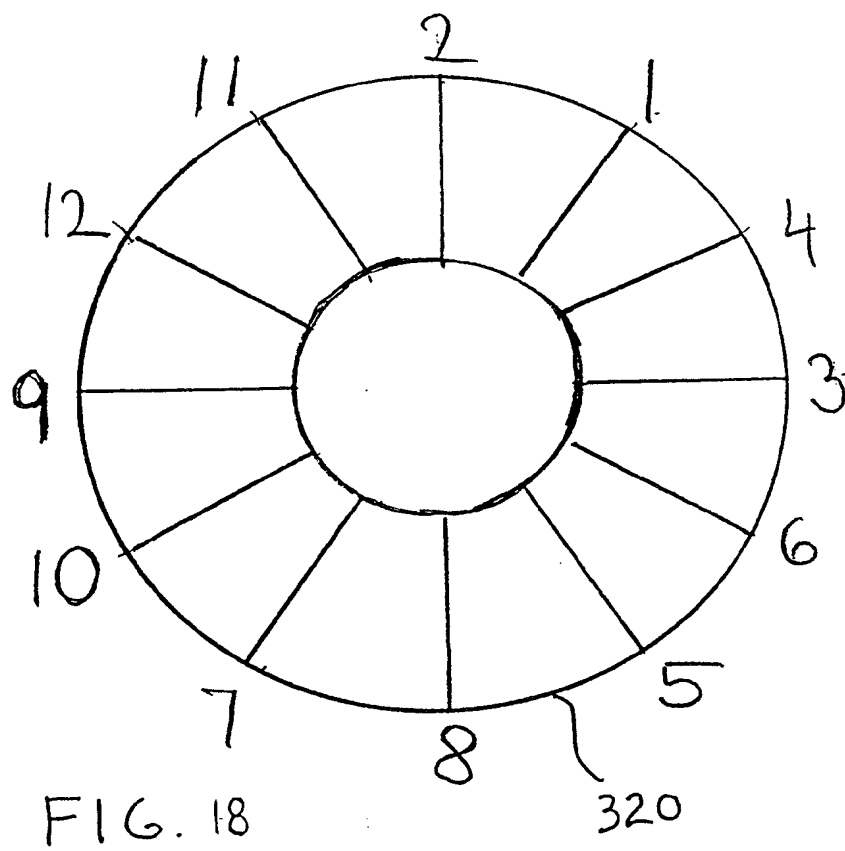


FIG. 16

FIG. 17





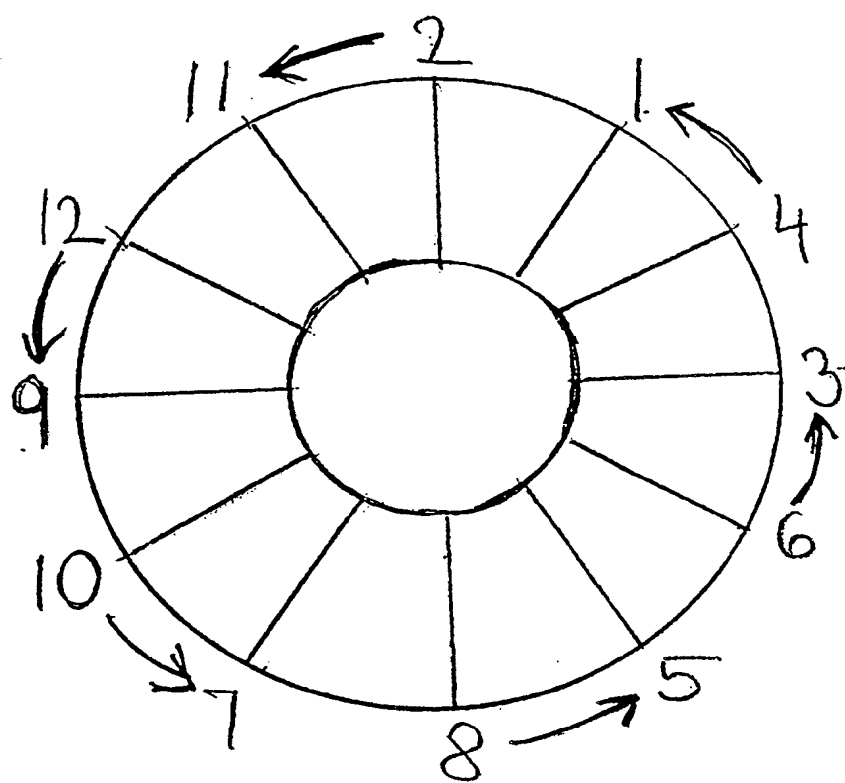
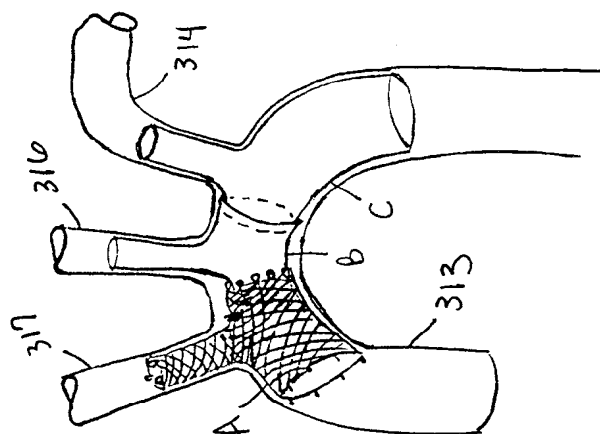
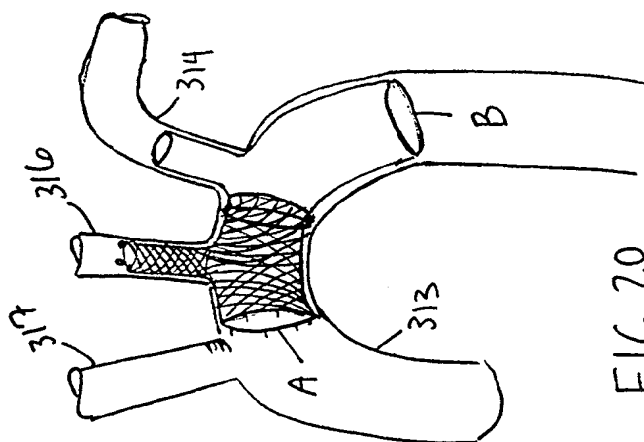


FIG. 19





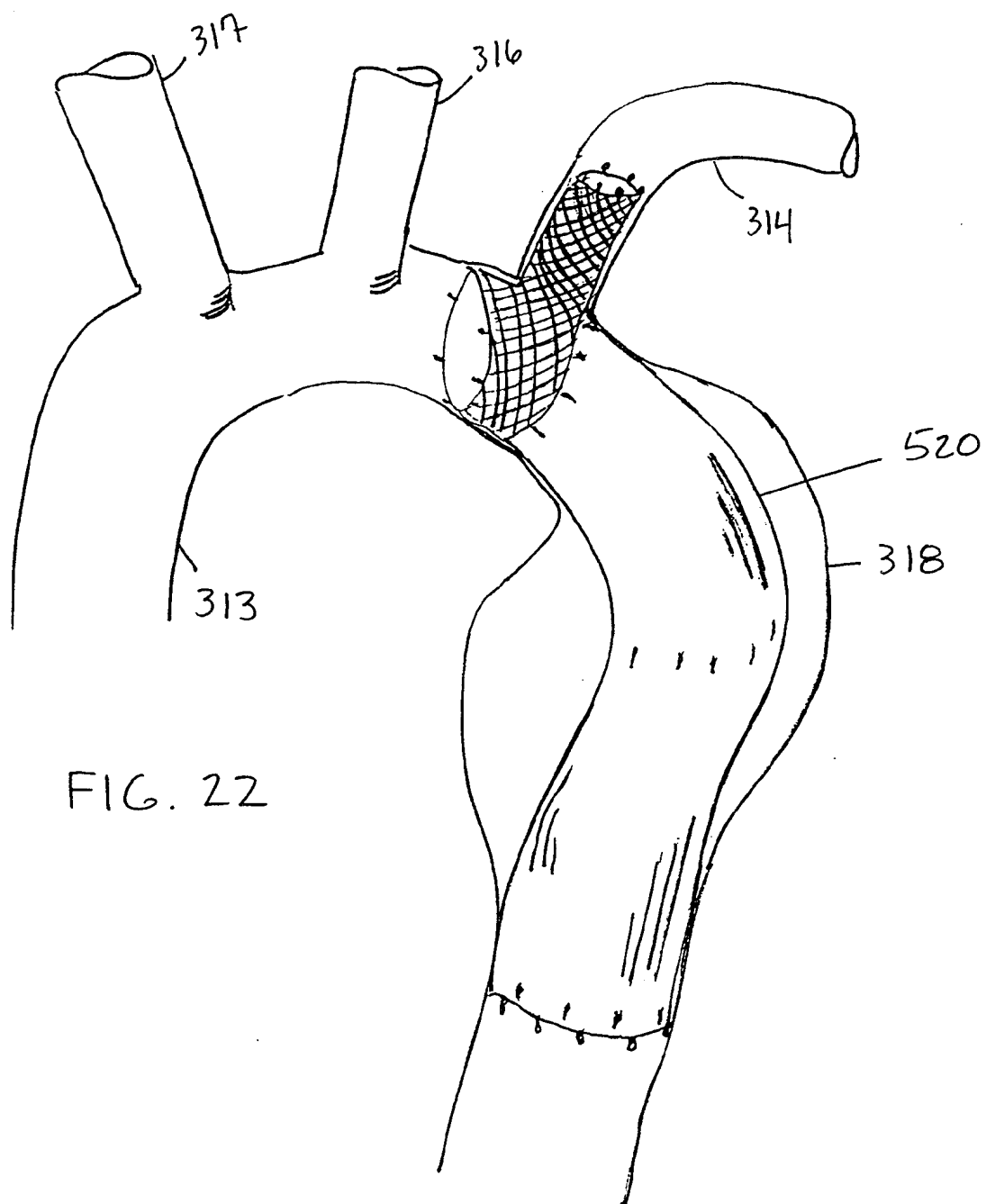


FIG. 22

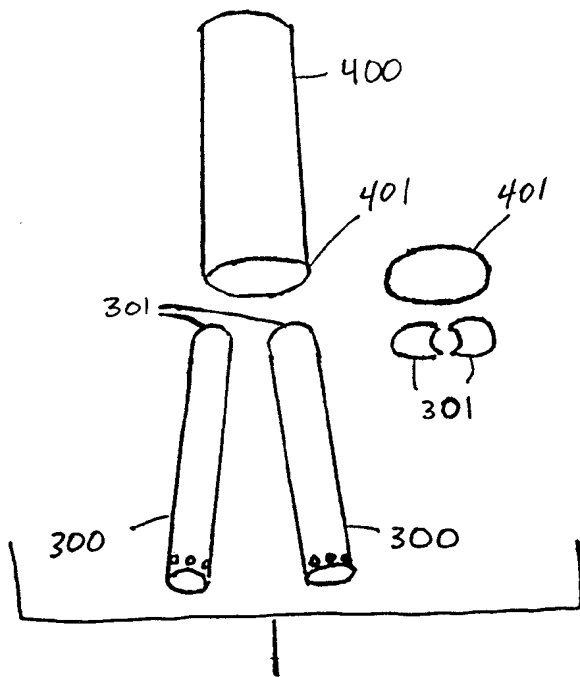


FIG. 23

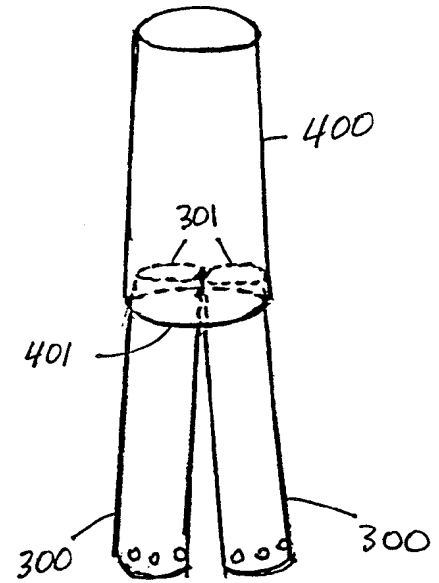


FIG. 24

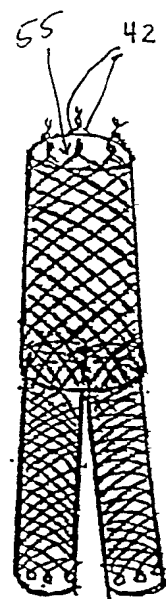
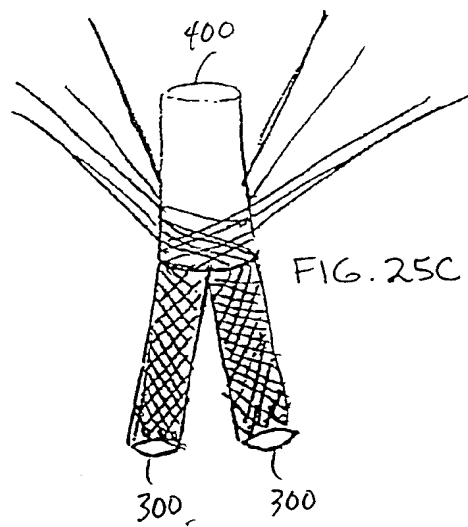
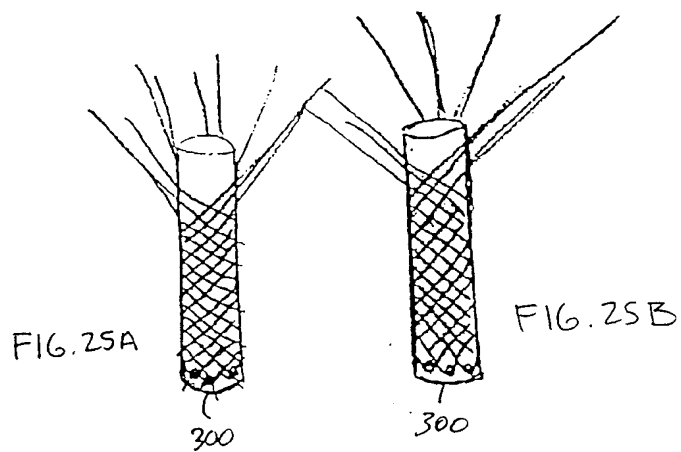


FIG. 26

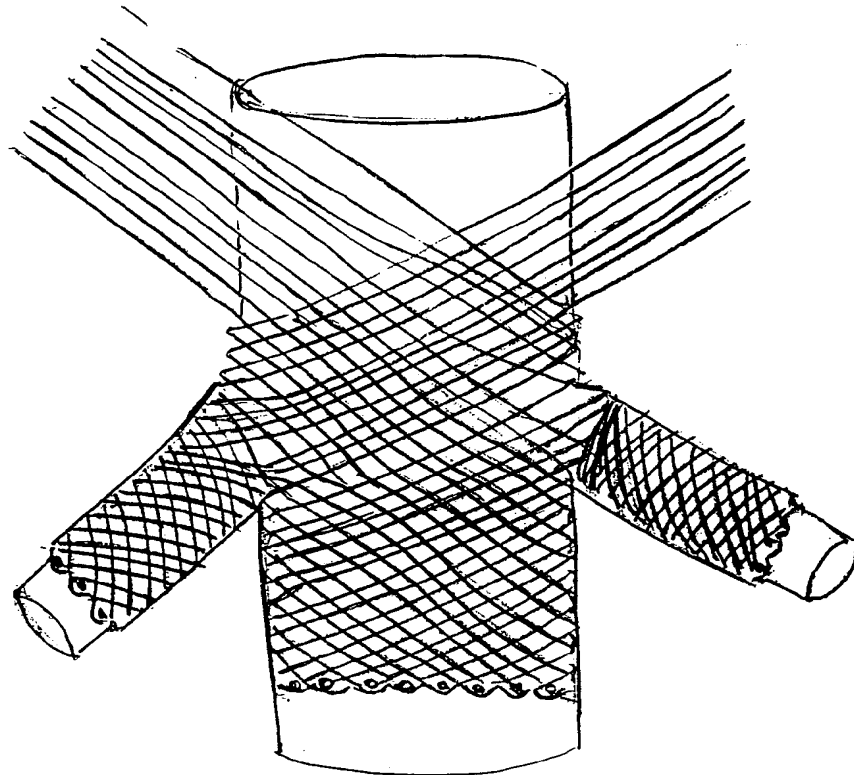


FIG. 27B

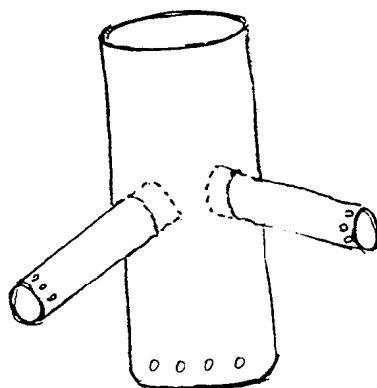


FIG. 27A

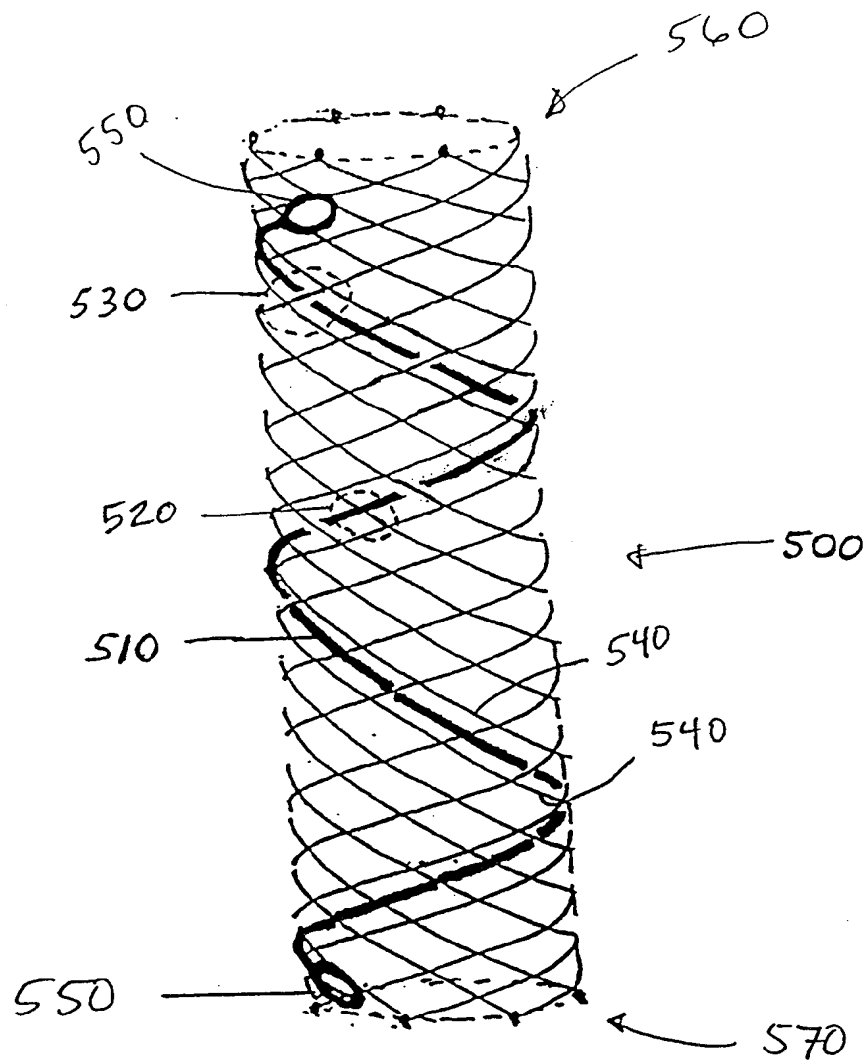


FIG. 28

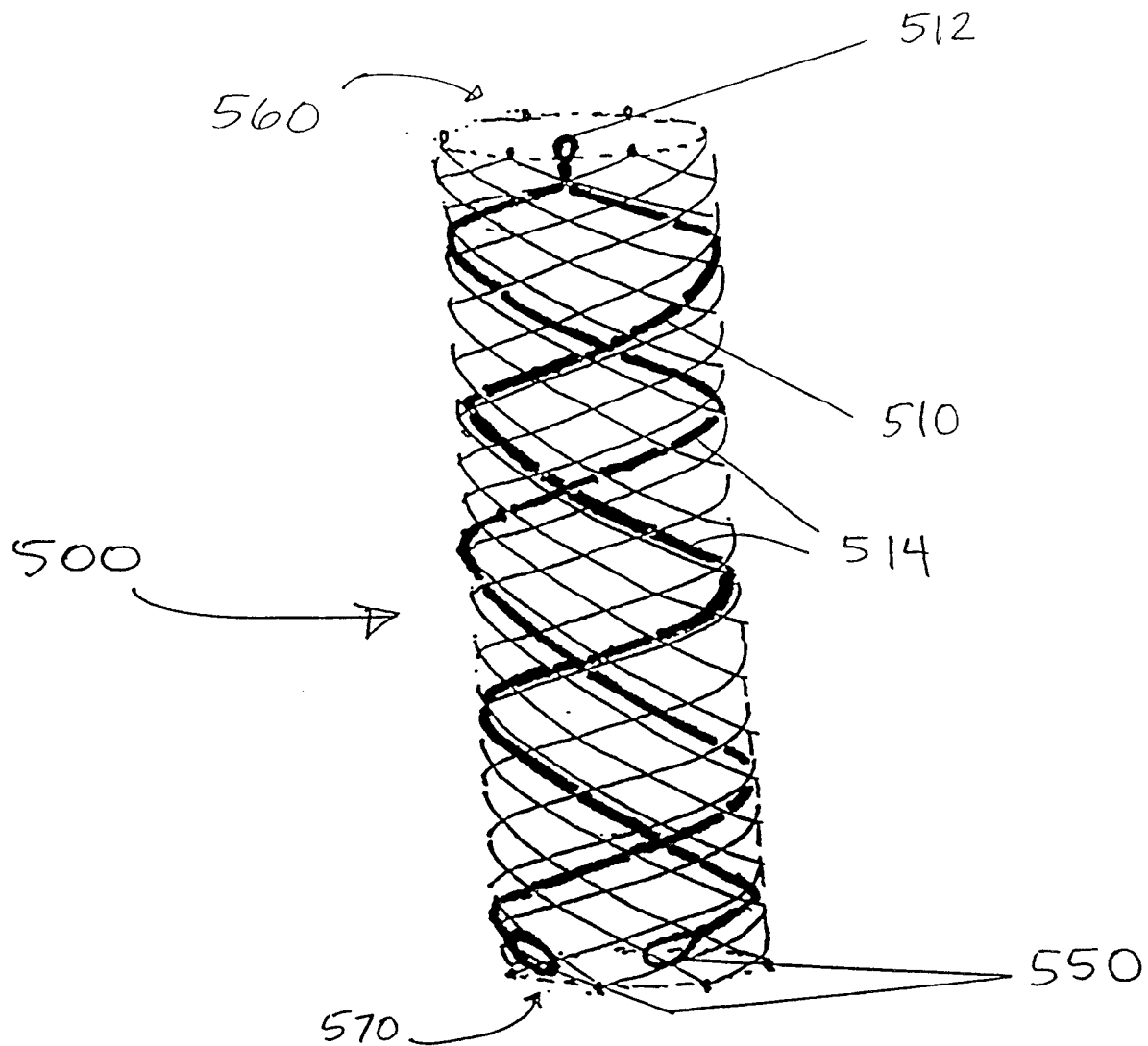


FIG. 29

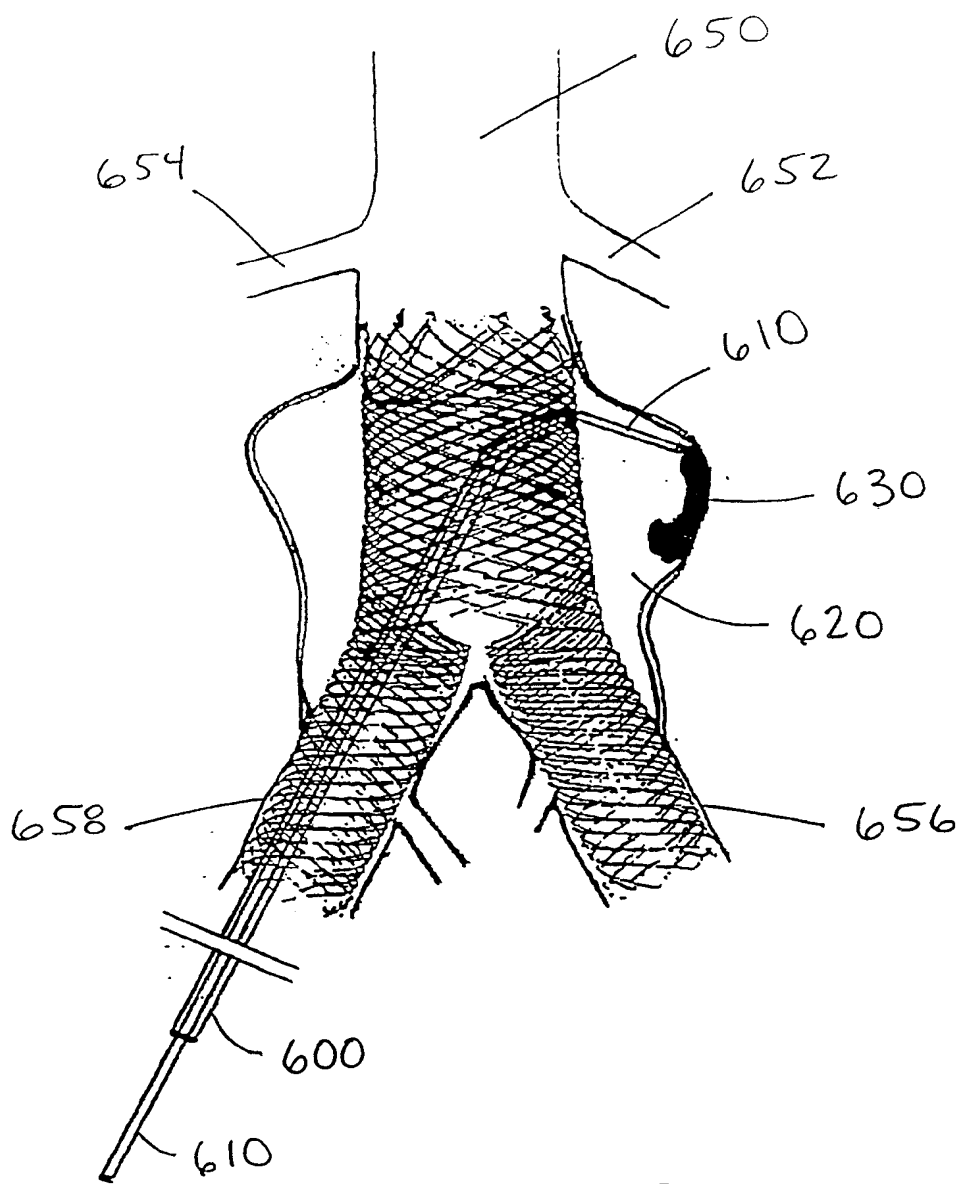


FIG. 30



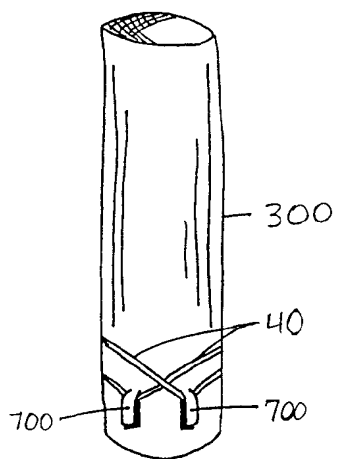


FIG. 31

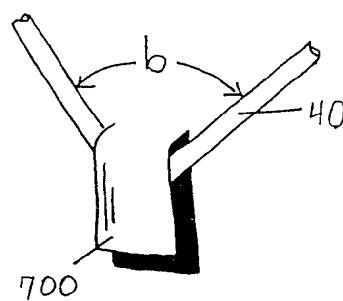


FIG. 32A

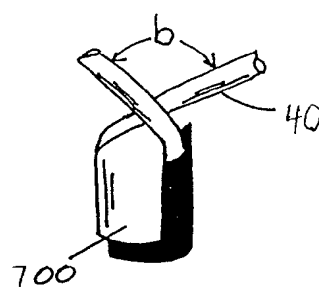


FIG. 32B

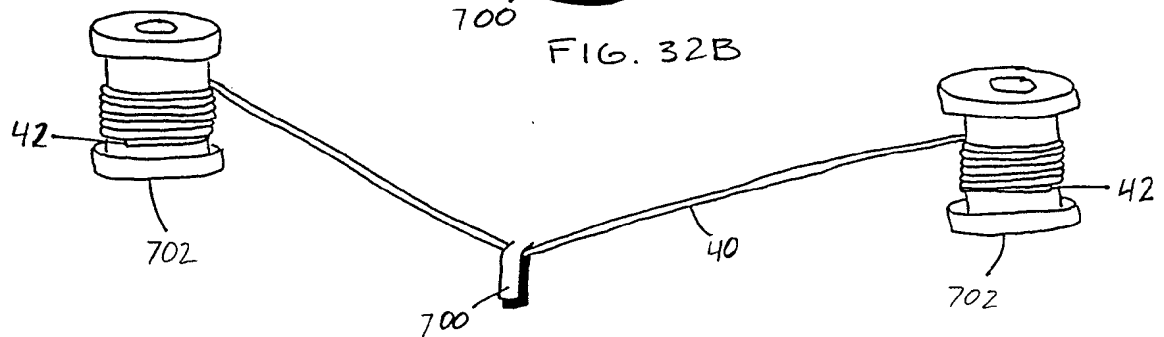


FIG. 33

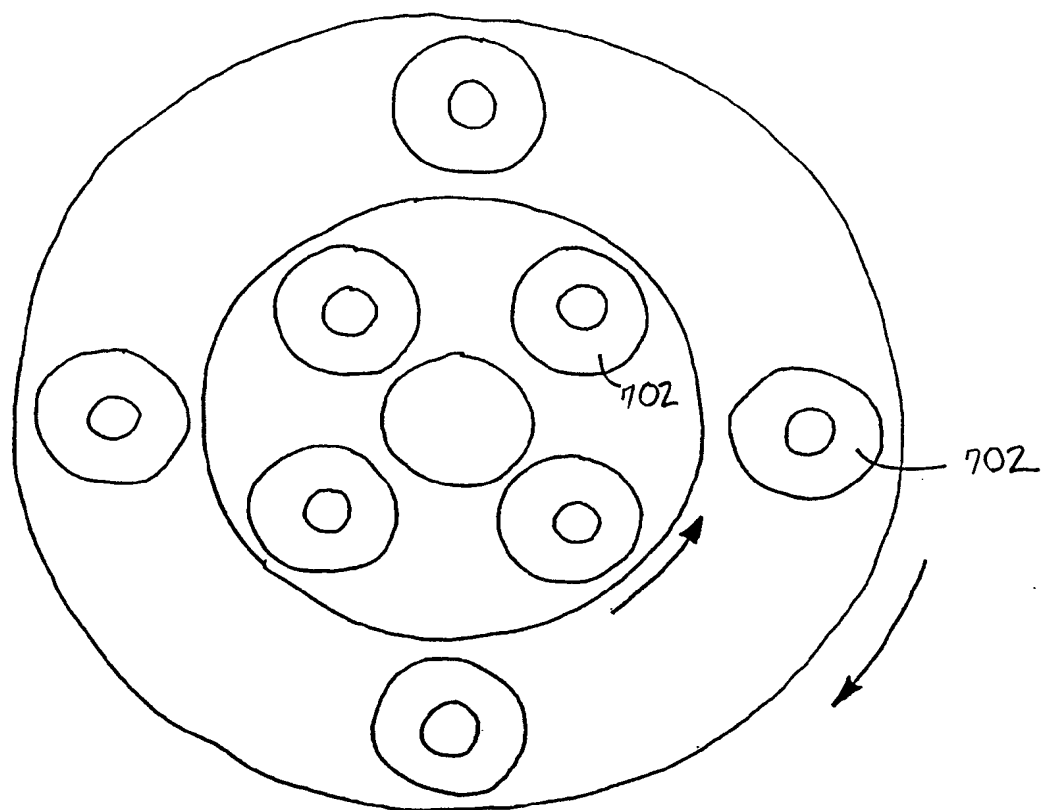
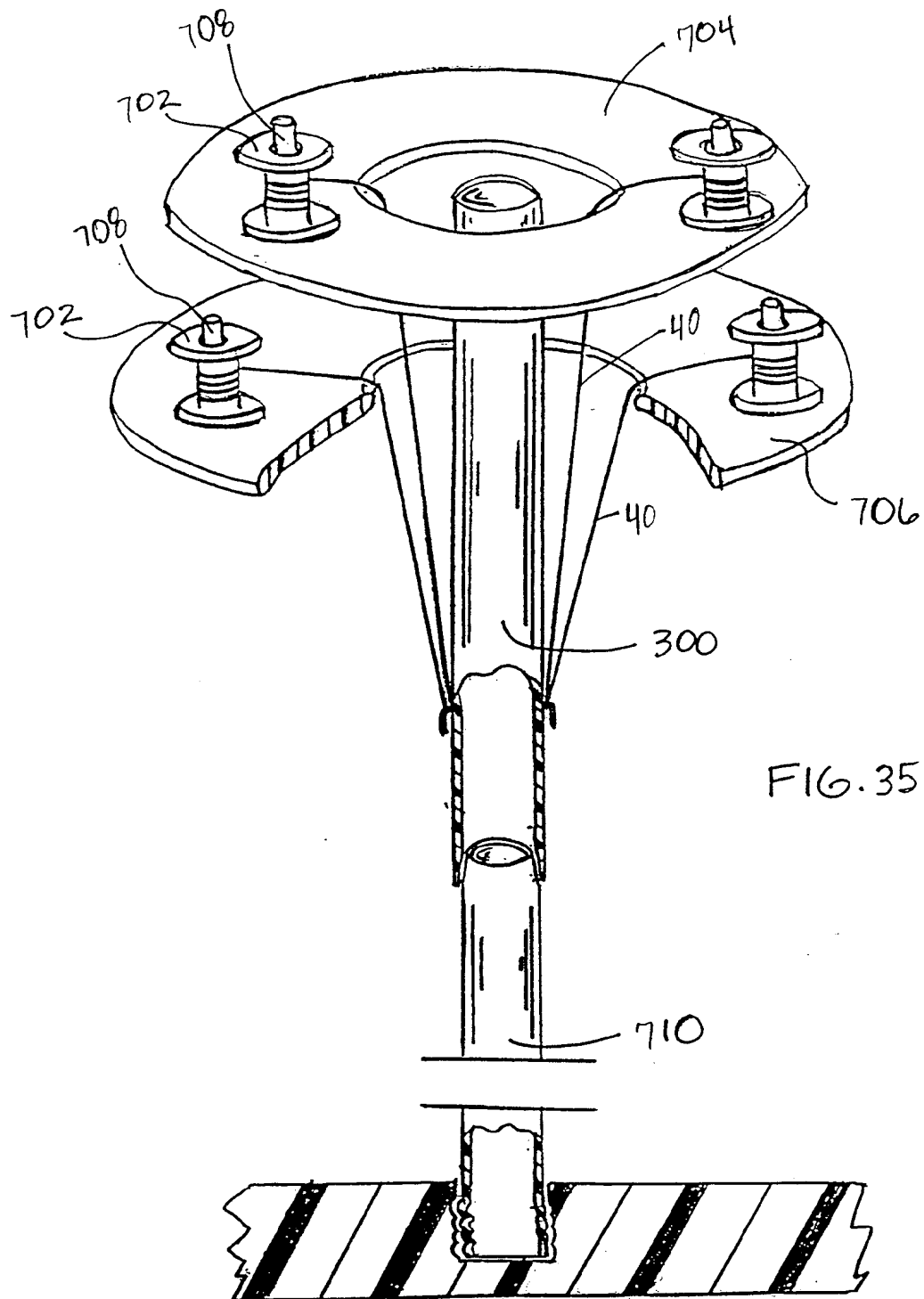


FIG. 34



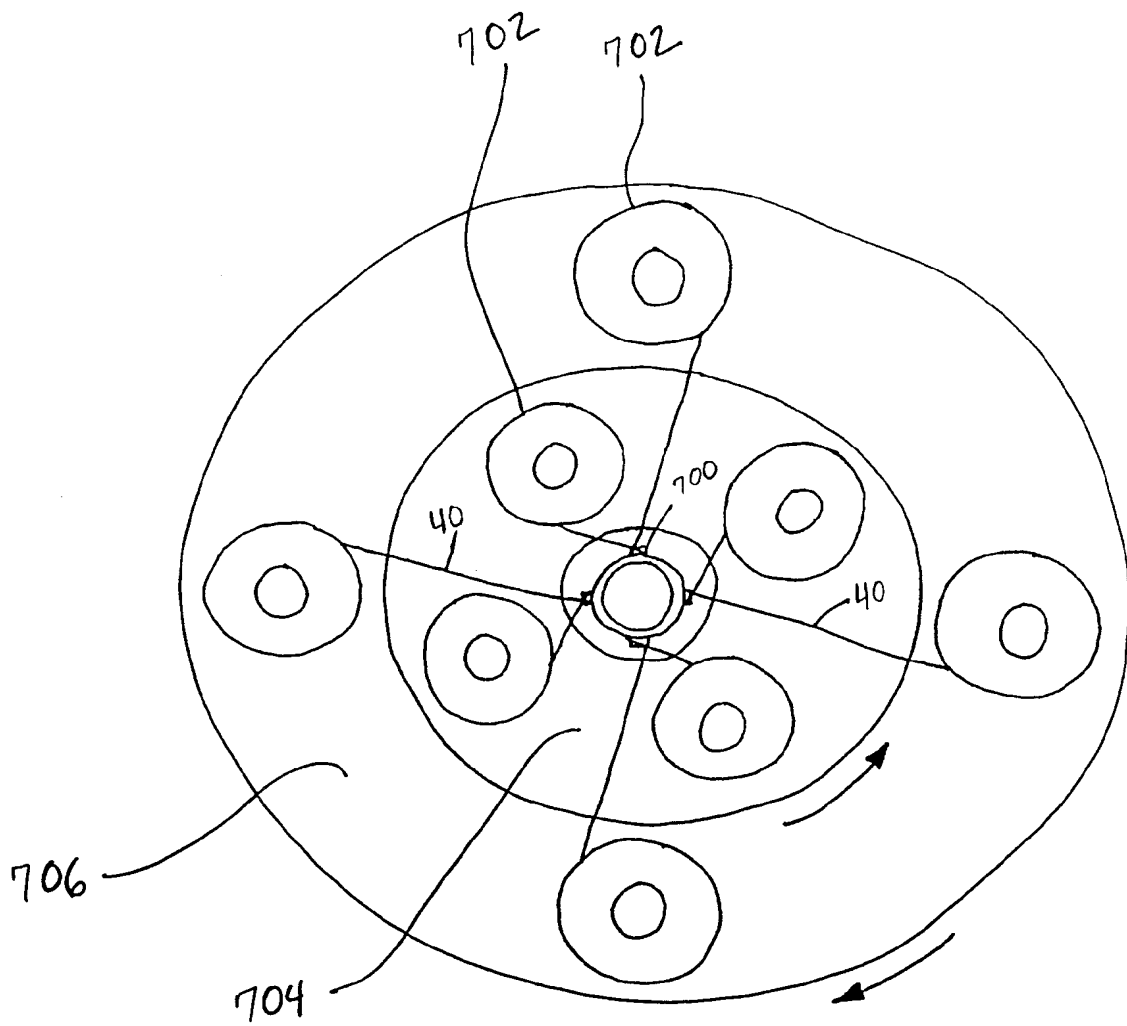


FIG. 36A

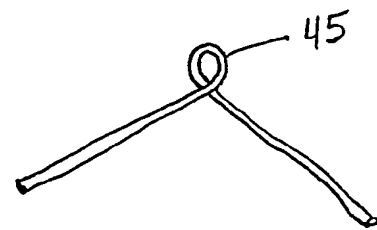
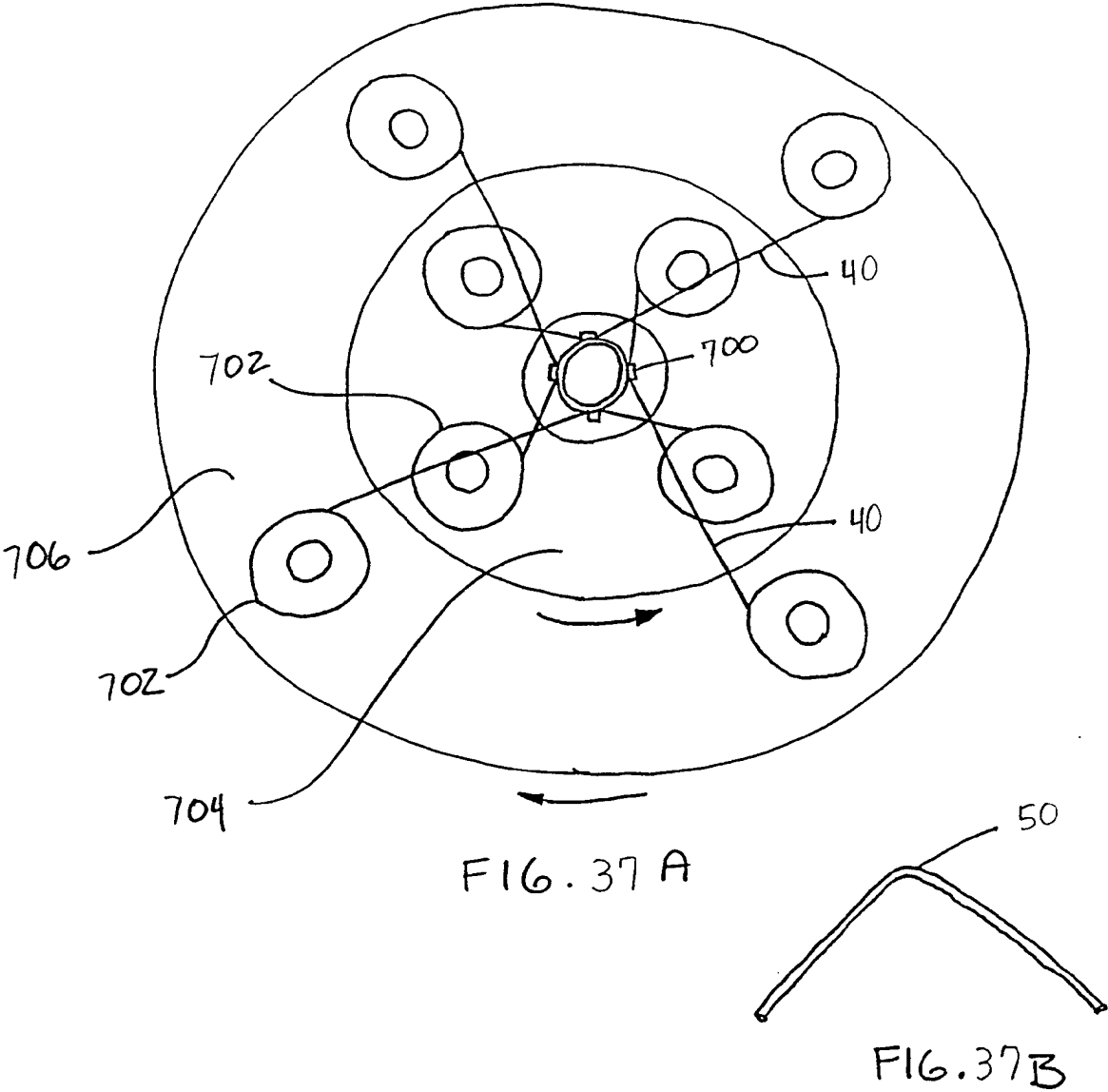


FIG. 36B



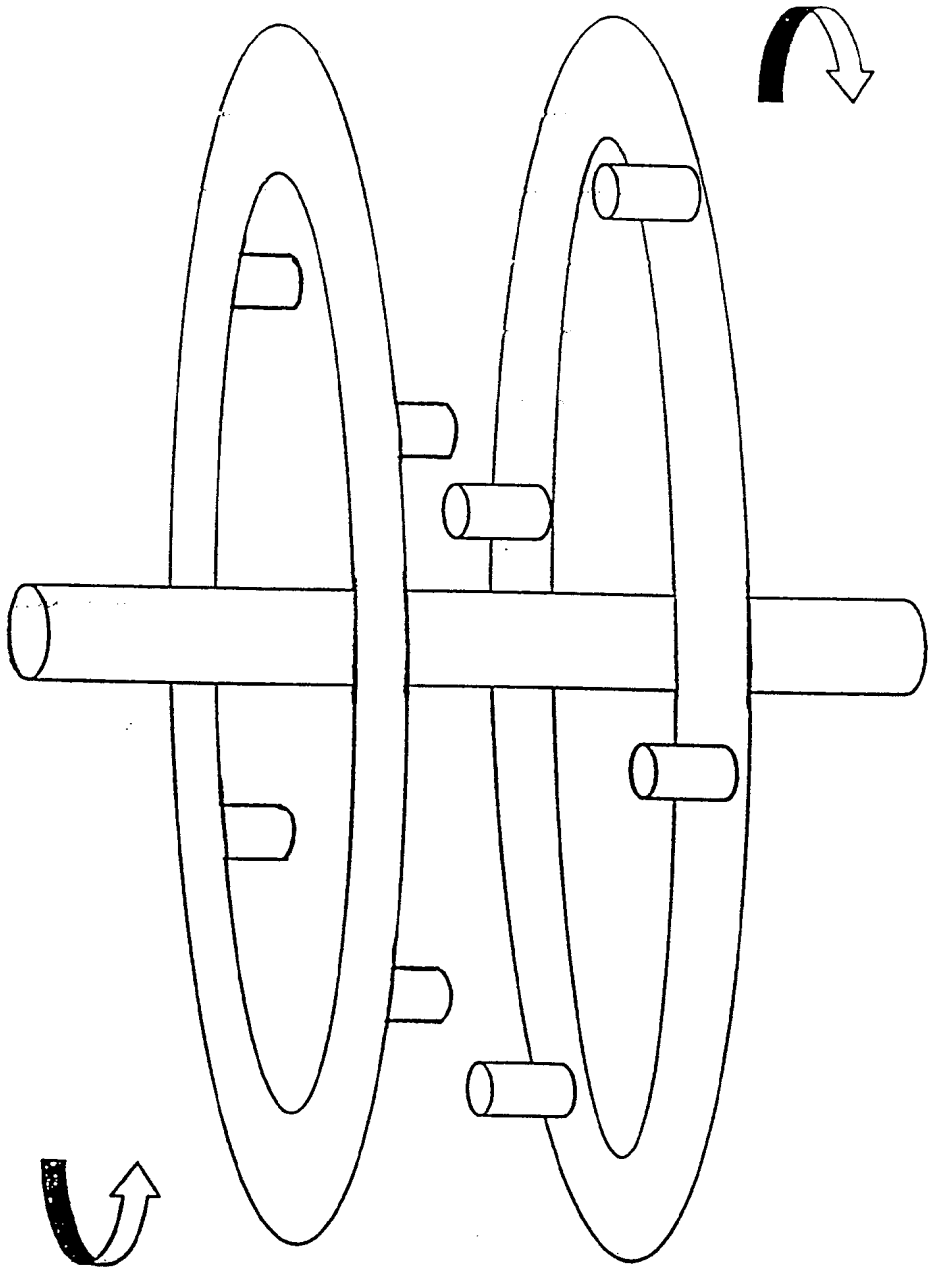


FIG. 38

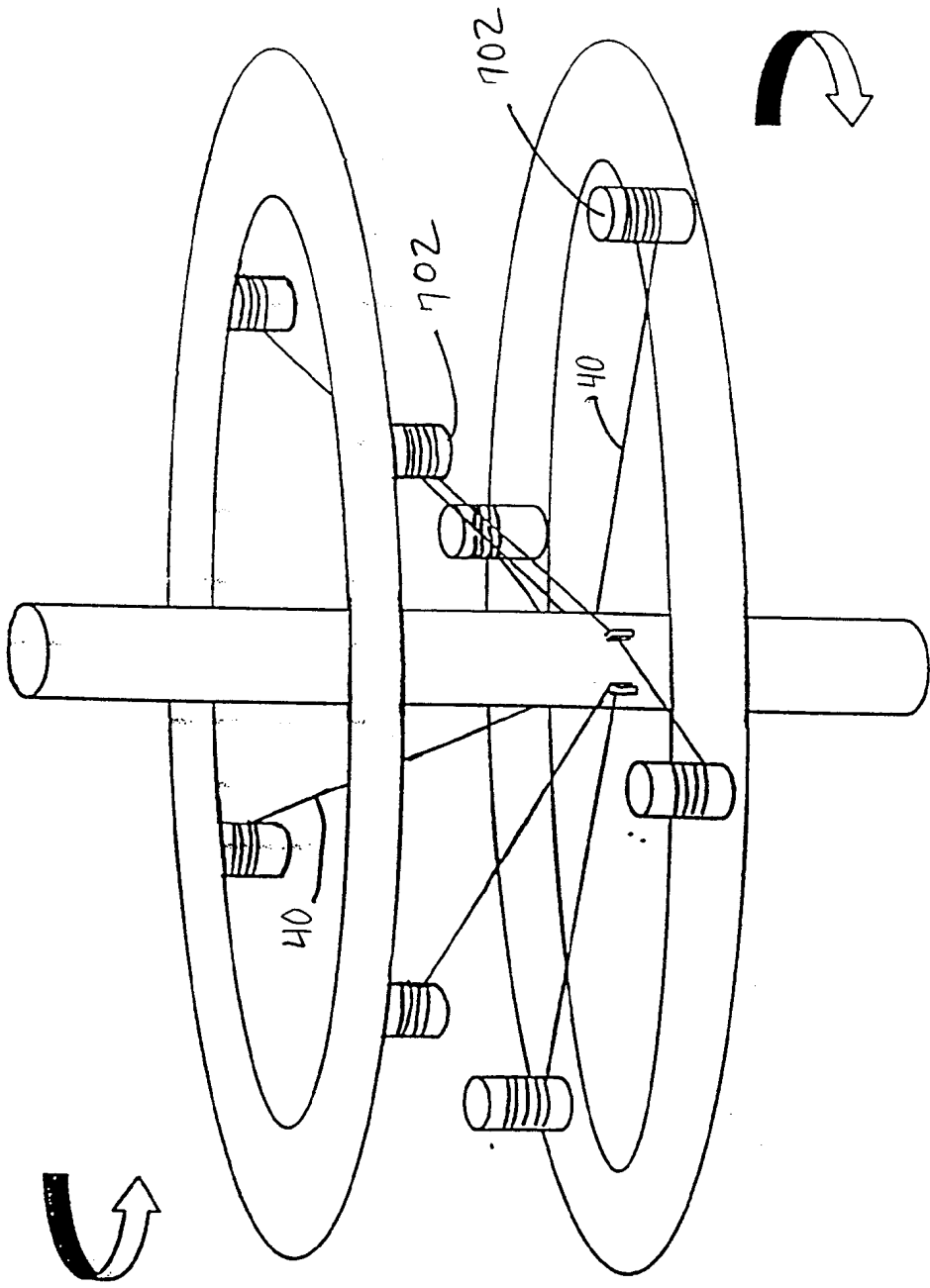
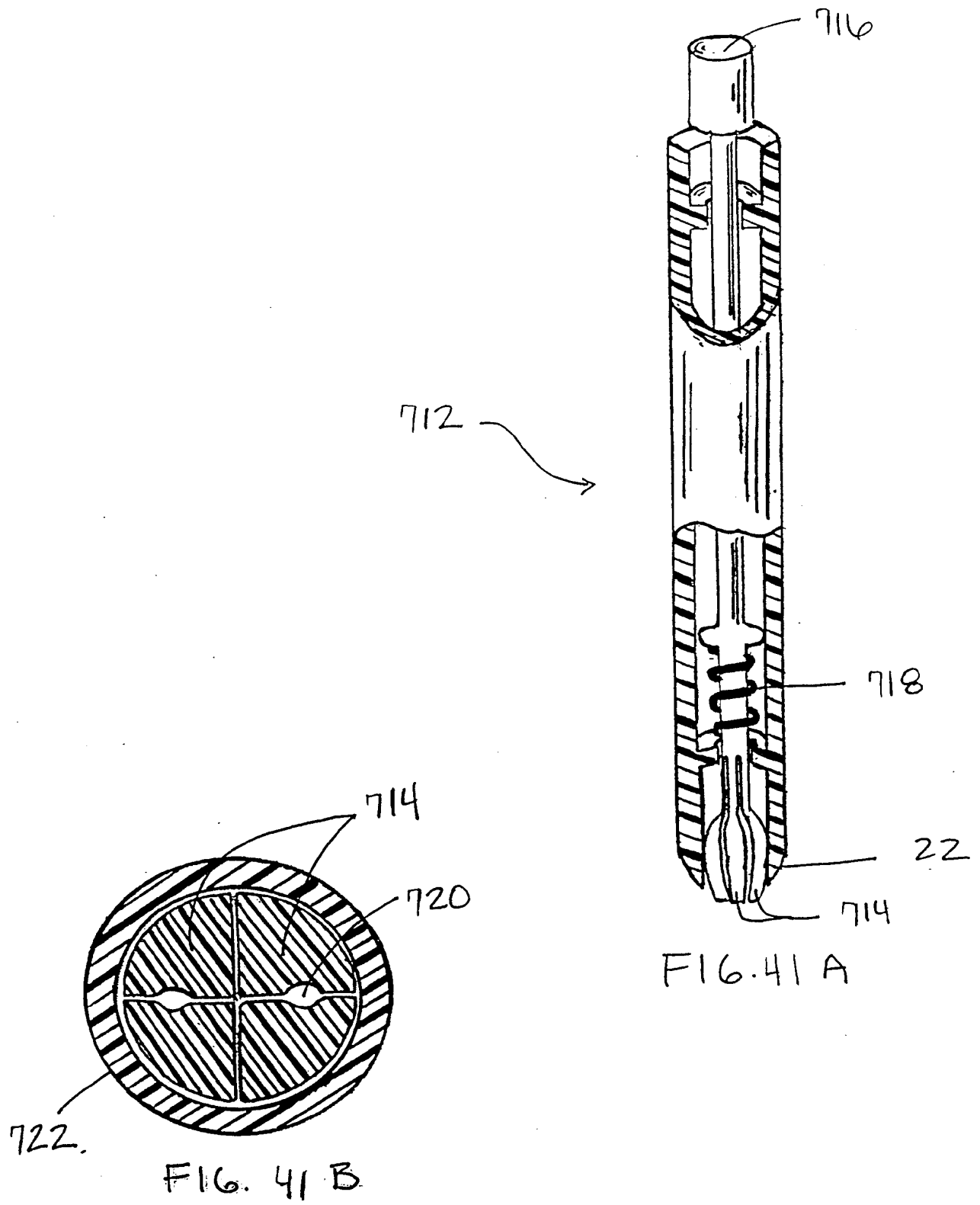


FIG. 39





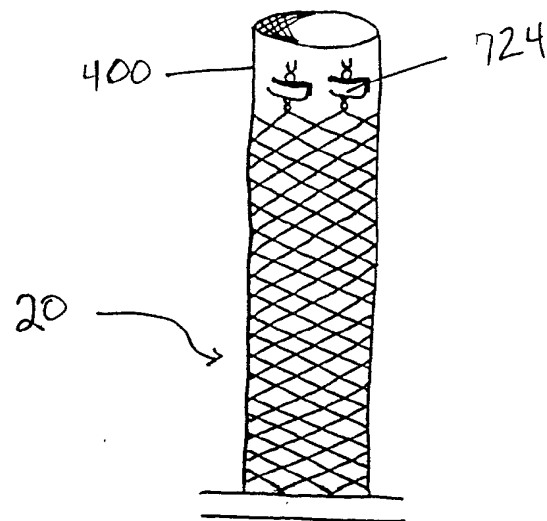


FIG. 42A

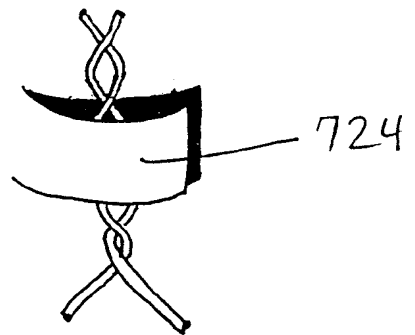


FIG. 42B

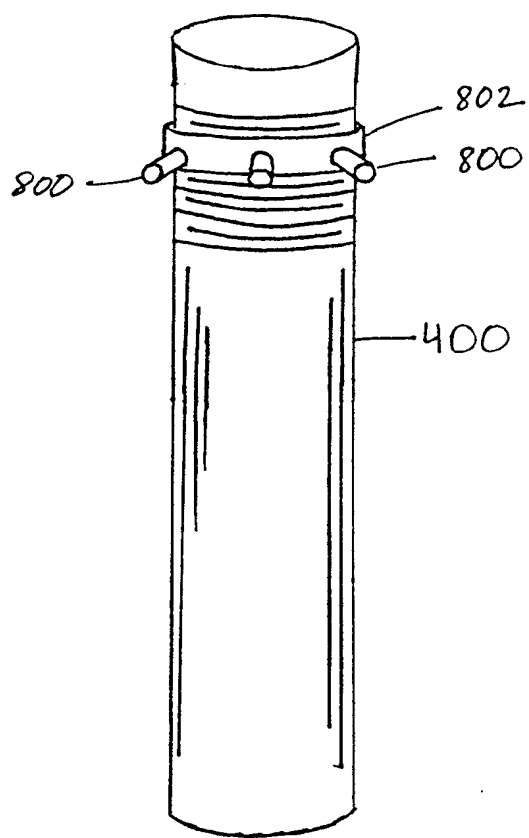


FIG. 43

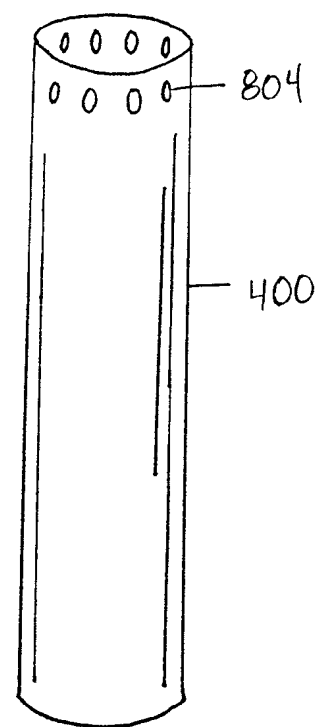


FIG. 44



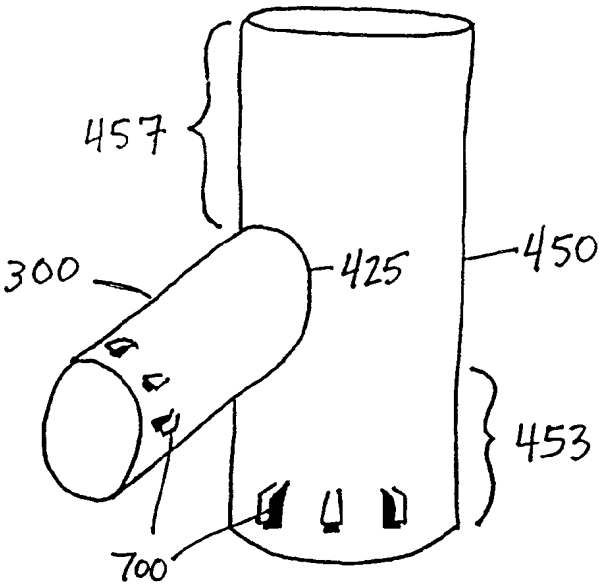


FIG. 46

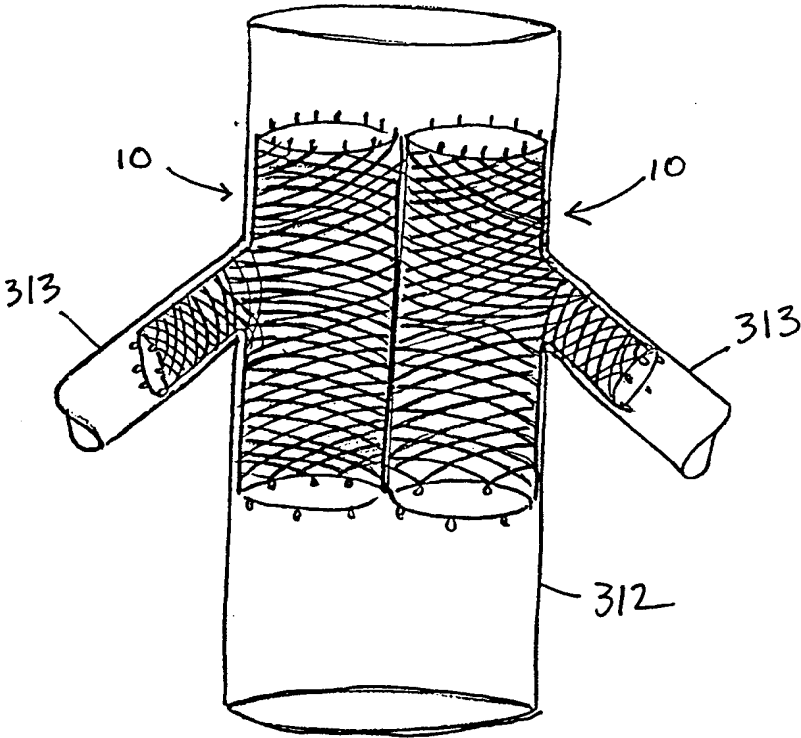


FIG. 40